

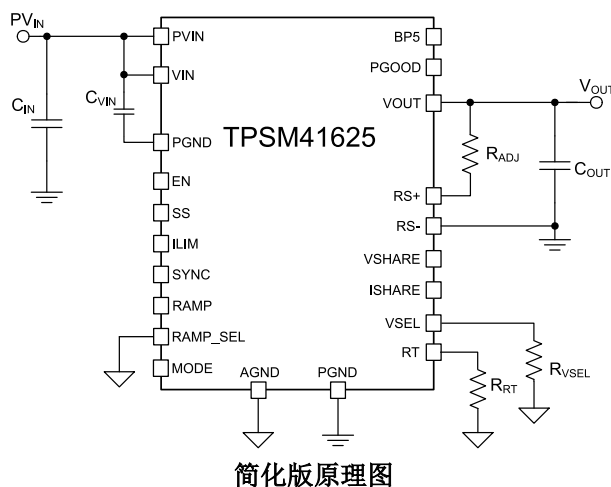
# 具有均流功能的 TPSM41625 4V 至 16V 输入、25A 直流/直流电源模块

## 1 特性

- 集成电感器电源解决方案
- 11mm × 16mm × 4.2mm QFN 封装
  - 所有引脚均分布在封装外围
- 输入电压范围：4V 至 16V
- 宽输出电压范围：0.6V 至 7.1V
- 可选内部基准（精度为 ±0.5%）
- 最多可堆叠两个器件
  - 并行输出，可获得更高的电流
  - 相位交错，可降低纹波
- 效率高达 97%
- 可调节固定开关频率（300kHz 至 1MHz）
- 支持与外部时钟同步
- 高级电流模式可提供超快负载阶跃响应
- 电源正常状态输出
- 符合 EN55011 辐射 EMI 限值
- 工作环境温度范围：-40°C 至 +105°C
- IC 工作结温范围：-40°C 至 +125°C
- 与以下器件引脚兼容：15A TPSM41615
- 使用 TPSM41625 并借助 WEBENCH® Power Designer 创建定制设计方案

## 2 应用

- 电信和无线基础设施
- 工业自动化测试设备
- 企业交换和存储应用
- 高密度分布式电源系统



## 3 说明

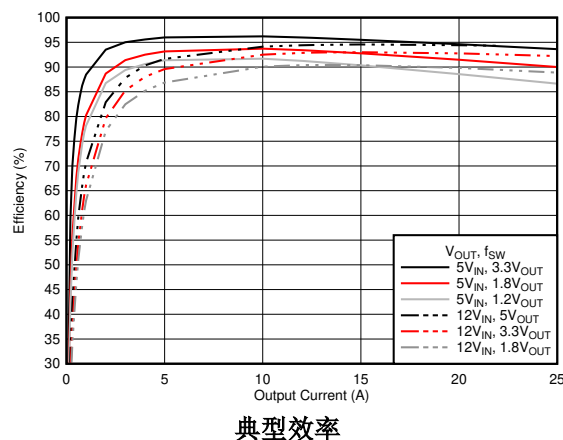
TPSM41625 电源模块是一款易于使用的集成式电源，它在紧凑的 QFN 封装内整合了一个带有功率 MOSFET 的直流/直流转换器、一个屏蔽式电感器和多个无源器件。该电源解决方案需要的外部组件很少，同时仍能够调整关键参数以满足特定的设计要求。需要更大电流的应用可通过并联两个 TPSM41625 器件而受益。

具有出色封装布局的 11mm × 16mm × 4.2mm、69 引脚 QFN 封装具有优异的功率耗散能力，可提高热性能。该封装的所有信号引脚均分布在外围，器件底部具有大散热垫。TPSM41625 通过电源正常状态信号、时钟同步、可编程 UVLO、软启动时序选择、预偏置启动以及过流和过热保护等众多功能提供灵活性，从而成为向各种器件和系统供电的出色产品。

### 器件信息

器件型号	封装 <sup>(1)</sup>	封装尺寸 (标称值)
TPSM41625	QFN (69)	11mm × 16mm

- (1) 如需了解所有可用封装，请参阅数据表末尾的可订购产品附录。



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## 4 Revision History

注：以前版本的页码可能与当前版本的页码不同

Changes from Revision * (September 2020) to Revision A (December 2020)	Page
• 将器件状态从“预告信息”更改为“量产数据” .....	1

## 5 Pin Configuration and Functions

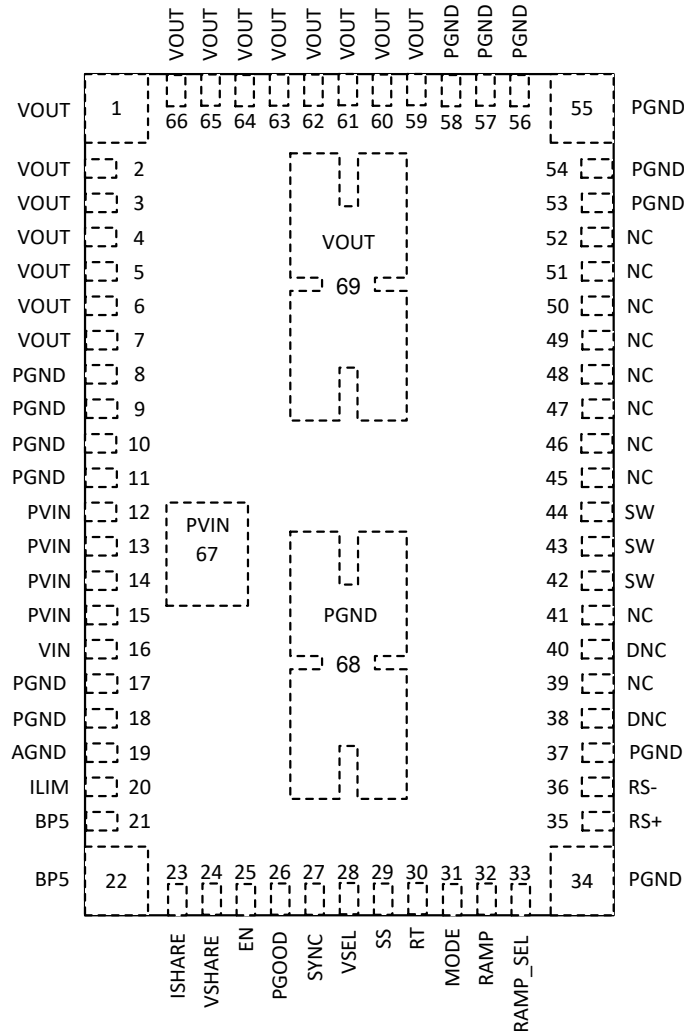


图 5-1. 69-Pin QFN MOV Package (Top View)

表 5-1. Pin Functions

PIN		TYPE (1)	DESCRIPTION
NAME	NO.		
AGND	19	G	Analog ground. Zero voltage reference for internal references and logic. Do not connect this pin to PGND; the connection is made internal to the device.
BP5	21, 22	O	Output of an internal 5-V regulator used for the controller driver stage within the module. This output can be used to connect a pullup resistor to the PGOOD pin. Leave these pins open if not used as a pullup for PGOOD.
DNC	38, 40	-	Do Not Connect. Do not connect these pins to AGND, PGND, another DNC pin, or any other voltage. These pins are connected to internal circuitry. Each pin must be soldered to an isolated pad.
EN	25	I	Enable pin. This pin turns the converter on when floated or opened. This pin is internally pulled up to the BP5 voltage when left open. The converter can be turned off by either driving it directly with a logic input or an open drain/collector device to connect this pin to AGND. An external voltage divider can be placed between this pin, AGND, and PVIN/VIN to create an external UVLO.
ILIM	20	I	Current limit setting pin. This pin sets the current limit threshold of the converter. Leave this pin open for the full current limit threshold. The current limit threshold can be lowered by connecting an appropriate resistor from this pin to AGND.
ISHARE	23	O	Current sharing pin. This pin is interconnected between modules for multi-phase configurations. Leave this pin open for single-phase configurations.

表 5-1. Pin Functions (continued)

PIN		TYPE (1)	DESCRIPTION
NAME	NO.		
MODE	31	I	Mode select pin. This pin is used to configure the module for single-phase or multi-phase operation. For single-phase operation, this pin is used to select the API and Body Brake functions. For multi-phase operation, this pin selects the primary/secondary and SYNC configurations.
NC	39, 41, 45-52	-	Not connected. These pins are not connected to any circuitry within the module. It is recommended that these pins be connected to the PGND plane on the application board to enhance shielding and thermal performance.
PGND	8-11, 17, 18, 34, 37, 53-58, 68	G	This is the return path for the power stage of the device. Connect these pins to the input supply return, load return, and bypass capacitors associated with the PVIN and VOUT pins.
PGOOD	26	O	Power Good pin. Open-drain output that asserts low if the remote sense feedback voltage is not within the specified PGOOD thresholds. When using this signal as an output, a pullup resistor is required. If unused, leave this pin open. The BP5 output can be used as the pullup voltage source.
PVIN	12-15, 67	I	Input switching voltage. Supplies voltage to the power switches of the converter. Connect these pins to the input supply. Connect bypass capacitors between these pins and PGND, close to the module.
RAMP	32	I	Internal ramp selection. This pin is used to select an internal ramp amplitude. See 表 7-3 for recommended settings. An internal 78.7-k $\Omega$ resistor is connected between RAMP and RAMP_SEL within the module. To select the internal resistor, it is recommended to leave this pin open and to connect the RAMP_SEL pin to AGND.
RAMP_SEL	33	I	Internal default ramp selection. This pin is used to select the internal default ramp selection for the control loop. An internal 78.7-k $\Omega$ resistor is connected between RAMP and RAMP_SEL pins. Connect the RAMP_SEL pin to AGND and leave the RAMP pin open to select the internal resistor.
RS+	35	I	Positive input to the internal differential remote sense amplifier. This pin is used for the feedback connection to VOUT. Connect this pin to the output voltage at the load. This connection can be made using a direct connection or an external upper feedback resistor, depending on the magnitude of VOUT and the VSEL selection. A 1-k $\Omega$ lower feedback resistor is connected across RS+ and RS - internal to the module. The RS+ connection is not needed for secondary devices in multi-phase configurations, and should be left open.
RS -	36	I	Negative input to the internal differential remote sense amplifier. This pin is used for the feedback connection to VOUT return. Connect this pin to the output voltage return at the load. A 1-k $\Omega$ lower feedback resistor is connected across RS+ and RS - internal to the module. The RS- connection is not needed for secondary devices in multi-phase configurations, and should be left open.
RT	30	I	Switching frequency setting pin. This analog pin is used to set the switching frequency of the converter by placing an external resistor from this pin to AGND. This pin also selects the phase interleaving of the module when used in multi-phase configurations.
SS	29	I	Soft-start selection pin. This pin is used to select the soft-start time. Ten possible selections are available by connecting an appropriate resistor from this pin to AGND. The selections range from 0.5 ms to 32 ms.
SW	42-44	O	Switch node. These pins are connected to the internal output inductor and switching MOSFETs. Connect these pins together using a small copper island beneath the device. Keep this copper island to a minimum to prevent issues with noise and EMI.
SYNC	27	I	Frequency synchronization pin. MODE can be used to configure this pin as a sync input or a sync output for external clock and multi-phase primary/secondary configurations.
VIN	16	I	Input bias voltage. Supplies the control circuitry of the power converter. Connect a 1- $\mu$ F bypass capacitor from this pin to PGND (pins 17 and 18) in close proximity to the module. For split rail applications, connect this pin to an input bias supply. For strapped rail applications, connect this pin to PVIN through a 0 $\Omega$ to 10 $\Omega$ resistor.
VOUT	1-7, 59-66, 69	O	Output voltage. These pins are connected to the internal output inductor. Connect these pins to the output load and connect external bypass capacitors between these pins and PGND in close proximity to the module.
VSEL	28	I	Internal reference voltage selection. This pin is used to select the desired internal reference voltage. Ten possible selections are available by connecting an appropriate resistor from this pin to AGND. The selections range from 0.6 V to 1.1 V.
VSHARE	24	O	Voltage sharing pin. This pin is interconnected between modules for multi-phase configurations. Leave this pin open for single-phase configurations.

(1) G = Ground, I = Input, O = Output, - = Not Connected

## 6 Specifications

### 6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

		MIN	MAX	UNIT	
Input voltage	PVIN	- 0.3	17	V	
	PVIN to SW	DC	- 0.3	25	V
		<10 ns	- 5	25	V
	VIN	- 0.3	18	V	
	VSEL, SS, MODE, RT, SYNC, EN, ISHARE, ILIM	- 0.3	7	V	
	RS+	- 0.3	3.6	V	
	RS-	- 0.3	0.3	V	
	AGND, PGND	- 0.3	0.3	V	
SW	DC	- 0.3	20	V	
	<10 ns	- 5.0	20	V	
Output voltage	VOUT	- 0.3	8	V	
	BP5, PGOOD, RAMP	- 0.3	7	V	
	VSHARE	- 0.3	3.6	V	
Mechanical shock	Mil-STD-883H, Method 2002.5, 1 msec, 1/2 sine, mounted		500	G	
Mechanical vibration	Mil-STD-883H, Method 2007.3, 20 to 2000 Hz		20	G	
Operating IC junction temperature, T <sub>J</sub> <sup>(2)</sup>		- 40	125	°C	
Operating ambient temperature, T <sub>A</sub> <sup>(2)</sup>		- 40	105	°C	
Storage temperature, T <sub>stg</sub>		- 40	150	°C	

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) The ambient temperature is the air temperature of the surrounding environment. The junction temperature is the temperature of the internal power IC when the device is powered. Operating below the maximum ambient temperature, as shown in the safe operating area (SOA) curves in the typical characteristics sections, ensures that the maximum junction temperature of any component inside the module is never exceeded.

