







**BQ77915** 

JAJSEZ9L - MARCH 2018 - REVISED AUGUST 2023

# BQ77915 自律的セル平衡化およびハイバネーション・モード搭載、3~5 直 列、スタック可能、超低消費電力1次側プロテクタ

# 1 特長

**TEXAS** 

INSTRUMENTS

- 超低静止電流:8µA (標準値、通常モード)、2µA (ハイ バネーション・モード)
- 電圧、電流、温度保護機能を完備
- スマートなパッシブ・セル平衡化によりセル間の不均衡 を解消
- セル数を3直列から20直列以上に拡張可能
- 電圧保護 (OV の精度 ±10mV、UV の精度 ±18mV)
  - 過電圧:3V~4.575V
  - 低電圧:1.2V~3V
- オープン・セルおよびオープン・ワイヤの検出 (OW)
- 電流保護
  - 過電流放電 1:-10mV~-85mV
  - 過電流放電 2:-20mV~-170mV
  - 短絡放電:-40mV~-340mV
- 温度保護機能
  - 過熱充電:45℃または 50℃
  - 過熱放電:65℃または 70℃
- 追加機能:
  - 独立した充電 (CHG) および放電 (DSG) FET ドラ イバ
  - 内蔵 FET によるスマートなセル平衡化アルゴリズ ム(最大 50mA の平衡化電流)。セル平衡化電流 を増やすための外部 FET もサポート
  - 超低消費電力のハイバネーション・モード
  - セル入力あたり 36V の高い絶対最大定格
  - 過電流 (OCD1/2) 遅延を抵抗によりプログラム可 能
- シャットダウン・モード:0.5µA 未満
- 機能安全対応
  - 機能安全システムの設計に役立つ資料を利用可 能

# 2 アプリケーション

- 電動工具、園芸用器具
- ロボット掃除機、掃除機、ホバーボード
- 電動アシスト自転車
- 10.8V~72V のパック

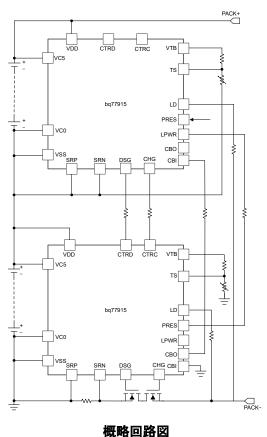
# 3 概要

BQ77915 デバイスは、一連の電圧、電流、温度保護機能 と、マイクロコントローラ (MCU) 制御を必要としないスマー トなセル平衡化アルゴリズムを実装した低消費電力バッテ リ・パック・プロテクタです。スタック可能なインターフェイス によって、単純なスケーリングにより3 直列から 20 直列ま で、さらにそれ以上のバッテリ・セルを持つアプリケーショ ンに対応できます。保護のスレッショルドおよび遅延は工 場出荷時に設定され、各種の構成で利用できます。過熱 と低温のスレッショルドは、放電 (OTD および UTD) と充 電 (OTC および UTC) についてそれぞれ別々に設定さ れるため、柔軟に使用できます。

#### 製品情報

部品番号 <sup>(1)</sup>	パッケージ	本体サイズ (公称)
BQ77915	TSSOP-24	7.70mm × 4.40mm

利用可能なすべてのパッケージについては、データシートの末尾 (1)にある注文情報を参照してください。



英語版のTI製品についての情報を翻訳したこの資料は、製品の概要を確認する目的で便宜的に提供しているものです。該当する正式な英語版の最新情報は、 🐼 www.ti.com で閲覧でき、その内容が常に優先されます。 TI では翻訳の正確性および妥当性につきましては一切保証いたしません。 実際の設計などの前には、必ず 最新版の英語版をご参照くださいますようお願いいたします。





# **Table of Contents**

1	特長1
	アプリケーション1
3	概要1
	Revision History2
	概要 (続き)3
6	Device Comparison Table
	Pin Configuration and Functions4
8	Specifications
	8.1 Absolute Maximum Ratings5
	8.2 ESD Ratings5
	8.3 Recommended Operating Conditions5
	8.4 Thermal Information7
	8.5 Electrical Characteristics7
	8.6 Typical Characteristics12
9	Detailed Description12
	9.1 Overview12
	9.2 Functional Block Diagram14
	9.3 Feature Description14

9.4 Device Functional Modes	31
10 Application and Implementation	33
10.1 Application Information	
10.2 Typical Application	
11 Power Supply Recommendations	
12 Layout	
12.1 Layout Guidelines	
12.2 Layout Example	
13 Device and Documentation Support	
13.1 サード・パーティ製品に関する免責事項	
13.2 Documentation Support	
13.3ドキュメントの更新通知を受け取る方法	
13.4 サポート・リソース	47
13.5 Trademarks	
13.6 静電気放電に関する注意事項	
13.7 用語集	
14 Mechanical, Packaging, and Orderable	
Information	

# **4 Revision History**

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision K (July 2023) to Revision L (August 2023)	Page
<ul> <li>最新のテキサス・インスツルメンツ標準に合わせてデータシートを更新</li> </ul>	1
Changes from Revision J (March 2022) to Revision K (July 2023)	Page
Added the BQ7791514 device to the <i>Device Comparison Table</i>	3
Changes from Revision I (Sentember 2020) to Revision I (March 2022)	Page

0		aye
•	このドキュメントは、最新のテキサス・インスツルメンツおよび業界データシート標準に準拠して更新されました。	1

# 5 概要 (続き)

BQ77915 デバイスは、内蔵の独立した CHG および DSG ローサイド NMOS FET ドライバを使用してパック保護を行い ます。これらは 2 つの制御ピンによってディセーブルできます。また、これらの制御ピンにより、経済的な方法で、上位に 直列接続されたセルの保護 (6 つの直列接続とその先)も可能になります。これを行うには、上位のデバイスの CHG およ び DSG 出力を、すぐ下位のデバイスの制御ピンへカスケード接続します。柔軟性を高めるため、OCDP ピンと VSS の 間に抵抗を接続して、放電過電流保護遅延をプログラムします。

BQ77915 プロテクタは、最大 50mA のセル平衡化電流に対応する内蔵 FET を使用してスマートなパッシブ・セル平衡 化アルゴリズムを実現しています。より大きなセル平衡化電流が必要な場合は、外部 FET を接続します。 ハイバネーショ ン・モードはバッテリ・パックの配送や保管を意図したもので、非常に低い消費電力での動作が可能になります。

BQ77915 プロテクタは、ホストによる監視を必要としないバッテリ・パック向けです。

# 6 Device Comparison Table

Unless otherwise specified, the device has, by default, a state comparator enabled with a 1.875-mV threshold. A filtered fault detection is used by default.

	ov		UV			ow	OW OCD1		OCD2		SCD		000		
Part Number	Thre- shold (mV)	Delay (s)	Hyst (mV)	Thre- shold (mV)	Delay (s)	Hyst (mV)	Load Remo- val Reco- very (Y/N)	Current (nA)	Thre- shold (mV)	Delay (ms)	Threshold (mV)	Delay (ms)	Threshold (mV)	Delay (ms)	Threshold (mV)
BQ7791500	4200	1	200	2900	1	400	Y	100	60	180	60	180	120	0.96	60
BQ7791501	4250	1	200	2800	1	400	Y	100	35	180	60	180	120	0.96	20
BQ7791502	4200	1	200	2900	1	400	Y	100	70	180	70	180	120	0.96	70
BQ7791504	4275	1	100	2000	1	200	N				Di	sabled			
BQ7791506	3800	1	200	2500	1	400	Y	100	50	700	100	350	300	0.4	60
BQ7791508	4200	4.5	100	3000	4.5	200	Y	100	70	1420	140	700	300	0.4	60
BQ7791513	4300	4.5	100	1800	9	200	N	Disabled							
BQ7791514	3650	1	100	2500	1	200	Y	100	50	700	100	350	200	0.4	50

表 6-1. Device Comparison Table

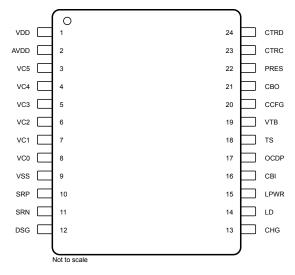
# 表 6-2. Device Comparison Table (continued)