### 6.2 ESD Ratings

		VALUE	UNIT	
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	500	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	1000	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Input voltage	$PV_{IN}, V_{IN}$	4	16	V
	VSEL, SS, MODE, RT, SYNC, EN, ISHARE, ILIM	- 0.1	5.5	V
	RS+	- 0.1	1.7	V
	RS-	- 0.1	0.1	V
	AGND, PGND	- 0.1	0.1	V
Output voltage	$V_{OUT}$	0.6	7.1	V
	BP5, PGOOD, RAMP	- 0.3	5.5	V
	VSHARE	- 0.3	3.3	V
Output current	$I_{OUT}$	0	25	A
Operating IC junction temperature, $T_J$		- 40	125	°C
Operating ambient temperature, $T_A$		- 40	105	°C

### 6.4 Thermal Information

THERMAL METRIC (1)		TPSM41625	UNIT
		MOV (QFN)	
		69 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance (2)	13.8	°C/W
$\psi_{JT}$	Junction-to-top characterization parameter (3)	4.4	°C/W
$\psi_{JB}$	Junction-to-board characterization parameter (4)	9.8	°C/W
$T_{SHDN}$	Thermal Shutdown Temperature	165	°C
	Thermal Shutdown Hysteresis	30	°C

- (1) For more information about thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
- (2) The junction-to-ambient thermal resistance,  $R_{\theta JA}$ , applies to devices soldered directly to a 90 mm × 90 mm, 6-layer PCB with 2 oz. copper and natural convection cooling. Additional airflow reduces  $R_{\theta JA}$ .
- (3) The junction-to-top characterization parameter,  $\psi_{JT}$ , estimates the junction temperature,  $T_J$ , of a device in a real system, using a procedure described in JEESD51-2A (section 6 and 7).  $T_J = \psi_{JT} \times P_{dis} + T_T$ ; where  $P_{dis}$  is the power dissipated in the device and  $T_T$  is the temperature of the top of the device.
- (4) The junction-to-board characterization parameter,  $\psi_{JB}$ , estimates the junction temperature,  $T_J$ , of a device in a real system, using a procedure described in JEESD51-2A (sections 6 and 7).  $T_J = \psi_{JB} \times P_{dis} + T_B$ ; where  $P_{dis}$  is the power dissipated in the device and  $T_B$  is the temperature of the board 1mm from the device.

## 6.5 Electrical Characteristics

Limits apply over  $T_A = -40^\circ\text{C}$  to  $+105^\circ\text{C}$ ,  $PV_{IN} = 12\text{ V}$ ,  $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.8\text{ V}$ ,  $V_{REF} = 1.0\text{ V}$ ,  $F_{SW} = 500\text{ kHz}$ ,  $I_{OUT} = 25\text{ A}$ , (unless otherwise noted); Minimum and maximum limits are specified through production test or by design. Typical values represent the most likely parametric norm and are provided for reference only.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INPUT SUPPLY</b>						
$PV_{IN}$	Input switching voltage		4		16	V
$V_{IN}$	Input bias voltage		4		16	V
$UVLO$	$PV_{IN}$ undervoltage lockout	$PV_{IN}$ increasing, $I_{OUT} = 0\text{ A}$		3.2		V
		$PV_{IN}$ decreasing, $I_{OUT} = 2.5\text{ A}$		3.0		V
	$V_{IN}$ undervoltage lockout	$V_{IN}$ increasing, $I_{OUT} = 0\text{ A}$		3.8		V
		$V_{IN}$ decreasing, $I_{OUT} = 2.5\text{ A}$		3.6		V
$I_{VIN}$	$V_{IN}$ bias current <sup>(1)</sup>	$V_{RS+} = 1.2\text{ V}$ , $I_{OUT} = 0\text{ A}$ , EN = OPEN, $T_A = 25^\circ\text{C}$		4.3		mA
$I_{VIN-STBY}$	$V_{IN}$ standby current	$I_{OUT} = 0\text{ A}$ , EN = 0 V, $T_A = 25^\circ\text{C}$		4.3		mA
<b>OUTPUT VOLTAGE</b>						
$V_{OUT}$	Output voltage adjust	RS+ connected directly to $V_{OUT}$	0.6		1.1	V
		RS+ connected to $V_{OUT}$ feedback divider			7.1 <sup>(1) (2)</sup>	V
	$V_{OUT}$ accuracy	$0.6\text{ V} \leq V_{REF} \leq 1.1\text{ V}$ , $V_{RS+} = V_{OUT}$ , $I_{OUT} = 0\text{ A}$ , $-40^\circ\text{C} \leq T_J = T_A \leq 125^\circ\text{C}$ <sup>(1)</sup>	-1.0		1.0	%
	Line regulation	Over $PV_{IN}$ range, $PV_{IN} = V_{IN}$ , $I_{OUT} = 0\text{ A}$ , $T_A = 25^\circ\text{C}$		0.01		%
	Load regulation	Over $I_{OUT}$ range, $T_A = 25^\circ\text{C}$		0.03		%
<b>OUTPUT CURRENT</b>						
$I_{OUT}$	Output current	Natural convection, $T_A = 25^\circ\text{C}$	0		25 <sup>(2)</sup>	A
	Overcurrent threshold			32		A
$I_{SHARE}$	Current sharing for multi-phase operation <sup>(1)</sup>	$I_{OUT} \leq 20\text{ A/phase}$		$\pm 3$		A
		$I_{OUT} \geq 20\text{ A/phase}$		$\pm 15\%$		
<b>BP5 REGULATOR</b>						
$V_{BP5}$	BP5 regulator output voltage		4.5	5	5.5	V
$V_{BP5-DROPOUT}$	BP5 regulator dropout voltage <sup>(1)</sup>	$V_{IN} = 4.5\text{ V}$ , $f_{SW} = 750\text{ kHz}$ , $T_A = 25^\circ\text{C}$			365	mV
<b>PERFORMANCE</b>						
$\eta$	Efficiency	$I_{OUT} = 12.5\text{ A}$		91		%
<b>RS+</b>						
$R_{RS+-RS-}$	Lower feedback resistor from RS+ to RS-		0.995	1	1.005	k $\Omega$
<b>ENABLE</b>						
$V_{EN-H}$	EN rising threshold	$I_{OUT} = 0\text{ A}$	1.45	1.6	1.75	V
$V_{EN-L}$	EN falling threshold	$I_{OUT} = 2.5\text{ A}$		1.3		V
$I_{EN\_LKG}$	EN input leakage current	$V_{IN} = 4.5\text{ V}$ , $I_{OUT} = 0\text{ A}$	-1	0	1	$\mu\text{A}$
<b>SOFT START</b>						
$t_{SS}$	Soft-start time <sup>(1)</sup>	SS = OPEN		4		ms
$t_{SS-Range}$	Soft-start range <sup>(1)</sup>	Programmable using SS pin	0.5		32	ms

**TPSM41625**

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Limits apply over  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ ,  $PV_{IN} = 12\text{ V}$ ,  $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.8\text{ V}$ ,  $V_{REF} = 1.0\text{ V}$ ,  $F_{SW} = 500\text{ kHz}$ ,  $I_{OUT} = 25\text{ A}$ , (unless otherwise noted); Minimum and maximum limits are specified through production test or by design. Typical values represent the most likely parametric norm and are provided for reference only.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>PGOOD</b>						
$V_{PGOOD}$	PGOOD thresholds <sup>(1)</sup>	$V_{RS+}$ rising (fault)		112%		
		$V_{RS+}$ falling (good)		105%		
		$V_{RS+}$ rising (good)		95%		
		$V_{RS+}$ falling (fault)		88%		
$V_{PGOOD-LOW}$	PGOOD low voltage with no supply voltage	$PV_{IN} = V_{IN} = 0\text{ V}$ , $I_{PGOOD} = 80\text{ }\mu\text{A}$			0.8	V
$I_{PGOOD-LKG}$	PGOOD leakage current	$V_{IN} = 4.5\text{ V}$ , $V_{PGOOD} = 5\text{ V}$ , $I_{OUT} = 0\text{ A}$			15	$\mu\text{A}$
<b>OVP / UVP</b>						
$V_{OVP}$	Overvoltage protection threshold <sup>(1)</sup>	$V_{RS+}$ rising		117%		
$V_{UVP}$	Under-voltage protection threshold <sup>(1)</sup>	$V_{RS+}$ falling		83%		
<b>FREQUENCY and SYNC</b>						
$f_{SW}$	Switching frequency	$V_{SEL} = \text{OPEN}$ , $R_T = 44.2\text{ k}\Omega$ , $I_{OUT} = 2.5\text{ A}$	450	500	550	kHz
	Switching frequency range <sup>(1)</sup>	$I_{OUT} = 2.5\text{ A}$	300		1000	kHz
$t_{on\_min}$	Minimum on-time of SW <sup>(1)</sup>			30		ns
$t_{off\_min}$	Minimum off-time of SW <sup>(1)</sup>			340		ns
$V_{CLK-H}$	Logic-high for SYNC <sup>(1)</sup>		2			V
$V_{CLK-L}$	Logic-low for SYNC <sup>(1)</sup>				0.8	V
$T_{CLK-MIN}$	Minimum pulse width for SYNC <sup>(1)</sup>	SYNC $F_{SW} = 500\text{ kHz}$	100			ns

(1) Ensured by design, not production tested.

(2) To determine  $I_{OUT}$  range for a given set of conditions, see the Safe Operating Area graphs in "Typical Characteristics" section of the datasheet for more information.



### 6.6 Typical Characteristics (PV<sub>IN</sub> = 12 V)

T<sub>A</sub> = 25°C, unless otherwise noted.

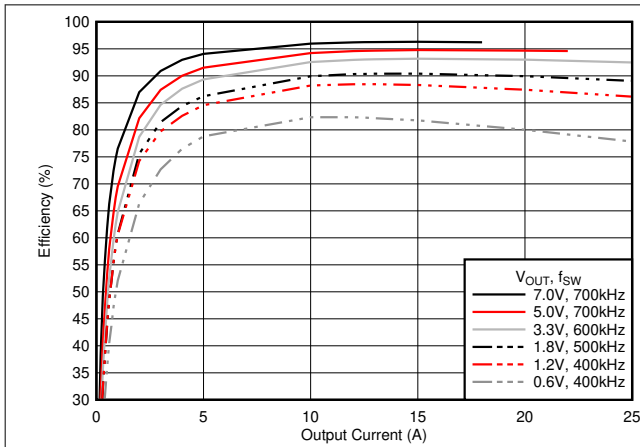


图 6-1. Efficiency vs Output Current

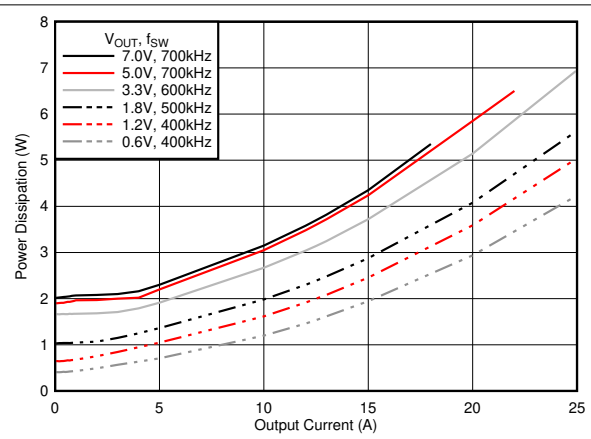


图 6-2. Power Dissipation vs Output Current

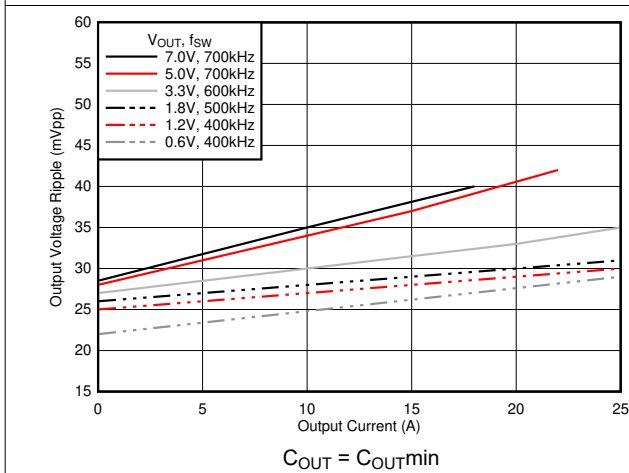


图 6-3. Output Voltage Ripple

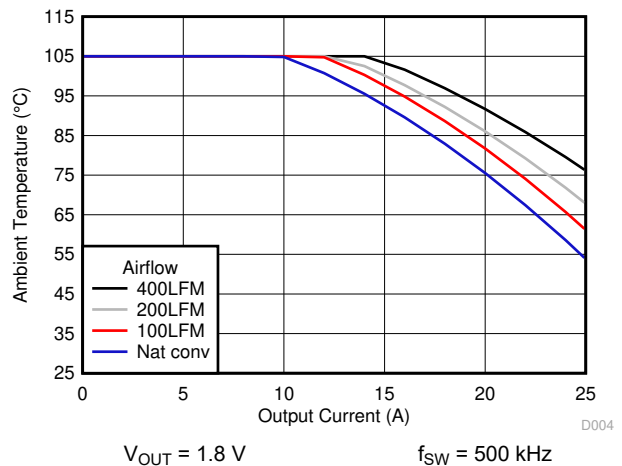


图 6-4. Safe Operating Area

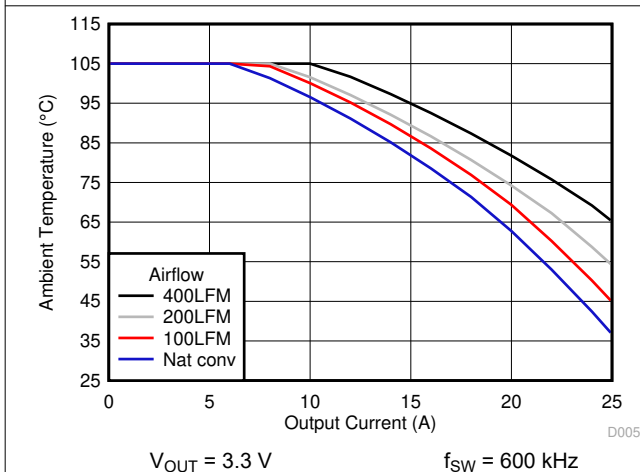


图 6-5. Safe Operating Area

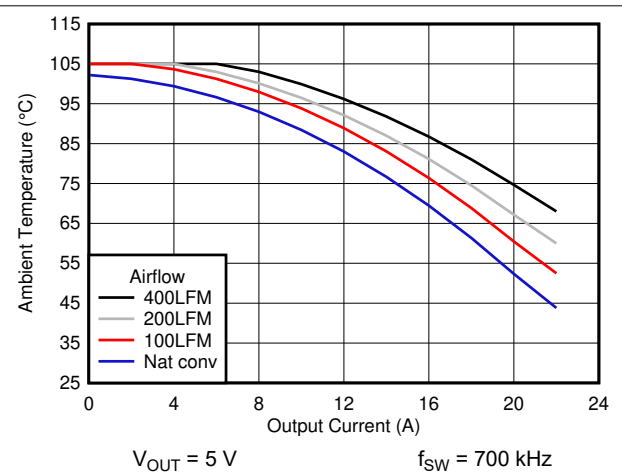
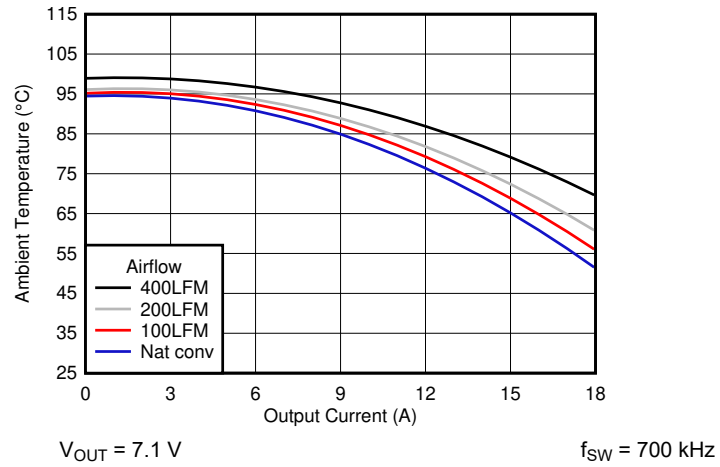


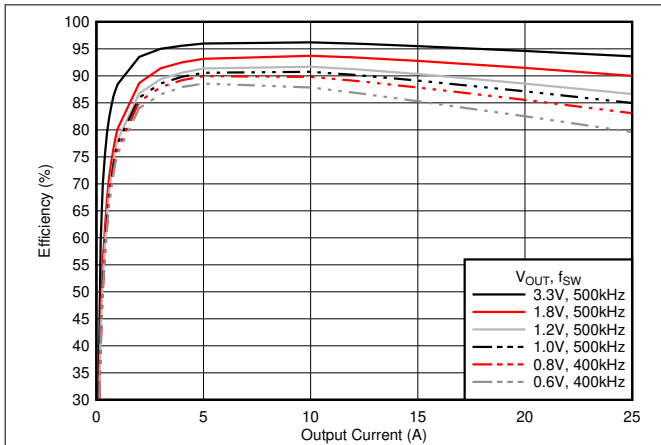
图 6-6. Safe Operating Area



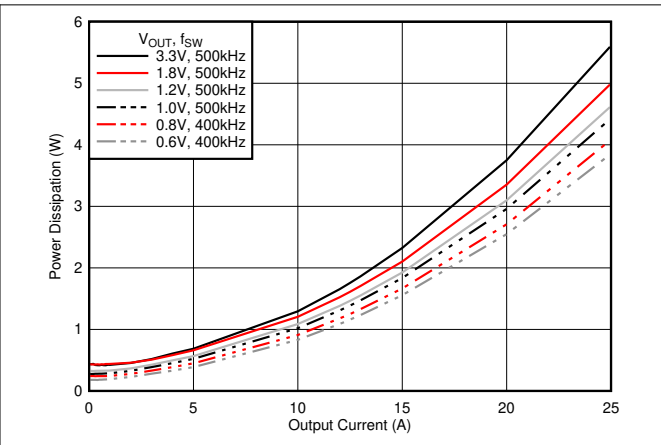
**图 6-7. Safe Operating Area**

### 6.7 Typical Characteristics (PV<sub>IN</sub> = 5 V)

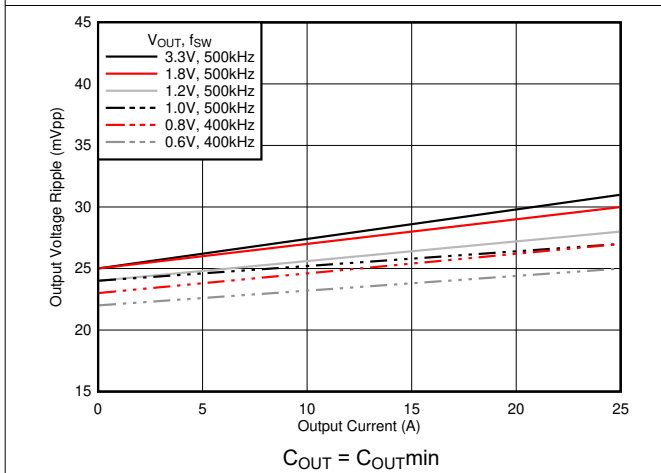
T<sub>A</sub> = 25°C, unless otherwise noted.



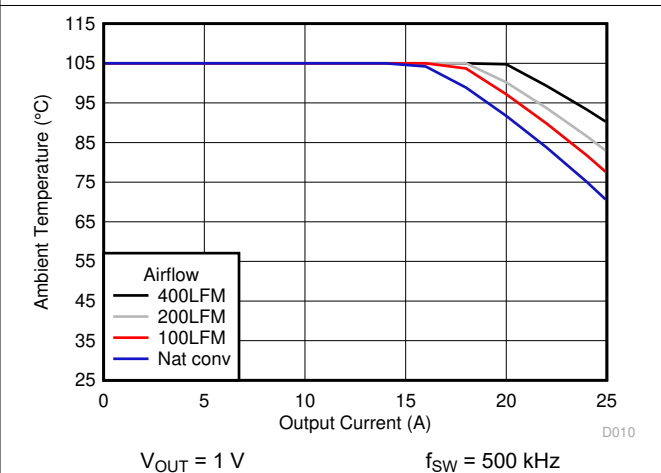
**图 6-8. Efficiency vs Output Current**



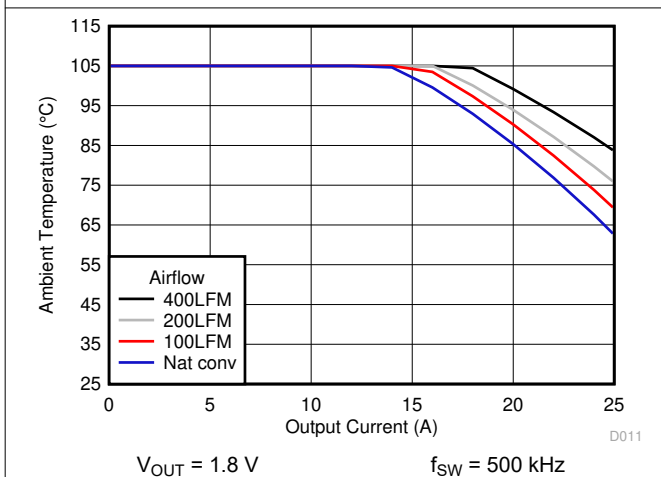
**图 6-9. Power Dissipation vs Output Current**