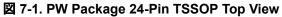
		Current Fault Recovery		Temperatu	re (°C) <sup>(1)</sup>		Cell Balancing			
Part Number	Delay (ms)	Method	отр	отс	UTD	UTC	V <sub>START</sub> (V)	V <sub>HYST</sub> (V <sub>OV</sub> – V <sub>FC</sub> ) (mV)	V <sub>STEP</sub> (V <sub>CBTH</sub> – V <sub>CBTL</sub> ) (mV)	
BQ7791500	N/A	Load removal only (OCD1, OCD2, SCD)/load detection only (OCC)	65	45	-10	0	3.8	100	100	
BQ7791501	N/A	Load removal only (OCD1, OCD2, SCD)/load detection only (OCC)	70	50	-20	0	3.8	100	100	
BQ7791502	N/A	Load removal only (OCD1, OCD2, SCD)/load detection only (OCC)	65	45	-10	0	3.8	100	100	
BQ7791504	Disabled	N/A		Disabled			3.5	50	50	
BQ7791506	N/A	Load removal only (OCD1, OCD2, SCD)/load detection only (OCC)	65	50	-10	0	3.5	100	50	
BQ7791508	500	Load removal only (OCD1, OCD2, SCD)/load detection only (OCC)	65	50	-20	-5	3.8	100	50	
BQ7791513	Disabled	N/A		Disab	led		3.8	150	50	
BQ7791514	N/A	Load removal only (OCD1, OCD2, SCD)/load		50	-10	0	3.5	100	50	

(1) These thresholds are targets, based on temperature, but they are dependent on external components that could vary based on customer selection. The circuit is based on a 103AT NTC thermistor connected to TS and VSS, and a 10-kΩ resistor connected to VTB and TS. Actual thresholds are determined in mV; refers to the overtemperature and undertemperature mV threshold in the *Electrical Characteristics* table.



# 7 Pin Configuration and Functions





NUMBER	NAME	I/O	DESCRIPTION
1	VDD	P <sup>(1)</sup>	Supply voltage
2	AVDD	0	Analog supply (only connect to a capacitor)
3	VC5	I	
4	VC4	I	
5	VC3	I	Cell voltage sense inputs
6	VC2	I	
7	VC1	I	
8	VC0	I	
9	VSS	Р	Analog ground
10	SRP	I	Current sense input connecting to the battery side of the sense resistor
11	SRN	I	Current sense input connecting to the pack side of the sense resistor
12	DSG	0	DSG FET driver output
13	CHG	0	CHG FET driver output
14	LD	I	PACK- load removal detection
15	LPWR	0	HIBERNATE mode communication pin. Connect to the PRES pin of the lower device in a stack configuration. For a single device, leave the LPWR pin floating.
16	СВІ	I	Cell balancing input. Leave the CBI pin floating to disable cell balancing, and do not drive with an external supply. Drive the pin low to enable cell balancing. In a stacked configuration, connect the CBI pin of an upper device to the CBO pin of the immediate lower device.
17	OCDP	I	Connecting a resistor from this pin to VSS programs the OCD1/2 fault detection delay. Connect to a 10-M $\Omega$ resistor to VSS for the upper devices in a stack.
18	TS	I	Thermistor measurement input. Connect a 10-k $\Omega$ resistor to the VSS pin if the function is not used.
19	VTB	0	Thermistor bias output
20	CCFG	I	Cell in-series configuration input
21	СВО	0	Cell balancing output. Connect through a 10-k resistor to the CBI pin of the upper device in a stacked configuration. For a single device, leave the CBO pin floating.
22	PRES	I	HIBERNATE mode input. Drive high for NORMAL mode operation. Leave the PRES pin floating for HIBERNATE mode. Connect to the LPWR pin of the upper device in a stack configuration.



#### 表 7-1. Pin Functions (continued)

NUMBER	NAME	I/O	DESCRIPTION			
23	CTRC	I	CHC and DSC override inpute			
24	CTRD	I	CHG and DSG override inputs			

(1) I = Input, O = Output, P = Power

# 8 Specifications

# 8.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted). All values are referenced to VSS unless otherwise noted.<sup>(1)</sup>

			MIN	MAX	UNIT
		VDD, VC5, VC4, VC3, VC2, VC1, CTRD, CTRC	-0.3	36	V
	Input voltage	LD	-30	20	V
VI	input voltage	PRES	-0.3	36	V
		VC0, SRN, SRP, TS, AVDD, CCFG, CBI	-0.3	3.6	V
Vo		DSG	-0.3	20	V
	Output voltage	CHG	-30	20	V
	Oulput voltage	СВО	-0.3	36	V
		LPWR	-30	3.6	V
Vo	Output voltage	VTB, OCDP	-0.3	3.6	V
L	Input current	LD, CHG		500	μA
II	input current	DSG		1	mA
lo	Output current	CHG, DSG		1	mA
lo	Output current	Cell Balancing current (VC5, VC4, VC3, VC2, VC1, VC0)		50	mA
Lead te	mperature (soldering, 10 s), T <sub>SOI</sub>		300	°C	
Storage	e temperature, T <sub>stg</sub>		-65	150	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

# 8.2 ESD Ratings

				VALUE	UNIT	
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>		V		
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±250	v		

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 8.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

			MIN	NOM MAX	UNIT
V <sub>BAT</sub>	Supply voltage	VDD	3	25	V



# 8.3 Recommended Operating Conditions (continued)

Over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
		VC5-VC4, VC4-VC3, VC3- VC2, VC2-VC1, VC1-VC0	0		5	
		CTRD, CTRC	0		(VDD + 5)	
		CCFG, CBI	0		AVDD	
/ <sub>1</sub>	Input voltage range	PRES	0		16	V
		SRN, SRP	-0.2		0.8	
		LD	0		16	
		TS	0		VTB	
		CHG, DSG	0		16	
/ <sub>0</sub>	Output voltage range	VTB, AVDD, LPWR	0		3	V
		СВО	0		VDD	
Γ <sub>OPR</sub>	Operating free-range temperature		-40		85	°C
R <sub>INE</sub>	Cell monitor filter resistance (External Cell balancing)	± 5% tolerance		1		kΩ
C <sub>INE</sub>	Cell monitor filter capacitance (External Cell balancing)	± 10% tolerance		0.1		μF
R <sub>INI</sub>	Cell monitor filter resistance (Internal Cell balancing. 50-mA balancing current at 4.2-V cell voltage)	± 5% tolerance		33		Ω
C <sub>INI</sub>	Cell monitor filter capacitance (Internal Cell balancing)	± 10% tolerance		1		μF
R <sub>VDD</sub>	Supply voltage filter resistance	± 5% tolerance		1		kΩ
C <sub>VDD</sub>	Supply voltage filter capacitance	± 20% tolerance		1		μF
R <sub>TS</sub>	Thermistor	103AT, ± 3% tolerance		10		kΩ
R <sub>TS_PU</sub>	Thermistor pullup resistor to VTB	± 1% tolerance		10		kΩ
R <sub>GS_CHG</sub>	CHG FET gate-source resistor	± 5% tolerance		1		MΩ
R <sub>GS_DSG</sub>	DSG FET gate-source resistor	± 5% tolerance		1		MΩ
R <sub>DSG</sub>	DSG gate resistor, System designers should adjust this parameter to meet the desirable FET rise/fall time.	± 5% tolerance		4.5		kΩ
		± 5% tolerance. System designers should adjust this parameter to meet the desirable FET rise/fall time.		1		kΩ
R <sub>CHG</sub>	CHG gate resistor	$\pm$ 5% tolerance. If additional components are used to protect the CHG FET and/or to enable load removal detection for UV recovery.		1		MΩ
R <sub>CTRC</sub>	CTRC current limit resistor	± 5% tolerance		10		MΩ
RCTRD	CTRD current limit resistor	± 5% tolerance		10		MΩ
RLD	LD resistor for load removal detection	± 5% tolerance		470		kΩ
R <sub>CB</sub>	Resistor between CBO of lower device and CBI of upper device	± 5% tolerance		10		kΩ
R <sub>HIB</sub>	Resistor between LPWR of upper device and PRES of upper device	± 5% tolerance		10		kΩ



# 8.3 Recommended Operating Conditions (continued)

Over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
R <sub>SNS</sub>	Current sense resistor for current protection. System designers should change this parameter according to the application current protection requirement.	± 1% tolerance		1		mΩ

# 8.4 Thermal Information

Over operating free-air temperature range (unless otherwise noted)

	THERMAL METRIC	BQ77915 PW (TSSOP) 24 PINS	UNIT <sup>(1)</sup>
R <sub>OJA</sub>	Junction-to-ambient thermal resistance	88.9	°C/W
R <sub>OJC(top)</sub>	Junction-to-case thermal resistance	26.5	°C/W
R <sub>ØJB</sub>	Junction-to-board thermal resistance	43.5	°C/W
ΨJT	Junction-to-top characterization parameter	1.1	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	43	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics Application Report, SPRA953 SPRA953.