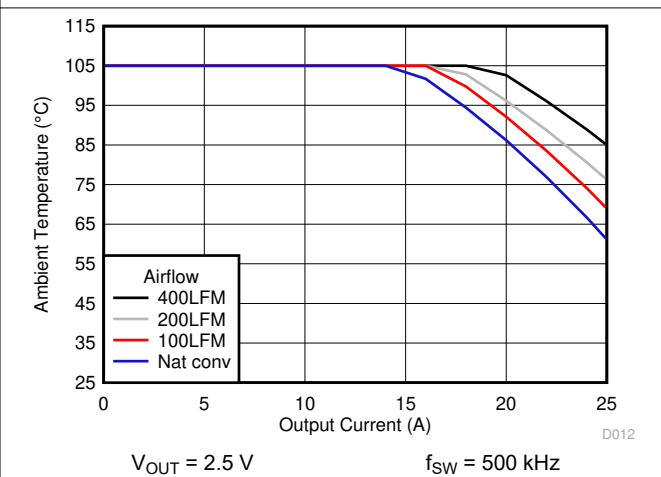
**图 6-10. Output Voltage Ripple**



**图 6-11. Safe Operating Area**



**图 6-12. Safe Operating Area**



**图 6-13. Safe Operating Area**

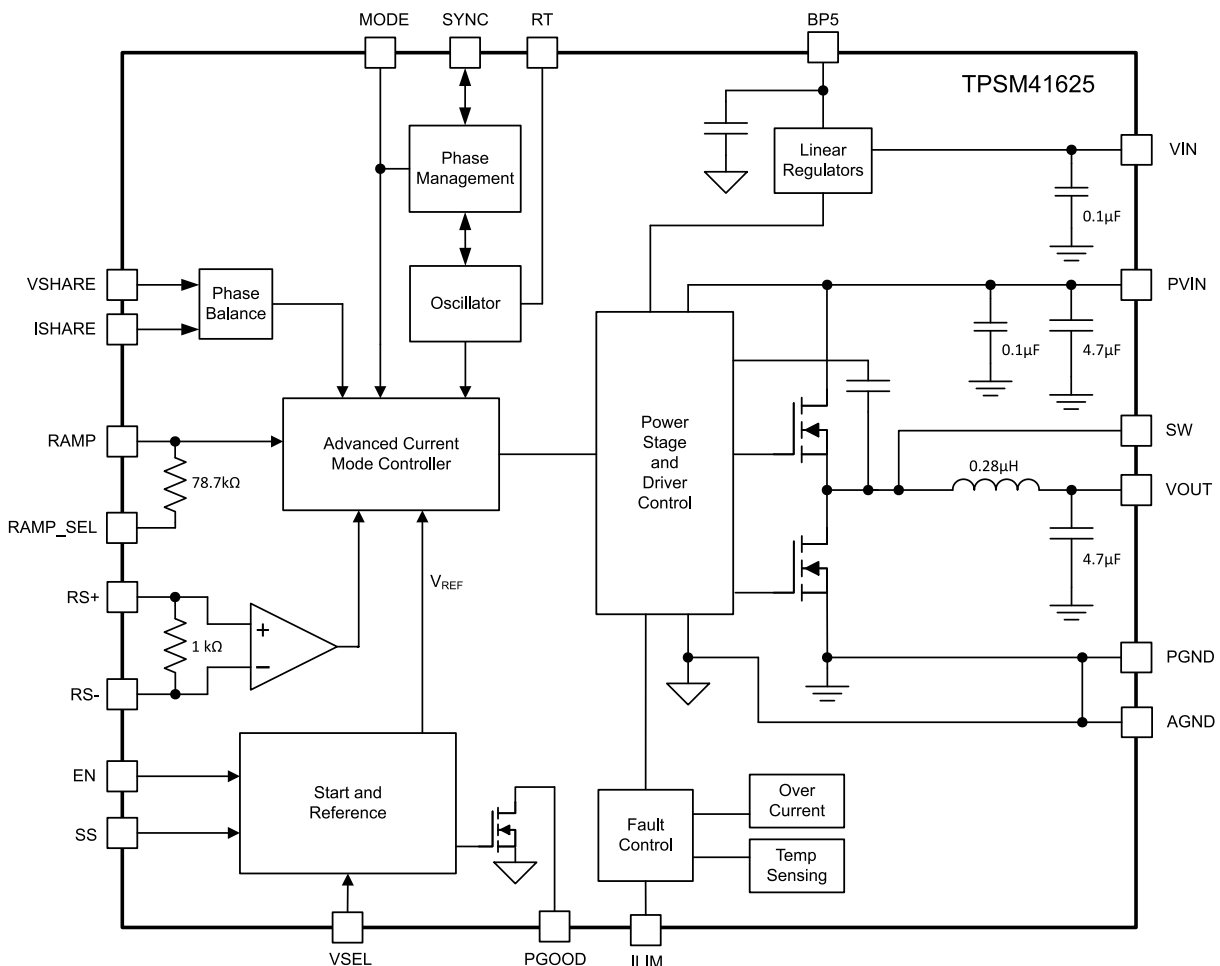
## 7 Detailed Description

### 7.1 Overview

The TPSM41625 is a full-featured, 4-V to 16-V input, 25-A, synchronous step-down converter with PWM, MOSFETs, inductor, and control circuitry integrated into a QFN package. The device integration enables small designs, while still leaving the ability to adjust key parameters to meet specific design requirements. The TPSM41625 provides an output voltage range of 0.6 V to 7.1 V, with a selectable internal reference from 0.6 V to 1.1 V, for greater accuracy. An external resistor is used to adjust the output voltage to the desired output. The switching frequency is also adjustable by using an external resistor or a synchronization clock to accommodate various input and output voltage conditions and to optimize efficiency. Applications requiring increased current can benefit from the stackability (parallel outputs and phase-interleaving) of the TPSM41625 device.

The TPSM41625 has been designed for safe start-up into pre-biased loads. The EN pin has an internal pullup current source that can be used to adjust the input voltage undervoltage lockout (UVLO) with two external resistors. In addition, the internal pullup current of the EN pin allows the device to operate with the EN pin floating. The EN pin can also be pulled low to put the device in standby mode to reduce input quiescent current. The device provides a power-good (PGOOD) signal to indicate when the output voltage is within regulation. Thermal shutdown and current limit features protect the device during an overload condition. A 69-pin QFN package that includes exposed bottom pads provides a thermally enhanced solution for space-constrained applications.

### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Setting the Output Voltage

The output voltage adjustment range of the TPSM41625 is 0.6 V to 7.1 V. Setting the output voltage requires first setting the internal reference voltage ( $V_{REF}$ ). The internal reference voltage can be set from 0.6 V to 1.1 V using a resistor ( $R_{VSEL}$ ) connected from VSEL (pin 28) to AGND (pin 19). 表 7-1 lists reference voltage selections and their corresponding setting resistors. If the required output voltage is the same as the reference voltage, connect the RS+ pin (pin 35) directly to VOUT to set the output voltage as shown in 图 7-1. Output voltages greater than the reference voltage require an external voltage setting resistor ( $R_{ADJ}$ ) between the RS+ pin and VOUT to set the output voltage as shown in 图 7-2. The value for  $R_{ADJ}$  can be calculated using 方程式 1 or simply selected from the recommended values given in 表 7-2. Additionally, 表 7-3 includes the recommended switching frequency ( $F_{SW}$ ), the recommended Ramp resistor ( $R_{RAMP}$ ), and the minimum output capacitance for several output voltage ranges.

$$R_{ADJ} = \left( \frac{V_{OUT}}{V_{ref}} - 1 \right) (k\Omega) \quad (1)$$

When setting the output voltage, selecting the highest reference voltage will result in the most accurate output voltage set point. The output voltage will be regulated at the connection point of RS+ or  $R_{ADJ}$  to VOUT. Making the connection near the load improves regulation at the load.

表 7-1. Setting the Reference Voltage

$V_{REF}$ (V)	0.6	0.7	0.75	0.8	0.85	0.9	0.95	1.0	1.05	1.1
$R_{VSEL}$ Value (k $\Omega$ ) <sup>(1)</sup>	0	8.66	15.4	23.7	34.8	51.1	78.7	open	121	187

(1) Resistors with  $\leq 1\%$  tolerance are recommended.

表 7-2. Setting the Output Voltage

$V_{OUT}$ (V)	0.6 - 1.1	1.2	1.5	1.8	2.5	3.3	5.0	6.0	7.0
$V_{REF}$ (V) <sup>(1)</sup>	0.6 - 1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1
$R_{ADJ}$ Value ( $\Omega$ ) <sup>(1)</sup>	short	90.9	365	634	1270	2000	3570	4420	5360

(1) Selecting the highest reference voltage will result in the most accurate output voltage set point.

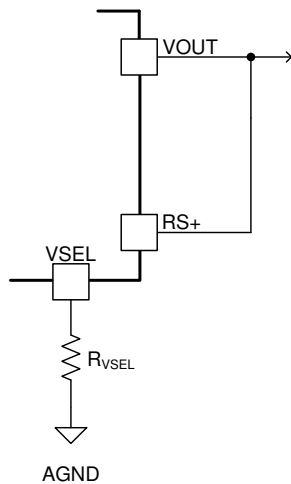


图 7-1. Setting the Output Voltage  
( $V_{OUT} = V_{REF}$ )

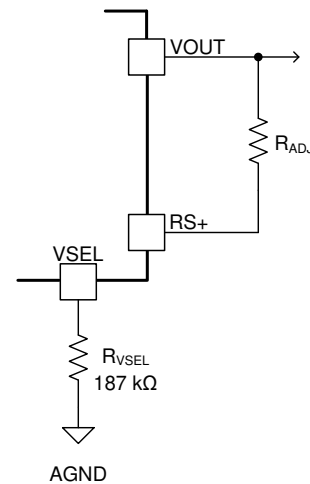


图 7-2. Setting the Output Voltage  
( $V_{OUT} > V_{REF}$ )

表 7-3. Recommended  $F_{SW}$ , RAMP, and Required  $C_{OUT}$ 

PV <sub>IN</sub> = 5 V						
V <sub>OUT</sub> RANGE (V)		RECOMMENDED F <sub>SW</sub> (kHz) <sup>(1)</sup>	ALLOWABLE F <sub>SW</sub> RANGE (KHZ)	R <sub>RAMP</sub> (k Ω)	MINIMUM REQUIRED C <sub>OUT</sub> (μF) <sup>(4)</sup>	
MIN	MAX				MINIMUM CERAMIC <sup>(3)</sup>	ADDITIONAL REQUIRED CAPACITANCE <sup>(5)</sup>
0.6	< 0.8	<b>400</b>	300 - < 450	78.7	294 <sup>(2)</sup>	610
		500	450 - < 550	187		490
		600	550 - < 700	187		300
		700	700 - 1000	78.7		280
0.8	< 1.0	<b>400</b>	300 - < 450	78.7	289 <sup>(2)</sup>	600
		500	450 - < 850	78.7		420
		900	850 - 1000	78.7		240
1.0	< 1.2	<b>500</b>	400 - 1000	187	284 <sup>(2)</sup>	190
1.2	< 1.5	<b>500</b>	400 - 1000	187	277 <sup>(2)</sup>	100
1.5	< 1.8	<b>500</b>	400 - 1000	187	266 <sup>(2)</sup>	90
1.8	< 2.5	<b>500</b>	400 - 1000	187	254 <sup>(2)</sup>	85
2.5	3.3	<b>500</b>	400 - 1000	78.7	224 <sup>(2)</sup>	65
PV <sub>IN</sub> = 12 V						
V <sub>OUT</sub> RANGE (V)		RECOMMENDED F <sub>SW</sub> (kHz) <sup>(1)</sup>	ALLOWABLE F <sub>SW</sub> RANGE (kHz)	R <sub>RAMP</sub> (k Ω)	MINIMUM REQUIRED C <sub>OUT</sub> (μF) <sup>(4)</sup>	
MIN	MAX				MINIMUM CERAMIC <sup>(3)</sup>	ADDITIONAL REQUIRED CAPACITANCE <sup>(5)</sup>
0.6	< 1.0	<b>400</b>	350 - < 450	78.7	294 <sup>(2)</sup>	760
		500	450 - < 550	78.7		430
		600	550 - 750	78.7		250
1.0	< 1.2	<b>400</b>	350 - < 500	78.7	284 <sup>(2)</sup>	760
		550	500 - < 600	78.7		430
		600	600 - 1000	78.7		250
1.2	< 1.8	<b>400</b>	350 - < 500	78.7	277 <sup>(2)</sup>	760
		500	500 - < 600	121		185
		600	600 - 1000	121		100
1.8	< 2.5	<b>400</b>	350 - < 500	78.7	254 <sup>(2)</sup>	600
		500	500 - < 600	187		430
		600	600 - < 850	187		250
		700	850 - 1000	78.7		90
2.5	< 3.3	<b>500</b>	450 - < 650	78.7	224 <sup>(2)</sup>	450
		700	650 - < 950	187		80
		1000	950 - 1000	121		80
3.3	< 5.0	<b>600</b>	550 - 1000	187	191 <sup>(2)</sup>	65
5.0	7.1	<b>700</b>	600 - 1000	187	134 <sup>(2)</sup>	0

- (1) The recommended  $F_{SW}$  is shown in **bold** text. Increasing the frequency can reduce the required output capacitance as well as reduce ripple, however it may also reduce efficiency.
- (2) This value of minimum ceramic is the effective amount of 6x 47 μF after taking into account DC bias and temperature derating.
- (3) The minimum required ceramic output capacitance must account for DC bias and temperature derating.
- (4) The Minimum Required output capacitance ensures start-up and stability. Additional output capacitance can be needed to meet transient response requirements.
- (5) The Additional Required Capacitance can be either ceramic or low-ESR polymer type. The total required output capacitance must include at least the amount of ceramic type listed in the *Minimum Ceramic* column.

### 7.3.2 Output Voltage Current Rating

The rated output current of the TPSM41625 depends on the output voltage required for an application. The output current derates at output voltages above 3.3 V. The area under the curve in 图 7-3 shows the operating range of the TPSM41625.

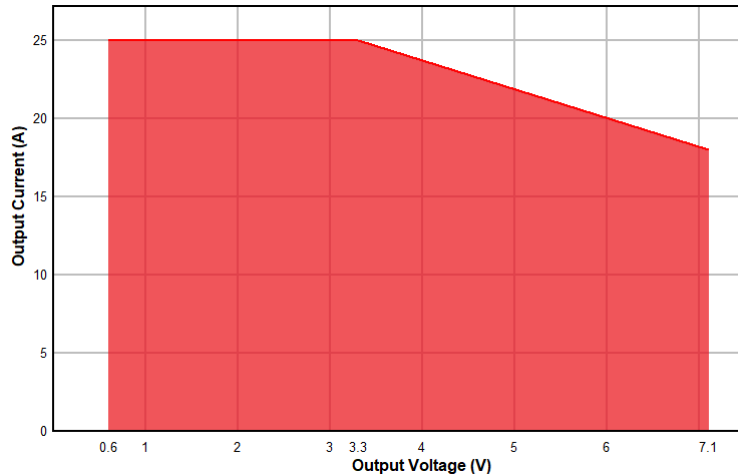


图 7-3. Output Voltage versus Output Current

### 7.3.3 RS+/RS- Remote Sense Function

RS+ and RS- pins are the remote sensing inputs to the internal differential remote sense amplifier. A 1-k $\Omega$  lower feedback resistor is connected across RS+ and RS- internal to the module. The RS+ pin is used for the feedback connection to VOUT. Connect this pin to the output voltage at the load. This connection can be made using a direct connection or an external upper feedback resistor, depending on the magnitude of VOUT and the VSEL selection. The RS- pin is used for the feedback connection to VOUT return. Connect this pin to the output voltage return at the load. The RS- connection is not needed for secondary devices in multi-phase configurations, and should be left open.

### 7.3.4 Ramp Select (RAMP and RAMP\_SEL)

The RAMP and RAMP\_SEL pins set the ramp amplitude for the internal control loop. Internal to the device, a 78.7-k $\Omega$  resistor is connected between RAMP and RAMP\_SEL. Applications requiring 78.7-k $\Omega$  ramp setting should connect the RAMP\_SEL pin to AGND and leave the RAMP pin open. Applications requiring a larger ramp setting resistor should connect it between the RAMP pin to AGND and leave the RAMP\_SEL pin open. The recommended ramp setting resistor can be found in 表 7-3.

### 7.3.5 Switching Frequency (RT)

The switching frequency range of the TPSM41625 is 300 kHz to 1 MHz. The switching frequency can easily be set by connecting a resistor ( $R_{RT}$ ) between the RT pin (pin 30) and AGND. Select  $R_{RT}$  from 表 7-4 based on input voltage and desired switching frequency.

The switching frequency must be selected based on the input voltage and output voltage of the application. See 表 7-3 for the allowable switching frequency range for each output voltage.

表 7-4.  $R_{RT}$  Frequency Setting Resistor (k $\Omega$ )

INPUT VOLTAGE	SWITCHING FREQUENCY														
	300 kHz	350 kHz	400 kHz	450 kHz	500 kHz	550 kHz	600 kHz	650 kHz	700 kHz	750 kHz	800 kHz	850 kHz	900 kHz	950 kHz	1 MHz
5 V	69.8	59.0	52.3	45.3	40.2	36.5	33.2	30.1	28.0	26.1	23.7	22.1	21.0	19.6	18.2
8 V	73.2	61.9	53.6	47.5	42.2	38.3	34.8	32.4	29.4	27.4	25.5	23.7	22.1	21.0	19.6
10 V - 16 V	75.0	63.4	54.9	48.7	43.2	39.2	35.7	33.2	30.1	28.0	26.1	24.3	23.2	21.5	20.5

### 7.3.6 Synchronization (SYNC)

The TPSM41625 device can be synchronized to an external clock. When synchronizing, the external clock signal must be applied to the SYNC pin before the device reaches its VIN UVLO threshold. In a stand-alone configuration, the external clock frequency must be within  $\pm 20\%$  of the frequency set by the  $R_{RT}$  resistor.

In stackable configuration: (see [# 7.3.7.1.1](#) for information on configuring the SYNC pins.)

1. When there is no external system clock applied, the SYNC pin of the primary device should be configured as Sync-Out and the SYNC pin of the secondary device should be configured as Sync-In. Connecting the SYNC pins of the primary and any secondary devices will synchronize all devices to the frequency of the primary.
2. When an external system clock is applied, the SYNC pin of the primary and secondary devices should be configured as Sync-In and both devices will synchronize to the external system clock.

#### 7.3.6.1 Loss of Synchronization

This device does not support the dynamic application or removal of an external SYNC signal. If the external SYNC signal is removed, the device treats this as a clock fault and stops power conversion.

### 7.3.7 Stand-alone/Stackable Operation

The TPSM41625 can be operated as a single stand-alone device or two devices can be combined to operate together in a stackable configuration for increased current. These operation modes are selected using a resistor connected from MODE pin to AGND. In stand-alone mode, the resistor value connected to the MODE pin also selects whether the transient response feature is ON or OFF (see [表 7-8](#)). In stackable mode, the transient response feature is not available. In stackable mode, the MODE resistor sets the device as primary or secondary, as well as SYNC pin function (sync in or sync out) of the primary device (see [表 7-5](#)).

表 7-5. MODE Pin Selections

OPERATION MODE	TRANSIENT FEATURE	SYNC MODE	MODE RESISTOR VALUE (k $\Omega$ )
Stand-alone	ON	Sync in	78.7
			187
	OFF		open
Stackable	OFF	Primary sync out	23.7
		Primary sync in	34.8
		Secondary sync in	51.1



### 7.3.7.1 Stackable Synchronization

#### 7.3.7.1.1 Sync Configuration

In stackable mode, a resistor between the MODE pin and AGND sets the device as primary or secondary, as well as SYNC pin function (sync in or sync out) of the primary device. See 表 7-6 for Mode resistor values.

表 7-6. MODE Setting for SYNC Function

SYNC FUNCTION	MODE RESISTOR VALUE (kΩ)	NOTE
Primary sync out	23.7	<ul style="list-style-type: none"> <li>• Sync pin to send out clock</li> <li>• RT pin to set frequency</li> </ul>
Primary sync in	34.8	<ul style="list-style-type: none"> <li>• Sync pin to receive clock</li> <li>• RT pin to set sync point</li> </ul>
Secondary sync in	51.1	<ul style="list-style-type: none"> <li>• Sync pin to receive clock</li> <li>• RT pin to set sync point</li> </ul>

#### 7.3.7.1.2 Clock Sync Point Selection

The TPSM41625 device implements a unique clock synchronization scheme for phase interleaving between devices. This is only used when stacking multiple devices. The device will receive a clock signal through the SYNC pin and generate sync points to achieve phase interleaving. Sync point options can be selected with a resistor from the RT pin to AGND. 图 7-4 shows the clock signals for a primary and a secondary device with a 180° phase shift. See 表 7-7 for clock sync options and the corresponding RT resistor value.

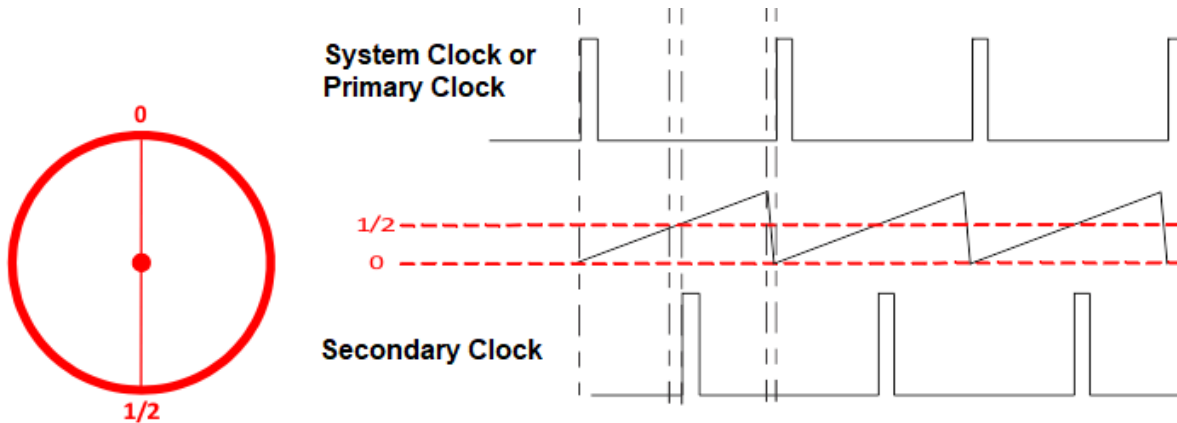


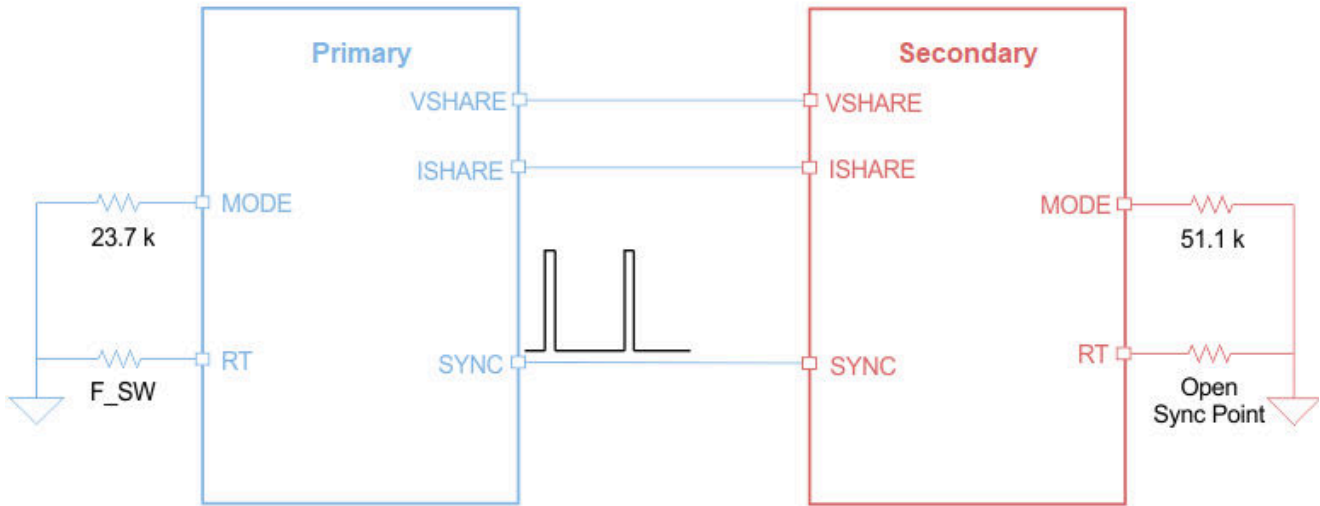
图 7-4. 2-Phase Stackable with 180° Clock Phase Shift

表 7-7. Sync Point Selection

CLOCK SYNC OPTIONS	RT RESISTOR VALUE (kΩ)
0 (0° Interleaving)	SHORT
1/2 (180° Interleaving)	OPEN

**7.3.7.1.3 Configuration 1: Dual Phase, Primary Sync-Out Clock to Secondary**

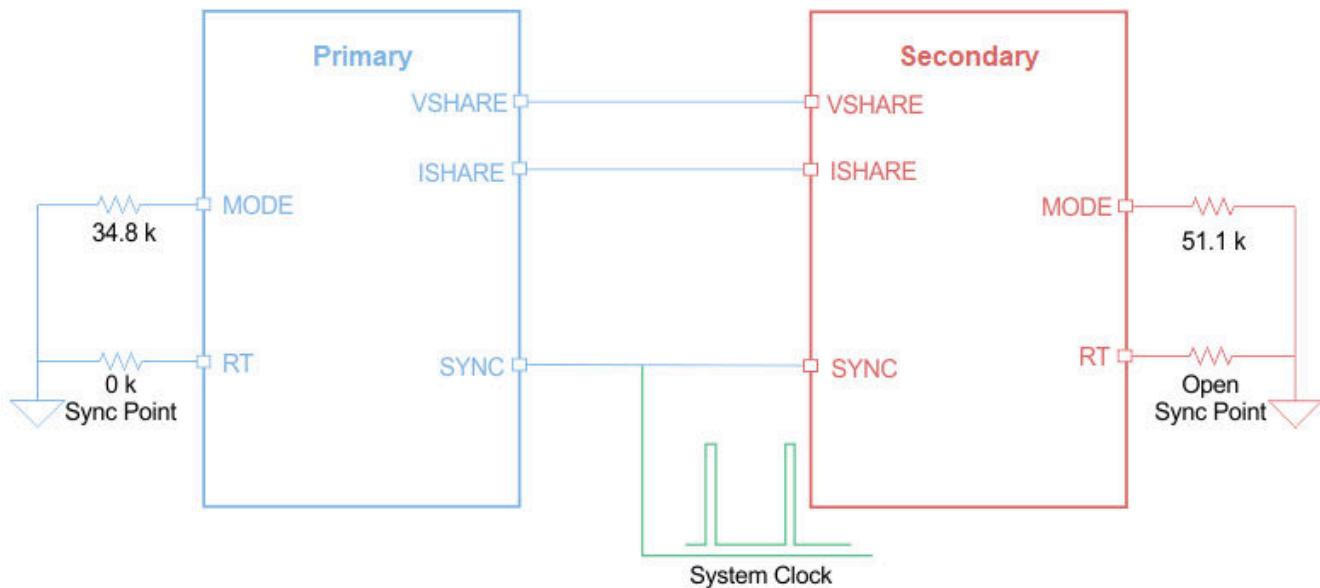
- Direct SYNC, VSHARE, and ISHARE connections between primary and secondary.
- Switching frequency is set by RT pin of primary, and pass to secondary through SYNC pin. SYNC pin of primary will be configured as sync out by its MODE pin.
- Secondary receives clock from SYNC pin. Its RT pin determines the sync point for clock phase shift.



**图 7-5. 2-Phase Stackable, 180° Phase Shift: Primary Sync-Out Clock to Secondary**

**7.3.7.1.4 Configuration 2: Dual Phase, Primary and Secondary Sync to External System Clock**

- Direct connection between external clock and SYNC pin of primary and secondary.
- Direct VSHARE and ISHARE connections between primary and secondary.
- SYNC pin of primary is configured as sync in by its MODE pin.
- Primary and secondary receive external system clock from SYNC pin. Their RT pin determine the sync point for clock phase shift.



**图 7-6. 2-Phase Stackable, 180° Phase Shift: Primary and Secondary Sync to External System Clock**

### 7.3.8 Improved Transient Performance versus Fixed Frequency (Stand-alone Operation Only)

The TPSM41625 is a fixed frequency converter. The major limitation for any fixed frequency converter is that during transient load step up, the output voltage drops until the next clock cycle of the converter before it can respond to the load change. The TPSM41625 implements a special circuitry to improve transient performance. During a load step up, the converter can issue an additional PWM pulse before the next available clock cycle to stop output voltage from further dropping, thus reducing the undershoot voltage. The additional pulse during a transient means that the device is not fixed frequency during the transient.

During load step-down, the TPSM41625 implements a body-brake function that turns off both high-side and low-side FET, and allows power to dissipate through the low-side body diode, reducing overshoot. This approach is very effective while having some impact on efficiency during transient.