# **8.5 Electrical Characteristics**

Typical values stated at  $T_A = 25^{\circ}$ C and VDD = 20 V. MIN and MAX values stated with  $T_A = -40^{\circ}$ C to  $85^{\circ}$ C and VDD = 3 to 25 V unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY VOL	TAGE	11			I	
V <sub>POR</sub>	POR threshold	VDD rising, 0 to 6 V			4	V
V <sub>SHUT</sub>	Shutdown threshold	VDD falling, 6 to 0 V	2		3.25	V
V <sub>AVDD</sub>	AVDD voltage	C <sub>VDD</sub> = 1 µF	2.1		3.6	V
SUPPLY AND	LEAKAGE CURRENT				I	
I <sub>cc</sub>	NORMAL mode current	Cell1 through Cell5 = 4 V, VDD = 20 V, No cell balancing		8	15	μA
		Cell balancing cells 3, 4 or 5		48	80	μA
I <sub>HIB</sub>	HIBERNATE mode current	Cell1 through Cell5 = 4 V, VDD = 20 V, HIBERNATE mode		2	3	μA
I <sub>CFAULT</sub>	Fault condition current	State comparator on		10	15	μA
I <sub>OFF</sub>	SHUTDOWN mode current	VDD < V <sub>SHUT</sub> , CTRC/CTRD floating			0.5	μA
I <sub>LKG_OW_DIS</sub>	Input leakage current at VCx pins	All cell voltages = 4 V, open-wire disable configuration	-100	0	100	nA
I <sub>LKG_100nA</sub>	Open-wire sink current at VCx pins	All cell voltages = 4 V, 100-nA configuration	30	110	175	nA
I <sub>LKG_200nA</sub>	Open-wire sink current at VCx pins	All cell voltages = 4 V, 200-nA configuration	95	210	315	nA
I <sub>LKG_400nA</sub>	Open-wire sink current at VCx pins	All cell voltages = 4 V, 400-nA configuration	220	425	640	nA
PROTECTION	ACCURACIES					
V <sub>OV</sub>	Overvoltage programmable threshold range		3000		4575	mV
V <sub>UV</sub>	Undervoltage programmable threshold range		1200		3000	mV



Typical values stated at  $T_A = 25^{\circ}$ C and VDD = 20 V. MIN and MAX values stated with  $T_A = -40^{\circ}$ C to 85°C and VDD = 3 to 25 V unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		T <sub>A</sub> = 25°C, OV detection accuracy	-10		10	mV
. ,		T <sub>A</sub> = 25°C, UV detection accuracy	-18		18	mV
V <sub>VA</sub>	OV, UV, detection accuracy	$T_A = 0 \text{ to } 60^{\circ}\text{C}$	-28	· · · ·	26	mV
		$T_{A} = -40 \text{ to } +85^{\circ}\text{C}$	-40		40	mV
V <sub>HYS_OV</sub>	OV hysteresis programmable threshold range		0		400	mV
V <sub>HYS_UV</sub>	UV hysteresis programmable threshold range		0		800	mV
,	Overtemperature in discharge	Threshold for 65°C based on a 10k pullup and 103AT thermistor	19.69%	20.56%	21.86%	VTB
V <sub>OTD</sub>	programmable threshold	Threshold for 70°C based on a 10k pullup and 103AT thermistor	17.28%	18.22%	19.51%	VTB
Voto DEO	Overtemperature in discharge	Recovery threshold at 55°C for when V <sub>OTD</sub> is at 65°C based on a 10k pullup and 103AT thermistor	25.18%	26.12%	27.44%	VTB
V <sub>OTD_REC</sub>	recovery	Recovery threshold at 60°C for when V <sub>OTD</sub> is at 70°C based on a 10k pullup and 103AT thermistor	22.05%	23.2%	24.24%	VTB
	Overtemperature in charge	Threshold for 45°C based on a 10k pullup and 103AT thermistor	32.14%	32.94%	34.54%	VTB
V <sub>OTC</sub>	programmable threshold	Threshold for 50°C based on a 10k pullup and 103AT thermistor	29.15%	29.38%	31.45%	VTB
V <sub>OTC_REC</sub>	Overtemperature in charge recovery	Recovery threshold at 35°C for when V <sub>OTD</sub> is at 45°C based on a 10k pullup and 103AT thermistor	38.63%	40.97%	40.99%	VTB
		Recovery threshold at 40°C for when V <sub>OTD</sub> is at 50°C based on a 10k pullup and 103AT thermistor	36.18%	36.82%	38.47%	VTB
	Undertemperature in discharge	Threshold for –20°C based on a 10k pullup and 103AT thermistor	86.41%	87.14%	89.72%	VTB
V <sub>UTD</sub>	programmable threshold	Threshold for –10°C based on a 10k pullup and 103AT thermistor	80.04%	80.94%	83.10%	VTB
	Undertemperature in discharge	Recovery threshold at –10°C for when V <sub>UTD</sub> is at –20°C based on a 10k pullup and 103AT thermistor	80.04%	80.94%	83.10%	VTB
V <sub>UTD_REC</sub>	recovery	Recovery threshold at 0°C for when $V_{UTD}$ is at -10°C based on a 10k pullup and 103AT thermistor	71.70%	73.18%	74.86%	VTB
luzo	Undertemperature in charge	Threshold for –5°C based on a 10k pullup and 103AT thermistor	75.06%	77.22%	78.32%	VTB
Vutc	programmable threshold	Threshold for 0°C based on a 10k pullup and 103AT thermistor	71.70%	73.18%	74.86%	VTB
UTC_REC	Undertemperature in Charge	Recovery threshold at 5°C for when $V_{UTC}$ is at -5°C based on a 10k pullup and 103AT thermistor	68.80%	69.73%	71.71%	VTB
	Recovery	Recovery threshold at 10°C for when $V_{UTC}$ is at 0°C based on a 10k pullup and 103AT thermistor	64.67%	65.52%	67.46%	VTB
V <sub>occ</sub>	Overcurrent charge programmable threshold range, (V <sub>SRP</sub> -V <sub>SRN</sub> )		5		80	mV
V <sub>OCD1</sub>	Overcurrent discharge 1 programmable threshold range		-85		-10	mV