In stand-alone mode, choose whether the transient response feature is enabled by placing either a 78.7-k $\Omega$  or 187-k $\Omega$  resistor between the MODE pin and AGND. A 78.7-k $\Omega$  MODE resistor is recommended when the output voltage is 0.6 V to 1.8 V or in applications that are more susceptible to noise. Leave the MODE pin open to operate in fixed frequency during a load step, (see 表 7-8).

**表 7-8. Stand-Alone Operation Feature Selections**

STAND-ALONE OPERATION	MODE RESISTOR VALUE (k $\Omega$ )
Transient Feature	78.7
	187
Fixed Frequency	open

### 7.3.9 Output On/Off Enable (EN)

The EN pin provides electrical ON/OFF control of the device. Once the EN pin voltage exceeds the threshold voltage, the device starts operation. If the EN pin voltage is pulled below the threshold voltage, the regulator stops switching and enters low operating current state. The EN pin has an internal pullup to BP5, allowing the user to float the EN pin for enabling the device.

If an application requires controlling the EN pin, either drive it directly with a logic input or use an open drain/collector device to interface with the pin. Applying a low voltage to the enable control (EN) pin disables the output of the supply. When the EN pin voltage exceeds the threshold voltage, the supply executes a soft-start power-up sequence.

### 7.3.10 Power Good (PGOOD)

The PGOOD pin is an open-drain output requiring an external pullup resistor to output a high signal. Once the output voltage is between 92% and 108% of the set-point voltage, the PGOOD pin pulldown is released and the pin floats. A pullup resistor between the values of 10 k $\Omega$  and 100 k $\Omega$  to a voltage source of 5.5 V or less is recommended. The PGOOD pin is pulled low when the output voltage is lower than 88% or greater than 112% of the set-point voltage.

### 7.3.11 Soft-Start Operation

For the TPSM41625 device, the soft-start time controls the inrush current required to charge the output capacitors during start-up. When the device is enabled, the output voltage ramps from 0 V to the set-point voltage in the time selected by the SS pin. The device offers 10 selectable soft start options ranging from 0.5 ms to 32 ms. See 表 7-9 for details.

**表 7-9. SS Pin Configuration**

SS TIME	0.5 ms	1 ms	2 ms	4 ms	5 ms	8 ms	12 ms	16 ms	24 ms	32 ms
RESISTOR VALUE (k $\Omega$ )	0	8.66	15.4	OPEN	23.7	34.8	51.1	78.7	121	187

### 7.3.12 Input Capacitor Selection

The TPSM41625 requires a minimum input capacitance of 88  $\mu\text{F}$  of ceramic type. Use only high-quality ceramic type X5R or X7R capacitors with sufficient voltage rating. An additional 100  $\mu\text{F}$  of non-ceramic, bulk capacitance is recommended for applications with transient load requirements. The voltage rating of input capacitors must be greater than the maximum input voltage. [表 7-10](#) includes a preferred list of capacitors by vendor.

**表 7-10. Recommended Input Capacitors**

VENDOR <sup>(1)</sup>	SERIES	PART NUMBER	CAPACITOR CHARACTERISTICS		
			WORKING VOLTAGE (V)	CAPACITANCE ( $\mu\text{F}$ ) <sup>(3)</sup>	ESR (m $\Omega$ ) <sup>(2)</sup>
TDK	X7R	C3225X7R1E226M250AB	25	22	2
Murata	X7R	GRM32ER71E226KE15L	25	22	2
Panasonic	ZA	EEHZA1H101P	50	100	28

- (1) **Capacitor Supplier Verification , RoHS, Lead-free and Material Details** Consult capacitor suppliers regarding availability, material composition, RoHS and lead-free status, and manufacturing process requirements for any capacitors identified in this table.  
(2) Maximum ESR at 100 kHz, 25°C  
(3) Specified capacitance values

### 7.3.13 Output Capacitor Selection

The minimum required output capacitance of the TPSM41625 is a function of the output voltage and is shown in [表 7-3](#). The required capacitance can be comprised of all ceramic capacitors or a combination of ceramic and low-ESR polymer type capacitors. When adding additional capacitors, low-ESR capacitors like the ones recommended in [表 7-11](#) are required. The required capacitance above the minimum is determined by actual transient deviation requirements.

**表 7-11. Recommended Output Capacitors**

VENDOR <sup>(1)</sup>	SERIES	PART NUMBER	CAPACITOR CHARACTERISTICS		
			WORKING VOLTAGE (V)	CAPACITANCE ( $\mu\text{F}$ ) <sup>(3)</sup>	ESR (m $\Omega$ ) <sup>(2)</sup>
Murata	X7R	GCM32ER70J476K	6.3	47	2
Taiyo Yuden	X7R	LMK325B7476MM-PR	10	47	2
Murata	X7R	GRM32ER71A476K	10	47	2
TDK	X5R	C3225X5R0J107M	6.3	100	2
Murata	X5R	GRM32ER60J107M	6.3	100	2
Murata	X5R	GRM32ER61A107M	10	100	2
Murata	X6S	GRM32EC80G227ME05L	4.0	220	2
Panasonic	POSCAP	4TPE220MF	4.0	220	15
Kemet	T520	T520D227M006ATE015	6.3	220	15
Panasonic	POSCAP	6TPE330MAA	6.3	330	10
Kemet	T520	T520D337M006ATE010	6.3	330	10
Kemet	T520	T520X337M010ATE010	10	330	10

- (1) **Capacitor Supplier Verification , RoHS, Lead-free and Material Details** Consult capacitor suppliers regarding availability, material composition, RoHS and lead-free status, and manufacturing process requirements for any capacitors identified in this table.  
(2) Maximum ESR at 100 kHz, 25°C  
(3) Specified capacitance values

### 7.3.14 Current Limit (ILIM)

The current limit of the TPSM41625 is internally set to 32 A (typ.) by leaving the ILIM pin open. Connecting a resistor between the ILIM pin and AGND adjusts the current limit threshold lower. Refer to [表 7-12](#) for current limit adjustment values.

**表 7-12. Current Limit Adjust**

CURRENT LIMIT REDUCTION	10 %	20 %	30 %	40 %	50 %
$R_{ILIM}$ (k $\Omega$ )	191	118	78.7	54.9	37.4

### 7.3.15 Safe Start-up into Pre-Biased Outputs

The TPSM41625 device has been designed to prevent the low-side MOSFET from discharging a pre-biased output. During pre-biased start-up, the low-side MOSFET is not allowed to sink current until the SS/TR pin voltage is higher than the FB pin voltage and the high-side MOSFET begins to switch.

### 7.3.16 Overcurrent Protection

For protection against load faults, the TPSM41625 is protected from overcurrent conditions by cycle-by-cycle current limiting. In an extended overcurrent condition, the device enters hiccup mode to reduce power dissipation. In hiccup mode, the module continues in a cycle of successive shutdown and power up until the load fault is removed. During this period, the average current flowing into the fault is significantly reduced, which reduces power dissipation. Once the fault is removed, the module automatically recovers and returns to normal operation.

### 7.3.17 Output Overvoltage and Undervoltage Protection

The device includes both output overvoltage protection and output undervoltage protection capability. The devices compare the RS+ pin voltage to internal selectable pre-set voltages. If the RS+ voltage with respect to RS- voltage rises above the output overvoltage protection threshold, the device terminates normal switching and turns on the low-side MOSFET to discharge the output capacitor and prevent further increases in the output voltage. Then, the device enters continuous restart hiccup.

If the RS+ pin voltage falls below the undervoltage protection level, after soft start has completed, the device terminates normal switching and forces both the high-side and low-side MOSFETs off, then enters hiccup time-out delay prior to restart.

### 7.3.18 Overtemperature Protection

An internal temperature sensor protects the device from thermal runaway. The internal thermal shutdown circuitry forces the device to stop switching if the junction temperature exceeds 165°C typically. The device reinitiates the power-up sequence when the junction temperature drops below 135°C typically.

## 7.4 Device Functional Modes

### 7.4.1 Active Mode

The TPSM41625 is in active mode when VIN is above the UVLO threshold and the EN pin voltage is above the EN high threshold. The EN pin has an internal current source to enable the output when the EN pin is left floating. If the EN pin is pulled low the device is put into a low quiescent current state.

### 7.4.2 Shutdown Mode

The EN pin provides electrical ON and OFF control for the TPSM41625. When the EN pin voltage is below the EN low threshold, the device is in shutdown mode. In shutdown mode, the device is put into a low quiescent current state. The TPSM41625 also employs undervoltage lockout protection. If  $V_{IN}$  is below the UVLO level, the output of the regulator turns off.

## 8 Application and Implementation

### 备注

以下应用部分中的信息不属于 TI 器件规格的范围，TI 不担保其准确性和完整性。TI 的客户应负责确定器件是否适用于其应用。客户应验证并测试其设计，以确保系统功能。

### 8.1 Application Information

The TPSM41625 is a synchronous step-down DC-DC power module. It is used to convert a higher DC voltage to a lower DC voltage with a maximum output current of 25 A. The following design procedure can be used to select components for the TPSM41625. Alternately, the WEBENCH® software may be used to generate complete designs. When generating a design, the WEBENCH software utilizes an iterative design procedure and accesses comprehensive databases of components. See [www.ti.com/webench](http://www.ti.com/webench) for more details.

### 8.2 Typical Application

The TPSM41625 requires only a few external components to convert from a wide input voltage supply range to a wide range of output voltages. 图 8-1 shows a typical TPSM41625 schematic with only the minimum required components.

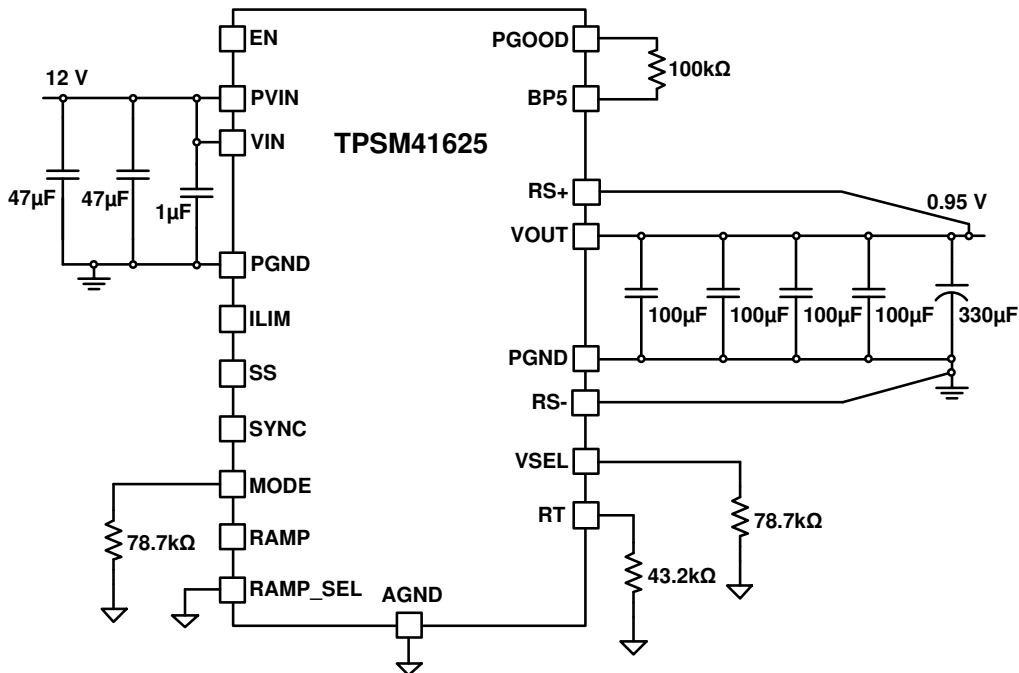


图 8-1. TPSM41625 Typical Application

#### 8.2.1 Design Requirements

For this design example, use the parameters listed in 表 8-1. Follow the design procedures in 节 8.2.2.

表 8-1. Design Example Parameters

DESIGN PARAMETER	VALUE
Input voltage $V_{IN}$	12 V typical
Output voltage $V_{OUT}$	0.95 V
Output current rating	25 A
Key care-about	Small solution size

## 8.2.2 Detailed Design Procedure

### 8.2.2.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPSM41625 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage ( $V_{IN}$ ), output voltage ( $V_{OUT}$ ), and output current ( $I_{OUT}$ ) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at [www.ti.com/WEBENCH](http://www.ti.com/WEBENCH).

### 8.2.2.2 Output Voltage Setpoint

The output voltage of the TPSM41625 is externally adjustable by first setting the reference voltage,  $V_{REF}$ , using the VSEL pin and then, if needed, setting the output voltage adjust resistor  $R_{ADJ}$ . For this application,  $V_{REF}$  is the same as the output voltage, so  $R_{ADJ}$  is not needed and RS+ should be connected to the output rail, near the load.

To set the output voltage to 0.95 V, select  $V_{REF}$  of 0.95 V by connecting a 78.7-k $\Omega$  resistor between VSEL pin and AGND and connect RS+ pin to the output voltage rail. VSEL resistor values for setting VREF can be found in [表 7-1](#).