Typical values stated at  $T_A = 25^{\circ}$ C and VDD = 20 V. MIN and MAX values stated with  $T_A = -40^{\circ}$ C to  $85^{\circ}$ C and VDD = 3 to 25 V unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OCD2</sub>	Overcurrent discharge 2 programmable threshold range		-170		-20	mV
V <sub>SCD</sub>	Short circuit discharge programmable threshold range		-340		-40	mV
V <sub>CCAL</sub>	OCD1 detection accuracy at lower thresholds	VOCD1 ≤ 20 mV	-30 %		30 %	
V <sub>CCAH</sub>	OCC, OCD1, OCD2, SCD detection accuracy	VOCD1 > 20 mV; all OCC, OCD2 and SCD threshold ranges	-20 %		20 %	
V <sub>ow</sub>	Open-wire fault voltage threshold at VCx per cell with respect to $VC_{x-1}$	Voltage falling on VCx, 3.6 V to 0 V	450	500	550	mV
V <sub>OW_HYS</sub>	Hysteresis for open wire fault	Voltage rising on VCx, 0 V to 3.6 V		100		mV
PROTECTION	DELAYS					
		0.5-s delay option	0.4	0.5	0.8	
		1-s delay option	0.8	1	1.4	
t <sub>OVn_DELAY</sub>	Overvoltage detection delay time	2-s delay option	1.8	2	2.7	S
		4.5-s delay option	4	4.5	5.2	
		1-s delay option	0.8	1	1.5	
		2-s delay option	1.8	2	2.7	
t <sub>UVn_DELAY</sub>	Undervoltage detection delay time	4.5-s delay option	4	4.5	5.5	S
		9-s delay option	8	9	10.2	
OWn DELAY	Open-wire detection delay time		3.6	4.5	5.3	s
	Overtemperature charge detection delay time		3.6	4.5	5.3	s
t <sub>UTC_DELAY</sub>	Undertemperature charge detection delay time		3.6	4.5	5.3	s
t <sub>OTD_DELAY</sub>	Overtemperature discharge detection delay time		3.6	4.5	5.3	s
	Undertemperature discharge detection delay time		3.6	4.5	5.3	s
		10-ms delay option	8	10	15	
		20-ms delay option	17	20	26	
		45-ms delay option	36	45	52	
	Overcurrent discharge 1 detection	90-ms delay option	78	90	105	
CCD1_DELAY	delay time	180-ms delay option	155	180	205	ms
		350-ms delay option	320	350	405	
		700-ms delay option	640	700	825	
		1420-ms delay option	1290	1420	1620	
		5-ms delay option	4	5	8	
		10-ms delay option	8	10	15	
		20-ms delay option	17	20	26	
	Overcurrent discharge 2 detection	45-ms delay option	36	45	52	
OCD2_DELAY	delay time	90-ms delay option	78	90	105	ms
		180-ms delay option	155	180	205	
		350-ms delay option	320	350	405	
			020	000	400	



Typical values stated at  $T_A = 25^{\circ}$ C and VDD = 20 V. MIN and MAX values stated with  $T_A = -40^{\circ}$ C to 85°C and VDD = 3 to 25 V unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>SCD_DELAY</sub>	Short-circuit detection delay time	960-µs delay option	528	960	1450	us
t <sub>SCD_DELAY</sub>	Short-circuit detection delay time	400-µs delay option	220	400	610	μs
t <sub>OCC_DELAY</sub>	Overcurrent charge detection delay time		8	10	12	ms
	Overcurrent discharge 1,	250-ms option	225	250	275	
t <sub>CD_REC</sub>	Overcurrent discharge 2, Overcurrent charge and short- circuit recovery delay time	500-ms option	450	500	550	ms
CHARGE AND	DISCHARGE FET DRIVERS				1	
\/		VDD ≥ 12 V, CL = 10 nF	11	12	14	V
V <sub>FETON</sub>	CHG/DSG on	VDD < 12 V, CL = 10 nF	VDD – 1.5		VDD	V
V <sub>FETOFF</sub>	CHG/DSG off	1-mA resistive load, CHG clamped to ground when CHG/DSG is off.			0.5	V
t <sub>CHGON</sub>	CHG on rise time	CL = 10 nF, 10% to 90%		50	150	μs
t <sub>DSGON</sub>	DSG on rise time	CL = 10 nF, 10% to 90%		2	75	μs
t <sub>CHGOFF</sub>	CHG off fall time	CL = 10 nF, 90% to 10%		15	30	μs
t <sub>DSGOFF</sub>	DSG off fall time	CL = 10 nF, 90% to 10%		5	15	μs
R <sub>CHGOFF</sub>	CHG off resistance	CHG off and pin held at 2V	0.3	0.5	0.75	kΩ
R <sub>DSGOFF</sub>	DSG off resistance	DSG off and pin held at 100 mV		10	16	Ω
CELL BALANC	ING	1			I	
V <sub>HYST</sub>	Hysteresis between overvoltage and full charge voltage range (VOV – VFC, 4 steps of 50 mV)	T <sub>A</sub> = 25°C	50		200	mV
V <sub>STEP</sub>	Difference between the cell balancing threshold voltages (VCBTH – VCBTL, 4 steps of 50 mV)	T <sub>A</sub> = 25°C	50		200	mV
V <sub>CBIL</sub>	CBI low threshold				0.5	V
t <sub>CBI_DEG</sub>	CBI deglitch period			100		ms
R <sub>BAL</sub>	Cell balancing internal FET resistance	Cell1 through Cell5 = 4 V, VDD = 20 V	8	12	20	Ω
D <sub>BAL</sub>	Cell balancing duty cycle	Only one cell balanced in the stack		90 %		
t <sub>BAL</sub>	Odd and even cell group balancing duration			521		ms
HIBERNATE MO	DDE				1	
V <sub>PRESH</sub>	PRES High Threshold		1.25	1.5	1.75	V
t <sub>PRES_DEG_ENT</sub>	PRES deglitch time (hibernate entry)			4.5		S
t <sub>PRES_DEG_EXT</sub>	PRES deglitch time (hibernate exit)			10		ms
CTRC AND CTR	RD CONTROL				I	
V <sub>CTR1</sub>	Enable FET driver (VSS)	With respect to VSS. Enabled < MAX			0.6	V
V <sub>CTR2</sub>	Enable FET driver (Stacked)	Enabled > MIN	VDD + 2.2			V
V <sub>CTRDIS</sub>	Disable FET driver	Disabled between MIN and MAX	2.04		VDD + 0.7	V
V <sub>CTRMAXV</sub>	CTRC and CTRD clamp voltage	I <sub>CTR</sub> = 600 nA	VDD + 2.8	VDD + 4	VDD + 5	V
t <sub>CTRDEG_ON</sub>	CTRC and CTRD deglitch for ON signal			8		ms