### 8.2.2.3 Setting the Switching Frequency

To set the switching frequency of the TPSM41625, a resistor ( $R_{RT}$ ) between the RT pin and AGND is required. Select the value of  $R_{RT}$  from [表 7-4](#). Before selecting the switching frequency, reference [表 7-3](#) for the allowable switching frequency range, required output capacitance, and RAMP setting for the desired output voltage.

For this application, after referencing [表 7-3](#), 500 kHz was selected and a 43.2-k $\Omega$  RT resistor is required for a 12-V input according to [表 7-4](#).

### 8.2.2.4 RAMP Setting

The value of the RAMP resistor,  $R_{RAMP}$ , must be selected based on the switching frequency and output capacitance of the application, as shown in [表 7-3](#). For this application, the required  $R_{RAMP}$  is 78.7 k $\Omega$ . There is a 78.7-k $\Omega$  resistor internal to the device connected between RAMP and RAMP\_SEL. To select the internal 78.7-k $\Omega$  resistor, leave the RAMP pin open and connect RAMP\_SEL to AGND.

### 8.2.2.5 Input Capacitors

The TPSM41625 requires a minimum of 88  $\mu$ F of ceramic input capacitance. Applications with load transient requirements can benefit from adding additional bulk input capacitance.

For this design, two 47- $\mu$ F ceramic capacitors rated for 25 V are used for the input decoupling capacitors.

Additionally, a 1- $\mu$ F bypass capacitor is required on the VIN pin, close to the device pins.

### 8.2.2.6 Output Capacitors

The minimum required output capacitance for a 12-V input and 0.95-V output at 500 kHz switching frequency is 294  $\mu$ F of ceramic capacitance, as well as an additional 430  $\mu$ F of either ceramic or low-ESR polymer, as shown in [表 7-3](#).

For this design, four 100- $\mu$ F ceramic capacitors plus a 330- $\mu$ F polymer capacitor were used to meet the requirements.

### 8.2.3 Application Waveforms

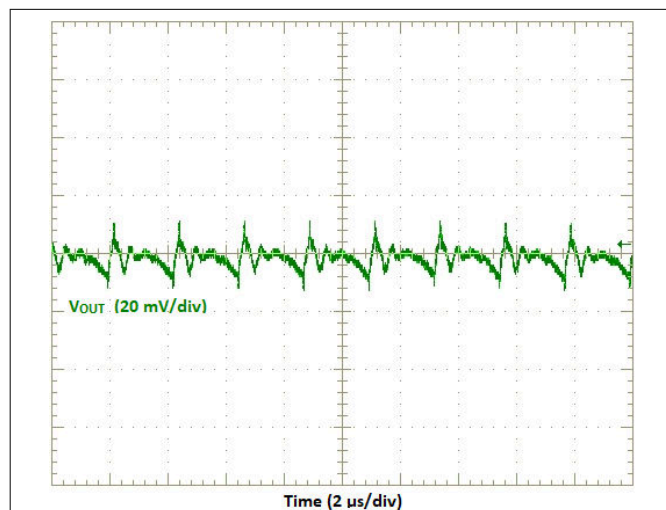


图 8-2. Output Ripple Waveform

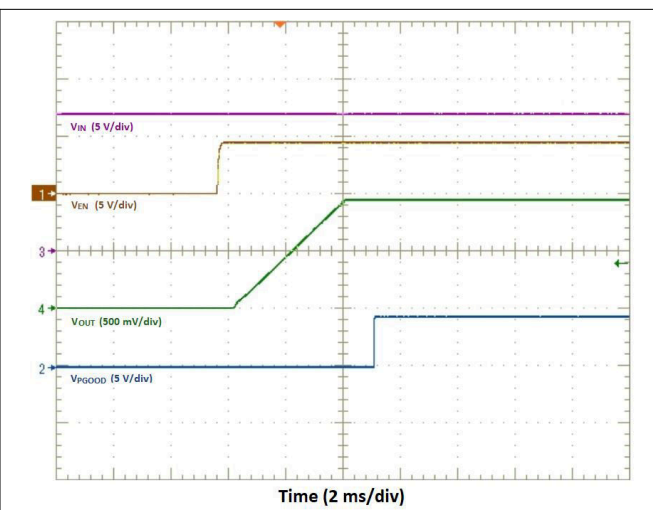


图 8-3. Start-Up Waveforms

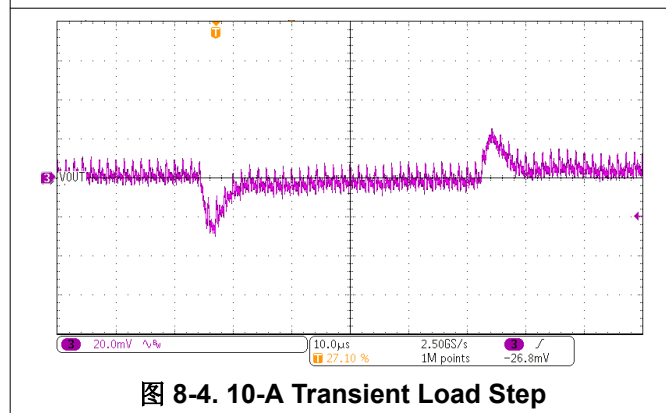


图 8-4. 10-A Transient Load Step

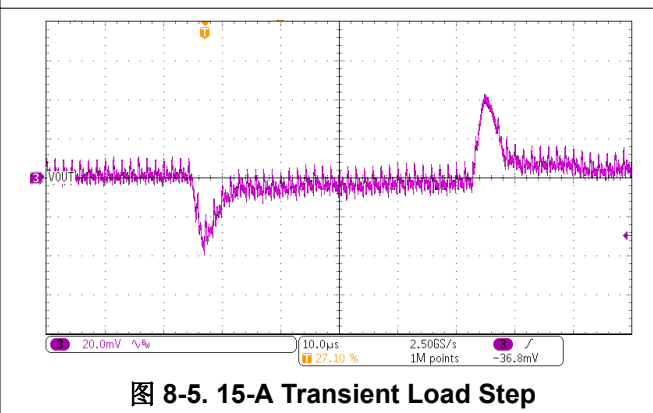


图 8-5. 15-A Transient Load Step

## 9 Power Supply Recommendations

The TPSM41625 is designed to operate from an input voltage supply range between 4 V and 16 V. The input supply must be well regulated and able to withstand maximum input current and maintain a stable voltage. The resistance of the input supply rail must be low enough that an input current transient does not cause a high enough drop at the TPSM41625 supply voltage that can cause a false UVLO fault triggering and system reset.

If the input supply is located more than a few inches from the TPSM41625 additional bulk capacitance can be required in addition to the ceramic bypass capacitors. Typically, a 47- $\mu$ F or 100- $\mu$ F electrolytic capacitor will suffice.



## 10 Layout

The performance of any switching power supply depends as much upon the layout of the PCB as the component selection. The following guidelines will help users design a PCB with the best power conversion performance, thermal performance, and minimized generation of unwanted EMI.

### 10.1 Layout Guidelines

To achieve optimal electrical and thermal performance, an optimized PCB layout is required. 图 10-1 through 图 10-4 shows a typical PCB layout. Some considerations for an optimized layout are:

- Use large copper areas for power planes (PVIN, VOUT, and PGND) to minimize conduction loss and thermal stress.
- Place ceramic input and output capacitors close to the device pins to minimize high frequency noise.
- Locate additional output capacitors between the ceramic capacitor and the load.
- Keep AGND and PGND separate from one another. The connection is made internal to the device.
- Place  $R_{VSEL}$ ,  $R_{ADJ}$ ,  $R_{RT}$ ,  $R_{MODE}$ , and  $C_{SS}$  as close as possible to their respective pins.
- Use multiple vias to connect the power planes (PVIN, VOUT, and PGND) to internal layers.

### 10.2 Layout Examples

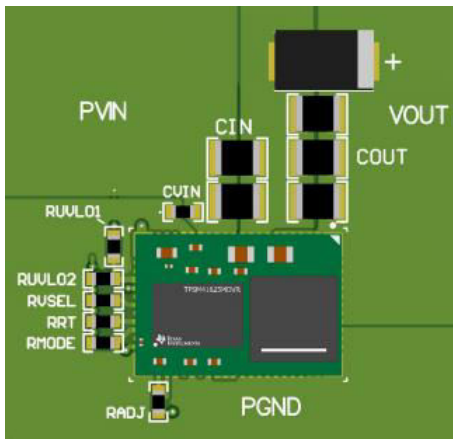


图 10-1. Top-Layer Components (Top View)

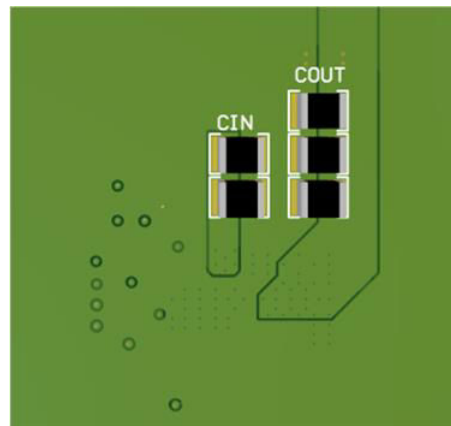


图 10-2. Bottom-Layer Components (Top View)

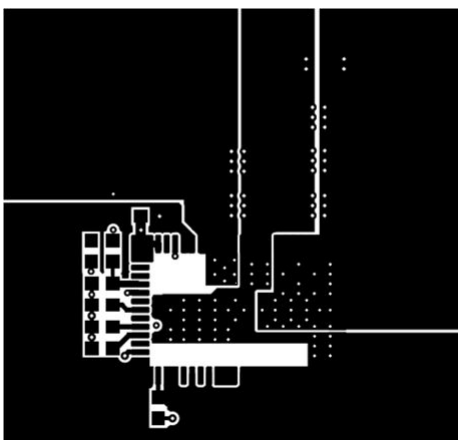


图 10-3. Top-Layer Layout (Top View)

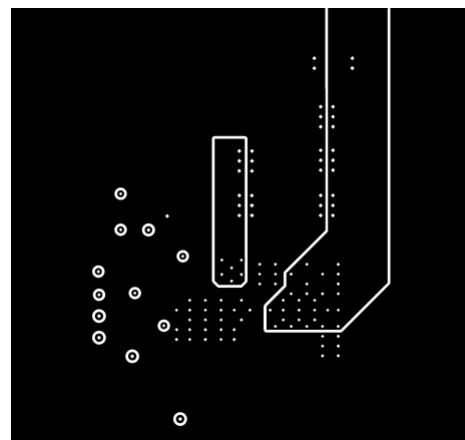


图 10-4. Bottom-Layer Layout (Top View)

### 10.2.1 Package Specifications

TPSM41625		VALUE	UNIT
Weight		1.32	grams
Flammability	Meets UL 94 V-O		
MTBF Calculated Reliability	Per Bellcore TR-332, 50% stress, T <sub>A</sub> = 40°C, ground benign	39.7	MHrs

### 10.2.2 EMI

The TPSM41625 is compliant with EN55011 Class B radiated emissions. 图 10-5, 图 10-6, and 图 10-7 show typical examples of radiated emissions plots for the TPSM41625. The graphs include the plots of the antenna in the horizontal and vertical positions.

#### 10.2.2.1 EMI Plots

EMI plots were measured using the standard TPSM41625EVM with an input filter in series with the input wires.

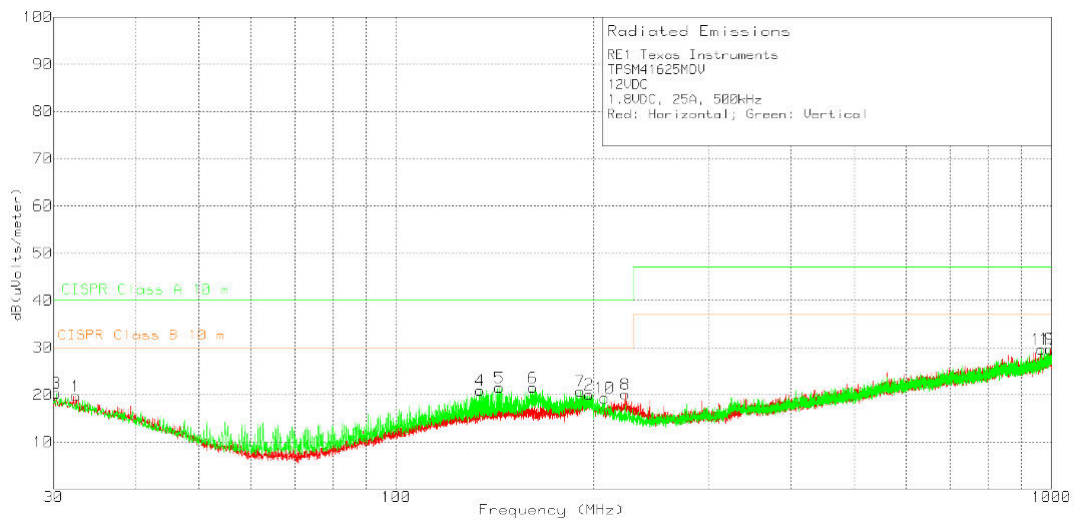


图 10-5. Radiated Emissions 12-V Input, 1.8-V Output, 25-A Load (EN55011 Class B)

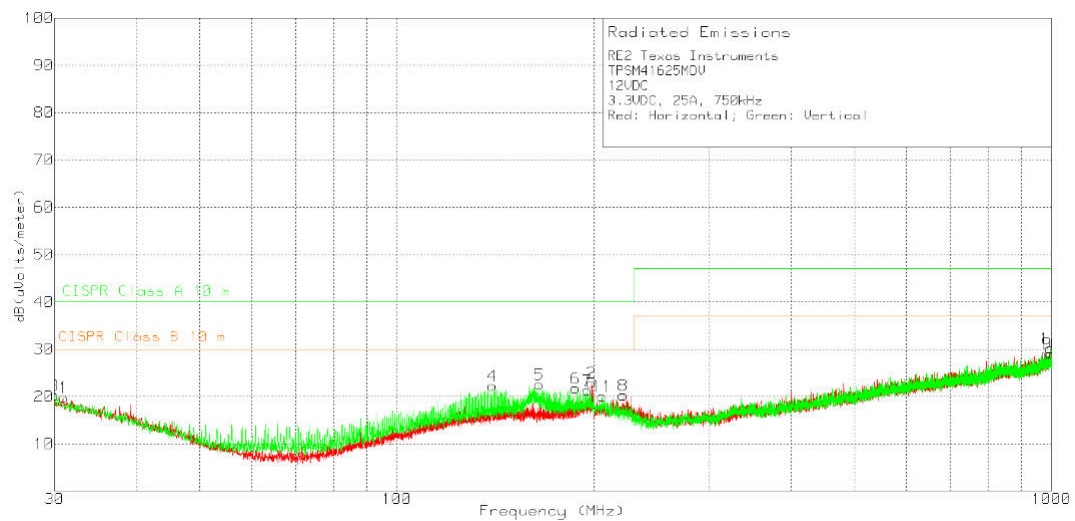


图 10-6. Radiated Emissions 12-V Input, 3.3-V Output, 25-A Load (EN55011 Class B)

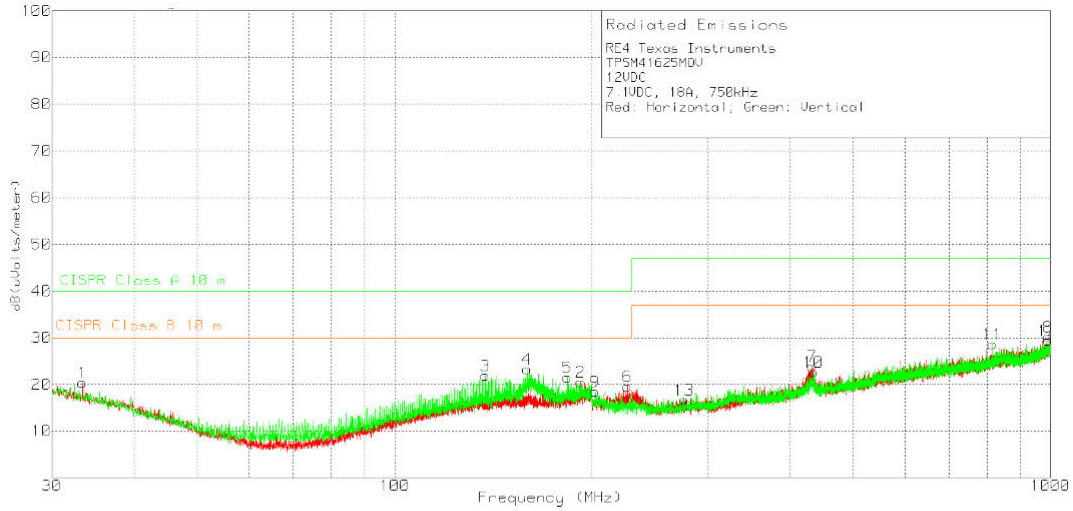


图 10-7. Radiated Emissions 12-V Input, 7.1-V Output, 18-A Load (EN55011 Class B)

## 11 Device and Documentation Support

### 11.1 Device Support

#### 11.1.1 Development Support

##### 11.1.1.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPSM41625 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage ( $V_{IN}$ ), output voltage ( $V_{OUT}$ ), and output current ( $I_{OUT}$ ) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

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- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at [www.ti.com/WEBENCH](http://www.ti.com/WEBENCH).

### 11.2 接收文档更新通知

要接收文档更新通知，请导航至 [ti.com](http://ti.com) 上的器件产品文件夹。点击 [订阅更新](#) 进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

### 11.3 支持资源

TI E2E™ 支持论坛是工程师的重要参考资料，可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题可获得所需的快速设计帮助。

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ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

### 11.6 术语表

[TI 术语表](#) 本术语表列出并解释了术语、首字母缩略词和定义。

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPSM41625MOVR	ACTIVE	QFM	MOV	69	500	RoHS Exempt & non-Green	NIAU	Level-3-260C-168 HR	-40 to 125	TPSM41625 MOV	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPSM41625MOVR	QFM	MOV	69	500	330.2	32.4	11.4	16.4	4.69	16.0	32.0	Q1

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPSM41625MOVR	QFM	MOV	69	500	381.0	381.0	101.6



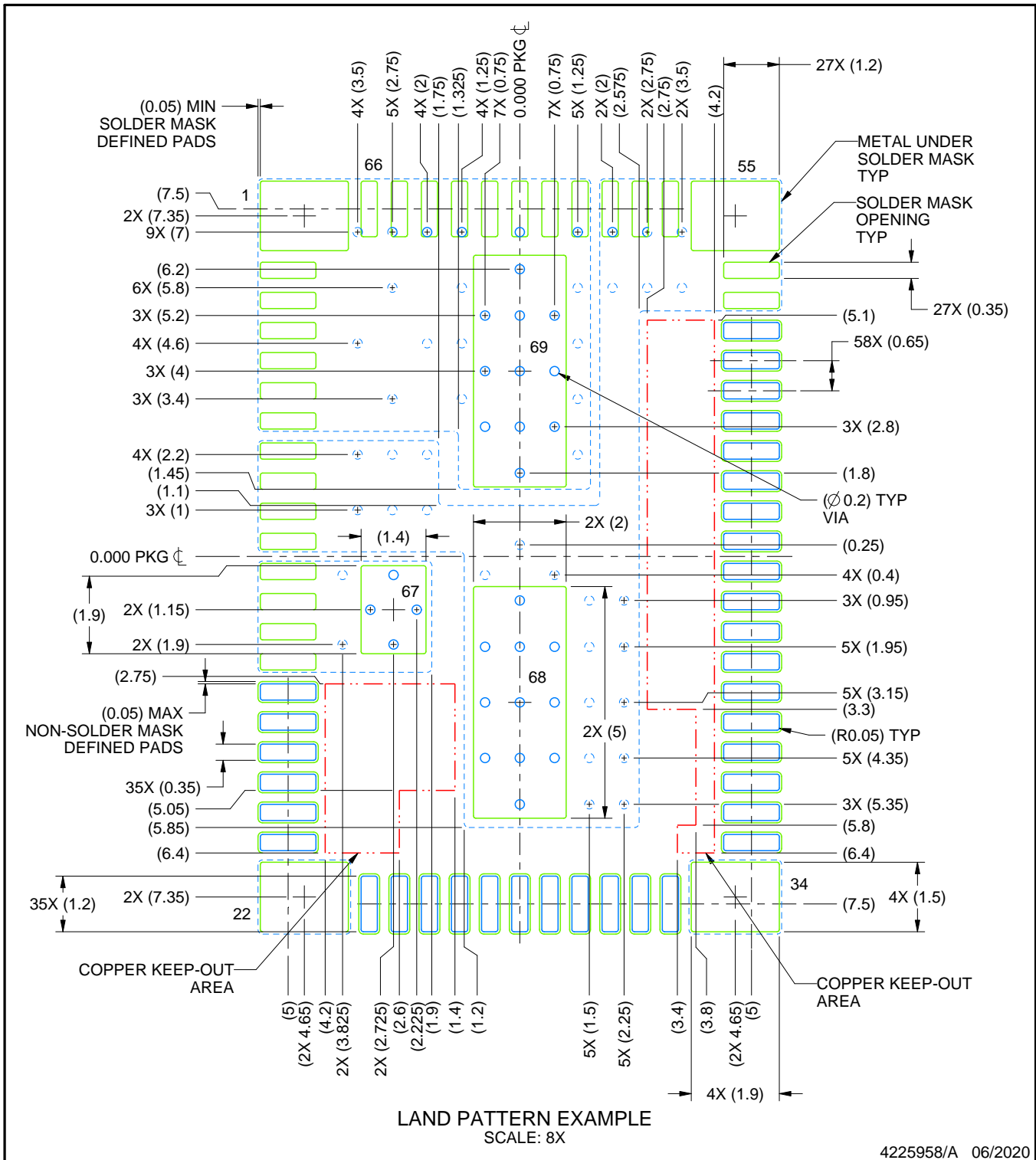


# EXAMPLE BOARD LAYOUT

MOV0069A

QFM - 4.4 mm max height

QUAD FLAT MODULE



NOTES: (continued)

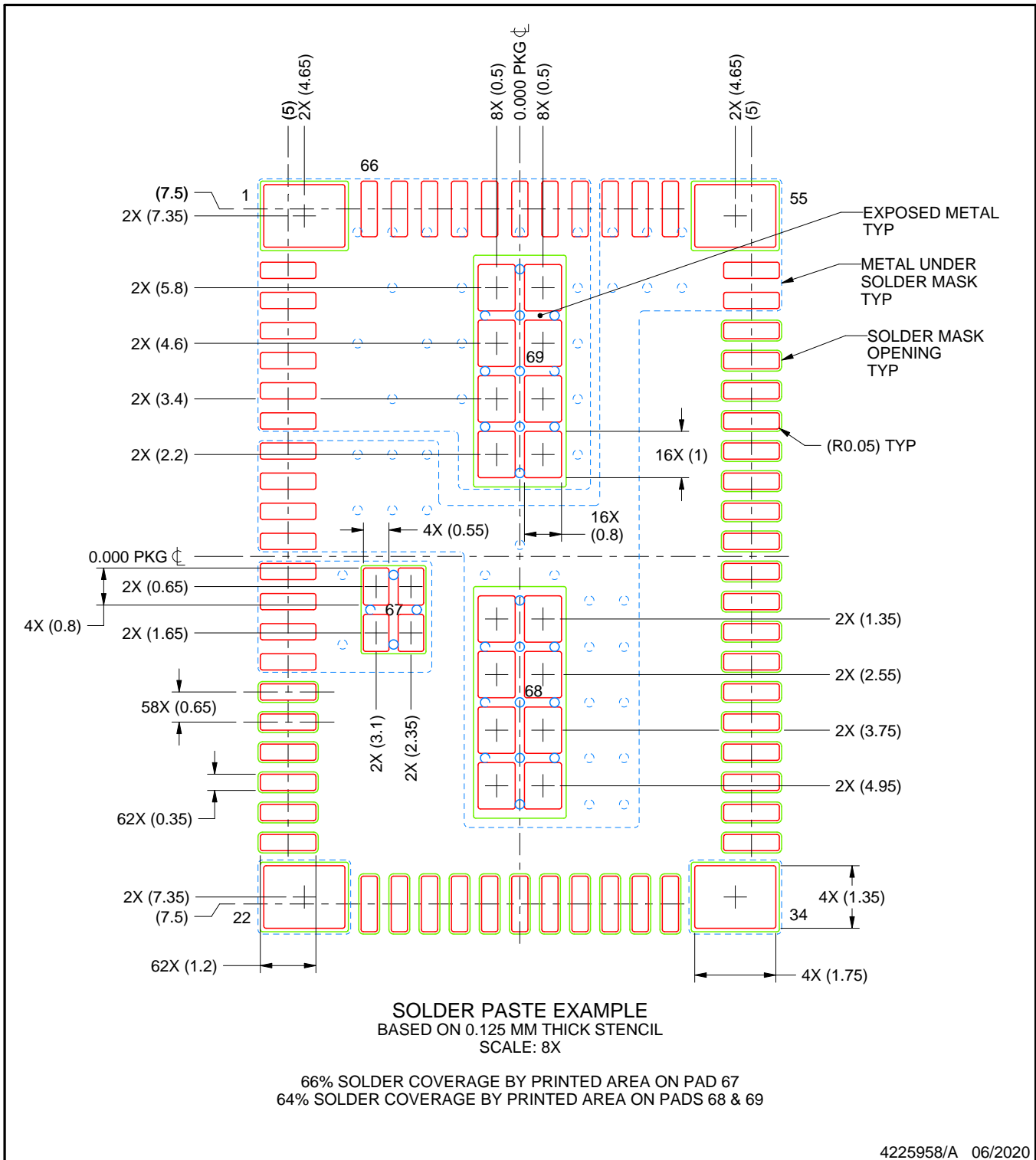
4. This package is designed to be soldered to the thermal pads on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

MOV0069A

QFM - 4.4 mm max height

QUAD FLAT MODULE



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

## 重要声明和免责声明

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