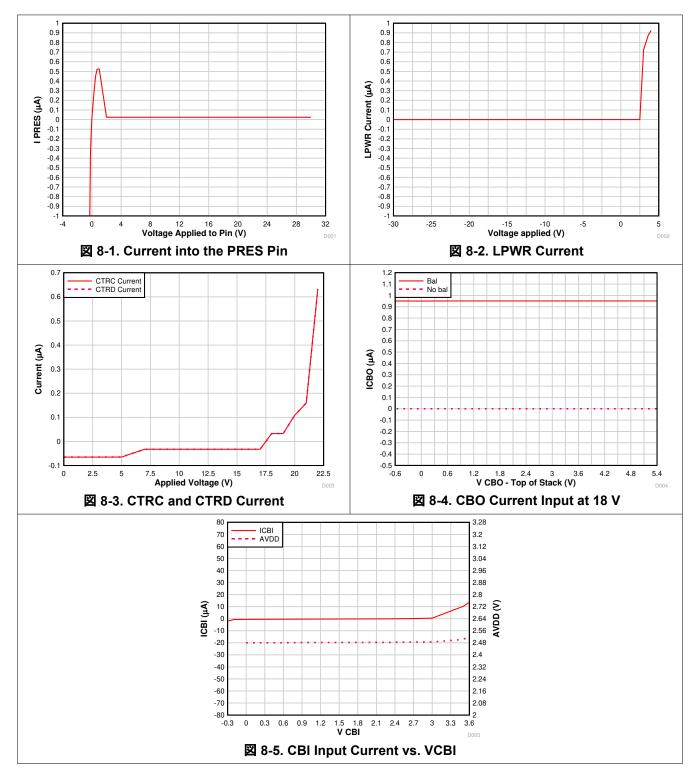


Typical values stated at  $T_A = 25^{\circ}$ C and VDD = 20 V. MIN and MAX values stated with  $T_A = -40^{\circ}$ C to  $85^{\circ}$ C and VDD = 3 to 25 V unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
tCTRDEG_OFF	CTRC and CTRD deglitch for OFF signal			8		ms
CURRENT STA	ATE COMPARATOR	· · ·				
V <sub>STATE_D</sub>	Discharge qualification threshold1	Measured at SRP-SRN		-1.875		mV
V <sub>STATE_D_HYS</sub>	Discharge qualification threshold1 hysteresis	Measured at SRP-SRN		-1.25		mV
V <sub>STATE_C</sub>	Charge qualification threshold1	Measured at SRP-SRN		1.875		mV
V <sub>STATE_C_HYS</sub>	Charge qualification threshold1 hysteresis	Measured at SRP-SRN		1.25		mV
t <sub>STATE</sub>	State detection qualification time				1.2	ms
LOAD DETECT	TION AND LOAD REMOVAL DETECT	TION			I	
V <sub>LDCLAMP</sub>	LD clamp voltage	I <sub>LDCLAMP</sub> = 300 μA	16	19	20	V
ILDCLAMP	LD clamp current	V <sub>LDCLAMP</sub> = 18 V			450	μA
V <sub>LDT</sub>	LD threshold	OPEN pack terminals	1.25	1.3	1.35	V
R <sub>LD_INT</sub>	LD input resistance when enabled	Measured to VSS		200		kΩ
t <sub>LD_DEG</sub>	LD detection de-glitch		1	1.5	2.3	ms
CCFG PIN		· · ·				
V <sub>CCFGL</sub>	CCFG threshold low (ratio of $V_{AVDD}$ )	3-cell configuration			10%	AVDD
V <sub>CCFGH</sub>	CCFG threshold high (ratio of V <sub>AVDD</sub> )	4-cell configuration	65%		100%	AVDD
V <sub>CCFGHZ</sub>	CFG threshold high-Z (ratio of $V_{AVDD}$ )	5-cell configuration, CCFG floating, internally biased	25%	33%	45%	AVDD
t <sub>CCFG_DEG</sub>	CCFG deglitch			6		ms
CUSTOMER TI	EST MODE	· · ·				
V <sub>CTM</sub>	Customer test mode entry voltage at VDD	VDD > VC5 + $V_{CTM}$ , $T_A = 25^{\circ}C$	8.5		10	V
t <sub>CTM_ENTRY</sub>	Delay time to enter and exit customer test mode	VDD > VC5 + $V_{CTM}$ , $T_A = 25^{\circ}C$	50			ms
t <sub>CTM_DELAY</sub>	Delay time of faults while in customer test mode	T <sub>A</sub> = 25°C			200	ms
t <sub>CTM_OC_REC</sub>	Fault recovery time of OCD1, OCD2, and SCD faults while in customer test mode	250-ms and 500-ms options, T <sub>A</sub> = 25°C			100	ms



# **8.6 Typical Characteristics**



# 9.1 Overview

The BQ77915 device is a full-feature stackable primary protector for Li-ion/Li-polymer batteries with a smart cellbalancing algorithm. The device implements a suite of protections that include the following:





- Cell voltage: overvoltage, undervoltage
- · Current: overcurrent charge, overcurrent discharge 1 and 2, short circuit discharge
- Temperature: overtemperature and undertemperature in charge and discharge
- PCB: cell open-wire connection
- FET body diode protection

Protection thresholds and delays are factory-programmed and available in a variety of configurations.

The BQ77915 device supports 3-series to 5-series cell configurations. Up to four devices stack to support  $\geq$ 6-series cell configurations, providing protections up to a 20-series cell configuration. It is possible to support greater than 20-series cell configurations, but with careful consideration of delays.

The device has an ultra-low current HIBERNATE mode for shipping and storage. The device also features a smart cell-balancing algorithm to minimize cell-to-cell imbalance. The BQ77915 has built-in CHG and DSG drivers for low-side N-channel FET protection, which automatically open up the CHG and/or DSG FETs after protection delay time when a fault is detected. A set of CHG/DSG overrides enables disabling the CHG and/or DSG driver externally. Although the host system can use this function to disable the FET control, the main usage of these pins is to channel down the FET control signal from the upper device to the lower device in a cascading configuration in  $\geq$ 6-series battery packs.

#### 9.1.1 Device Functionality Summary

	表 9-1. Device Functionality Summary						
FA	ULT DESCRIPTOR	FAULT DETECTION THRESHOLD and DELAY OPTIONS		FAULT RECOVERY METHOD and S	ETTING OPTIONS		
OV	Overvoltage	3 V to 4.575 V (25-mV step)	0.5, 1, 2, 4.5 s	Hysteresis	0, 100, 200, 400 mV		
UV	Undervoltage	1.2 V to 3 V (100-mV step for < 2.5 V, 50-mV step for ≥ 2.5 V)	1, 2, 4.5, 9 s	Load removal + hysteresis	0, 200, 400, 800 mV		
OW	Open wire (cell to pcb disconnection)	0 (disabled), 100 nA, 200 nA, 400 nA	4.5 s	Restore bad VCx to PCB connection	VCx > V <sub>OW</sub>		
OTD <sup>(1)</sup>	Overtemperature during discharge	65°C or 70°C	4.5 s	Hysteresis or load removal + hysteresis	10°C		
OTC <sup>(1)</sup>	Overtemperature during charge	45°C or 50°C	4.5 s	Hysteresis	10°C		
UTD <sup>(1)</sup>	Undertemperature during discharge	–20°C or –10°C	4.5 s	Hysteresis	10°C		
UTC <sup>(1)</sup>	Undertemperature during charge	–5°C or 0°C	4.5 s	Hysteresis	10°C		
OCC	Overcurrent during charge	5 mV to 80 mV (5-mV step)	10 ms	Timer auto-release and load detection, timer auto-release only, load detection only			
OCD1	Overcurrent1 during discharge	-10 mV to -85 mV (5-mV step)	10, 20, 45, 90, 180, 350, 700, 1420 ms		250 ms or 500 ms		
OCD2	Overcurrent1 during discharge	–20 mV to –170 mV (10-mV step)	5, 10, 20, 45, 90, 180, 350, 700 ms	Timer auto-release and load removal, timer auto-release only, load removal only	250 ms or 500 ms		
SCD	Short circuit discharge	-40 mV to -340 mV (20-mV step)	400, 960 µs				
CTRC	CHG signal override control	Disable through external control or through CHG signal from the upper device in stack configuration	tctrdeg_on	Enable through external control or through the CHG signal from the upper device in stack configuration	t <sub>CTRDEG_OFF</sub>		
CTRD	DSG signal override control	Disable through external control or through DSG signal from the upper device in stack configuration	tctrdeg_on	Enable through external control or through the DSG signal from the upper device in stack configuration	tctrdeg_off		

表 9-1. Device Functionality Summary

(1) These thresholds are target-based on temperature, but they are dependent on external components that could vary based on customer selections. The circuit is based on a 103AT NTC thermistor connected to TS and VSS, and a 10-kΩ resistor connected to VTB and TS. Actual thresholds are determined in mV; refers to the over- and undertemperature mV threshold in the *Electrical Characteristics* table.

表 9-2. Cell Balancing	Threshold Summary
-----------------------	-------------------

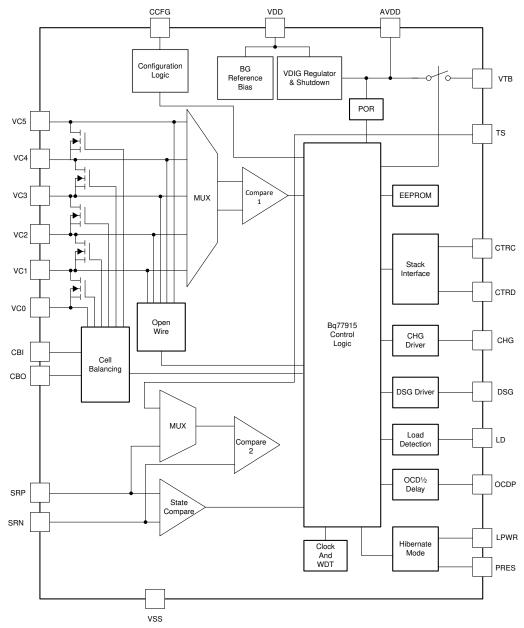
NAME	Description	Options
V <sub>START</sub>	Start threshold for cell balancing	3.5 V, 3.8 V
V <sub>HYST</sub>	Hysteresis between overvoltage and full charge voltage range (VOV – VFC)	50 mV, 100 mV, 150 mV, 200 mV



#### 表 9-2. Cell Balancing Threshold Summary (continued)

NAME	Description	Options
V <sub>STEP</sub>	Difference between the cell balancing threshold voltages (VCBTH – VCBTL)	50 mV, 100 mV, 150 mV, 200 mV

# 9.2 Functional Block Diagram



# 9.3 Feature Description

# 9.3.1 Protection Summary

Two comparators are time-multiplexed to detect all of the protection fault conditions, and to measure cell voltages for balancing. Each of the comparators runs on a time-multiplexed schedule and cycles through the assigned protection fault checks and voltage measurements. Comparator 1 checks for OV, UV, OW, OTC, OTD, UTC, and UTD protection faults and measure individual cell voltages for balancing. Comparator 2 checks for OCD1, OCD2, SCD, and OCC protection faults. For OV, UV, and OW protection faults and cell balancing, every



cell is checked individually in a round-robin fashion, starting with cell 1 and ending with the highest selected cell. The number of the highest cell is configured using the CCFG pin.

Devices can be ordered with various timing and hysteresis settings. See  $\frac{1}{2}$  9-1 for more details.

#### 9.3.2 Fault Operation

#### 9.3.2.1 Operation in OV

An OV fault detection occurs when at least one of the cell voltages is measured above the OV threshold,  $V_{OV}$  for a time of OV delay,  $t_{OVn\_DELAY}$ . The CHG FET is turned off. The OV fault recovers when the voltage of the cell in fault is below the (OV threshold – OV hysteresis,  $V_{HYS\_OV}$ ) for a time of OV delay.

The device assumes an OV fault after reset, and clears automatically after an OV delay if all cell voltages are below the OV threshold minus hysteresis. In the event of an overvoltage fault condition on a particular cell, the balancing FET corresponding to that cell is turned on until the cell voltage drops to the full charge voltage or until the cell has recovered from overvoltage fault condition, whichever occurs earlier. See *Cell Balancing* for more details.

The state comparator is turned on when CHG is turned off. If a discharge current is detected, the device immediately switches the CHG back on. The response time of the state comparator is typically in 700 µs and does not pose any disturbance in the discharge event.

#### 9.3.2.2 Operation in UV

A UV fault detection is when at least one of the cell voltages is measured below the UV threshold,  $V_{UV}$ , for a duration of a UV delay,  $t_{UVn\_DELAY}$ . The DSG FET is turned off. The UV fault recovers when:

- The voltage of the cell in fault goes above the (UV threshold + UV hysteresis, V<sub>HYS\_UV</sub>) for a time of a UV delay OR
- The voltage of the cell in fault goes above the (UV threshold + UV hysteresis, V<sub>HYS\_UV</sub>) for a time of a UV delay and the load is removed.

The state comparator turns on the DSG FET before the cell voltage recovers to protect the body diode.

To minimize device supply current when a UV fault has occurred or CTRD was driven to the DISABLED state, the BQ77915 device disables all discharge overcurrent detection blocks. Upon recovery from the fault or when CTRD is no longer externally driven, all discharge overcurrent detection blocks are reactivated.

#### 9.3.2.3 Operation in OW

An OW fault detection is when at least one of the cell voltages is measured below the OW threshold,  $V_{OW}$ , for a duration of OW delay,  $t_{OWn\_DELAY}$ . CHG and DSG are turned off. The OW fault recovers when the cell voltage in fault is above the OW threshold + OW hysteresis,  $V_{OW}$  HYS, for a time of OW delay.

The  $t_{OWn\_DELAY}$  time starts when the voltage at a given cell is detected below the  $V_{OW}$  threshold and is not from the time that the actual event of an open wire occurs. During an open-wire event, it is common that the device detects an undervoltage and/or overvoltage fault before detecting an open-wire fault. This occurs due to the differences in fault thresholds, fault delays, and the VCx pin filter capacitor values. For CHG and DSG to return to normal operation mode, the OW, OV, and UV faults' recovery conditions must be met.

#### 9.3.2.4 Operation in OCD1

An OCD1 fault is when the discharge load is high enough that the voltage across the  $R_{SNS}$  resistor ( $V_{SRP}-V_{SRN}$ ) is measured below the OCD1 voltage threshold,  $V_{OCD1}$ , for a duration of OCD1 delay,  $t_{OCD1}_{DELAY}$ . CHG and DSG are turned off.

The OCD1 fault recovers when:

- Load removal is detected only, V<sub>LD</sub> < V<sub>LDT</sub>, OR
- Overcurrent Recovery Timer, t<sub>CD\_REC</sub>, expiration only OR
- Overcurrent Recovery Timer expiration and load removal is detected.



# 9.3.2.5 Operation in OCD2

An OCD2 fault is when the discharge load is high enough that the voltage across the  $R_{SNS}$  resistor ( $V_{SRP}-V_{SRN}$ ) is measured below the OCD2 voltage threshold,  $V_{OCD2}$ , for a duration of OCD2 delay,  $t_{OCD2\_DELAY}$ . CHG and DSG are turned off.

The OCD2 fault recovers when:

- Load removal detected only, V<sub>LD</sub> < V<sub>LDT</sub>, OR
- Overcurrent Recovery Timer, t<sub>CD REC</sub>, expiration only OR
- Overcurrent Recovery Timer expiration and load removal is detected.

# 9.3.2.6 Programming the OCD1/2 Delay Using the OCDP Pin

OCD1 and OCD2 detection delays are programmed by the resistor connected from the OCDP pin to VSS. The device checks for the resistor value at power-up. For the bottom device in a stack,  $\gtrsim$  9-3 shows how the resistor values are chosen.

Resistor Value	OCD1 Delay	OCD2 Delay		
750 kΩ±1%	1420 ms	700 ms		
604 kΩ±1%	700 ms	350 ms		
487 kΩ±1%	350 ms	180 ms		
383 kΩ±1%	180 ms	90 ms		
294 kΩ±1%	90 ms	45 ms		
196 kΩ±1%	45 ms	20 ms		
100 kΩ±1%	EEP	EEPROM Delay Options (EC Table)		

# 表 9-3. OCD1/2 Delay Using OCDP Pin

The OCD2 delay is roughly half of the OCD1 delay when any of the first six resistors are connected from the OCDP pin to VSS. However, if a 100-k $\Omega$  resistor is connected, the OCD1 and OCD2 delays are independent of each other and can be chosen to have any value provided in the EC table.

For any device other than the bottom device in a stacked configuration, a  $10-M\Omega$  resistor must be connected from the OCDP pin of that device to the VSS pin of the device.

If the OCDP pin is left open, the OCD1 and OCD2 delays are determined by the EEPROM settings.

# 9.3.2.7 Operation in SCD

An SCD fault is when the discharge load is high enough that the voltage across the  $R_{SNS}$  resistor, ( $V_{SRP}-V_{SRN}$ ), is measured below the SCD voltage threshold,  $V_{SCD}$ , for a duration of SCD delay,  $t_{SCD}$ \_DELAY. CHG and DSG are turned off.

The SCD fault recovers when:

- Load removal detected only, V<sub>LD</sub> < V<sub>LDT</sub>, OR
- Overcurrent Recovery Timer, t<sub>CD REC</sub>, expiration only OR
- Overcurrent Recovery Timer expiration and load removal is detected.

# 9.3.2.8 Operation in OCC

An OCC fault is when the charging current is high enough that the voltage across the R<sub>SNS</sub> resistor, (V<sub>SRP</sub>-V<sub>SRN</sub>), is measured above the OCC voltage threshold, V<sub>OCC</sub>, for a duration of OCC delay, t<sub>OCC\_DELAY</sub>. CHG and DSG are turned off.

The OCC fault recovers when:

- Load detected only, V<sub>LD</sub> > V<sub>LDT</sub>, OR
- Overcurrent Recovery Timer, t<sub>CD REC</sub>, expiration only OR
- Overcurrent Recovery Timer expiration and load is detected.



#### 9.3.2.9 Overcurrent Recovery Timer

The timer expiration method activates an internal recovery timer as soon as the initial fault condition exceeds the OCD1/OCD2/SCD/OCC time. When the recovery timer reaches its limit, both of the CHG and DSG drivers are turned back on. If the combination option of the timer expiration AND load removal/detection is used, then the load removal/detection condition is only evaluated upon expiration of the recovery timer, which can have an expiration period of  $t_{CD REC}$ .

#### 9.3.2.10 Load Detection and Load Removal Detection

The load detection and removal detection features are implemented with the LD pin. When no undervoltage fault and current fault conditions are present, the LD pin is held in an open-drain state. Once any UV, OCD1, OCD2, OCC, or SCD fault occurs and load removal or detection is selected as device of the recovery conditions, a high impedance pulldown path to VSS is enabled on the LD pin. With an external load still present, the LD pin will be externally pulled high: It is internally clamped to V<sub>LDCLAMP</sub> and is resistor-limited through R<sub>LD</sub> externally to avoid conducting excessive current. If the LD pin voltage exceeds V<sub>LDT</sub> for t<sub>LD\_DEG</sub>, it is interpreted as a *load present condition* and is one of the recovery mechanisms selectable for an OCC fault. When the load is eventually removed, the internal high-impedance path to VSS is sufficient to pull the LD pin below V<sub>LDT</sub> for t<sub>LD\_DEG</sub>. This is interpreted as a *load removed condition* and is one of the recovery mechanisms selectable for UV, OCD1, OCD2, and SCD faults.

衣 9-4. Load State				
LD PIN	LOAD STATE			
$\geq V_{LDT}$ for $t_{LD_{DEG}}$	Load present			
$< V_{LDT}$ for $t_{LD_DEG}$	Load removed			

表 9-4. Load State

#### 9.3.2.11 Operation in OTC

An OTC fault is when the temperature increases such that the voltage across an NTC thermistor goes below the OTC voltage threshold,  $V_{OTC}$ , for an OTC delay time,  $t_{OTC\_DELAY}$ . CHG is turned off. The state comparator is turned on when CHG is turned off. If a discharge current is detected, the device immediately switches the CHG back on. The response time of the state comparator is typically in 700 µs and does not pose a disturbance in the discharge event. The OTC fault recovers when the voltage across the thermistor goes above the OTC recovery threshold,  $V_{OTC\_REC}$ , for an OTC delay time.

# 9.3.2.12 Operation in OTD

An OTD fault is when the temperature increases such that the voltage across an NTC thermistor goes below the OTD voltage threshold, V<sub>OTD</sub>, for an OTD delay time, t<sub>OTD</sub> DELAY. CHG and DSG are turned off.

The OTD fault recovers when:

- The voltage across thermistor gets above OTD recovery threshold, V<sub>OTD REC</sub>, for a time of OTD delay OR
- The voltage across thermistor gets above OTD recovery threshold, V<sub>OTD\_REC</sub>, for a time of OTD delay and load is removed.

# 9.3.2.13 Operation in UTC

A UTC fault occurs when the temperature decreases such that the voltage across an NTC thermistor gets above the UTC voltage threshold,  $V_{UTC}$ , for a time of a UTC delay,  $t_{UTC\_DELAY}$ . CHG is turned off. The state comparator is turned on when CHG is turned off. If a discharge current is detected, the device will immediately switch the CHG back on. The response time of the state comparator is typically in 700 µs and not pose a disturbance in the discharge event. The UTC fault recovers when the voltage across thermistor gets below UTC recovery threshold,  $V_{UTC\_REC}$ , for a time of UTC delay.

#### 9.3.2.14 Operation in UTD

A UTD fault occurs when the temperature decreases such that the voltage across an NTC thermistor goes above the UTD voltage threshold,  $V_{UTD}$ , for a UTD delay time,  $t_{UTD}$  DELAY. CHG and DSG are turned off. The



UTD fault recovers when the voltage across thermistor gets below UTD recovery threshold,  $V_{UTD\_REC}$ , for a time of UTD delay.

#### 9.3.3 Protection Response and Recovery Summary

FAULT	FAULT TRIGGER CONDITION	CHG	DSG	RECOVERY METHOD	TRIGGER DELAY	RECOVERY DELAY
CTRC disabled	CTRC disabled for deglitch delay time	OFF	_	CTRC must be enabled for deglitch delay time		
CTRD disabled	CTRD disabled for deglitch delay time	_	OFF	CTRD must be enabled for deglitch delay time	tctrdeg_on tctrdeg_off	
ov	V(Cell) rises above V <sub>OV</sub> for delay time	OFF	_	V(Cell) drops below $V_{OV} - V_{HYS_OV}$ for delay	t <sub>OVn_DE</sub>	LAY
UV	V(Cell) drops below V <sub>UV</sub> for delay time	_	OFF	DSG FET turned on after Load is removed and V(Cell) rises above $V_{UV}$ + $V_{HYS_UV}$ for delay.	t <sub>UVn_DE</sub>	LAY
ow	$VC_X - VC_{X-1} < V_{OW}$ for delay time	OFF	OFF	Bad VC <sub>X</sub> recovers such that VC <sub>X</sub> – VC <sub>X-1</sub> > $V_{OW}$ + $V_{OW_{-HYS}}$ for delay	t <sub>OWn_DE</sub>	LAY
OCC	(VSRP – VSRN) > VOCC for delay time	OFF	OFF	Recovery delay expires, OR LD detects > V <sub>LDT</sub> , OR Recovery delay expires + LD detects > V <sub>LDT</sub>	t <sub>OCC_DELAY</sub>	t <sub>CD_REC</sub>
OCD1, OCD2, SCD	(VSRP – VSRN) < VOCD1, VOCD2, or VSCD for delay time	OFF	OFF	Recovery delay expires, OR LD detects < V <sub>LDT</sub> , OR Recovery delay expires + LD detects < V <sub>LDT</sub>	tocd1_delay, tocd2_delay, tscd_delay	t <sub>CD_REC</sub>
OTC <sup>(1)</sup>	Temperature rises above T <sub>OTC</sub> for delay time	OFF	_	Temp drops below $T_{OTC} - T_{OTC\_REC}$ for delay	totc_de	LAY
OTD <sup>(1)</sup>	Temperature rises above T <sub>OTD</sub> for delay time	OFF	OFF	Temp drops below $T_{OTD} - T_{OTD\_REC}$ for delay, OR Temp drops below $T_{OTD} - T_{OTD\_REC}$ for delay and Load is removed	t <sub>otd_de</sub>	LAY
UTC <sup>(1)</sup>	Temperature drops below $T_{UTC}$ for delay time	OFF	_	Temperature rises above T <sub>UTC</sub> + T <sub>UTC_REC</sub> for delay	t <sub>UTC_DE</sub>	LAY
UTD <sup>(1)</sup>	Temp drops below T <sub>UTD</sub> for delay time	OFF	OFF	Temp rises above T <sub>UTD</sub> + T <sub>UTD_REC</sub> for delay	t <sub>UTD_DE</sub>	LAY

表 9-5. Fault Condition, State, and Recovery Metho	ds
---	----

(1) T<sub>UTC</sub>, T<sub>UTD</sub>, T<sub>UTC\_REC</sub>, and T<sub>UTD\_REC</sub> correspond to the temperature produced by V<sub>UTC</sub>, V<sub>UTD</sub>, V<sub>UTC\_REC</sub>, and V<sub>UTD\_REC</sub> of the selected thermistor resistance.

To prevent FET damage, there are times when the CHG FET or DSG FET may be enabled even though a fault event has occurred. See the *State Comparator* section for details.

# 9.3.4 Cell Balancing

Cell balancing is performed by comparing the cell voltages with respect to cell balancing threshold voltages, evaluating the results of the comparison and controlling the cell balancing FET, which over a period of time will allow for closer cell voltages, thereby extending battery pack life. The conditions for performing cell balancing are: CBI is connected to VSS, no device in the stack is in a fault condition, and the pack is charging. The *State Comparator* section lists the conditions for the device's charging state.

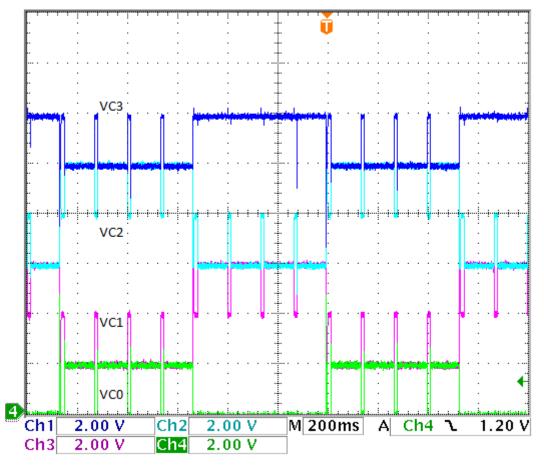
CBI is the cell balancing input pin. It enables cell balancing function for the device.

- Leave the CBI pin floating to disable cell balancing. An internal circuit pulls up the CBI pin to AVDD in this case.
- Connect CBI to VSS to enable cell balancing.

In a single device, cell balancing of all the odd numbered cells can happen at the same time, and balancing of all the even numbered cells can also happen at the same time, but odd and even cells are not balanced at the same time. When devices are stacked on top of each other, verify in the PCB layout that the trace from VC5 pin to a cell and the trace from the VC0 pin of the next upper device to the immediately higher cell are kept separate.



All cell balancing FETs are turned off during voltage measurements. If odd numbered and even numbered cells need balancing at the same time, one single cycle time  $t_{BAL}$  is dedicated for odd numbered cells alone followed by the next  $t_{BAL}$  dedicated for even numbered cells alone. See an example of adjacent cell balancing in  $\boxtimes$  9-1.



🛛 9-1. Balancing Cells 1, 2, and 3

In a stacked configuration, the CBO pin of the bottom device must be connected to the CBI pin of the next upper device through a  $10-k\Omega$  resistor and so forth.

When a cell is in OV, its corresponding balancing FET is turned on if CBI is connected to VSS and if there are no discharge faults anywhere in the stack. The balancing FET is ON until the cell voltage drops to  $V_{FC}$  or  $V_{OV} - V_{HYS OV}$ , whichever occurs earlier.

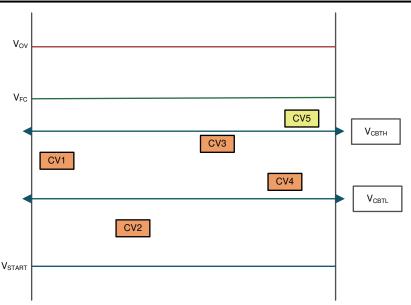
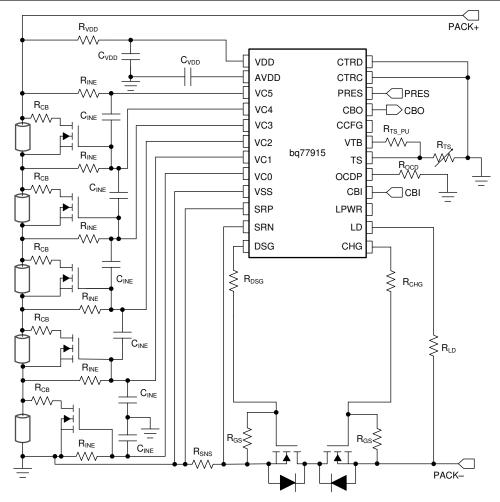


図 9-2. Cell-Balancing Algorithm

 $V_{CBTL}$  is the lower cell balancing threshold and  $V_{CBTH}$  is the upper cell balancing threshold. In  $\boxtimes$  9-2, the balancing FET is turned on only for the cell CV5. The BQ77915  $V_{START}$  is set at 3.8 V; therefore, cell balancing starts only when individual cell voltages exceed 3.8 V. The difference between  $V_{CBTH}$  and  $V_{CBTL}$  can be programmed in the EEPROM to be between 50 mV and 200 mV, in steps of 50 mV. The difference between the  $V_{OV}$  and  $V_{FC}$  can also be programmed in the EEPROM to be between 50 mV and 200 mV, and 200 mV, in steps of 50 mV.

When using the integrated MOSFETs for cell balancing, the cell monitor filter resistance  $R_{INI}$  controls the amount of cell balancing current the device can supply to the cells. Internal cell balancing should be used for cell balancing currents up to 50 mA. External MOSFETs have to be used if higher cell balancing currents are required. In the case of external balancing, the balancing current is controlled by the resistor  $R_{CB}$  in series with the external MOSFET, as shown in  $\boxtimes$  9-3. The pin filter resistance  $R_{INE}$  should be 1 k $\Omega$  and the capacitance  $C_{INE}$  should be 0.1 µF. The gate bias voltage necessary to turn on the FET connected to Cell(n) is generated by the resistor  $R_{INE}$  connected to the VC<sub>(n-1)</sub> pin. The external MOSFET must be selected with a threshold voltage less than 1.7 V.

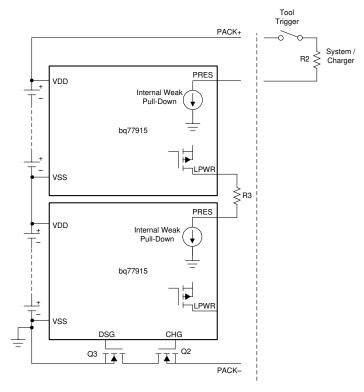




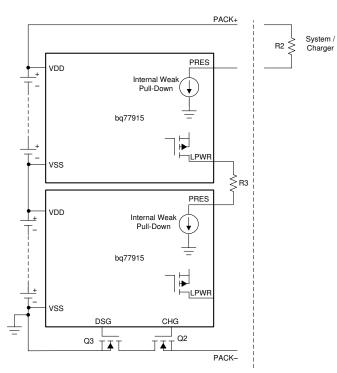
**図** 9-3. Cell Balancing with External MOSFETs



# 9.3.5 HIBERNATE Mode Operation



#### **図** 9-4. HIBERNATE Mode Simplified Schematic 1







The BQ77915 device has two dedicated pins (PRES and LPWR) for HIBERNATE mode operation. Most of the internal circuitry is turned off in HIBERNATE mode to save power. Charge and discharge FETs are turned off and all fault protections are disabled.

The PRES pin has an internal pulldown connected to the pin, which pulls PRES low. When the PRES pin is left floating (the system or charger is not connected to the pack), the load is not connected, and the device is not in any fault condition, the device enters HIBERNATE mode after  $t_{PRES_DEG_ENT}$  time. Once in HIBERNATE mode, the system or the charger should drive this pin high (>V<sub>PRESH</sub>) through the resistor R2 for NORMAL mode operation. When the battery pack (in HIBERNATE mode) is inserted to the tool/system or when a charger is connected to the pack, the system has to provide a pull-up to the PRES pin, which puts the device back to NORMAL mode. The device will exit HIBERNATE mode after a  $t_{PRES_DEG_EXT}$  deglitch time.

In a stacked configuration, connect the LPWR pin of an upper device to the PRES pin of a lower device through the resistor R3.

# 9.3.6 Configuration CRC Check and Comparator Built-In-Self-Test

To improve reliability, the device has a built-in CRC check for all the factory-programmable configurations, such as the thresholds and delay time settings. When the device is set up in the factory, a corresponding CRC value is also programmed to the memory. During normal operation, the device compares the configuration setting against the programmed CRC periodically. A CRC error will reset the digital circuitry and increment the CRC fault counter. The digital reset forces the device to reload the configuration as an attempt to correct the configurations. A correct CRC check reduces the CRC fault counter. Three CRC fault counts will turn off both the CHG and DSG drivers. If FETs are opened due to a CRC error, only a POR can recover the FET state and reset the CRC fault.

In addition to the CRC check, the device also has built-in-self-test (BIST) on the comparators. The BIST runs in a scheduler, and each comparator is checked for a period of time. If a fault is detected for the entire check period, the particular comparator is considered at fault, and the CHG and DSG FETs are turned off. The BIST continues to run by the scheduler even if a BIST fault is detected. If the next BIST result is good, the FET driver resumes normal operation.

The CRC check and BIST check do not affect the normal operation of the device. However, there is not specific indication when a CRC or BIST error is detected besides turning off the CHG and DSG drivers. If there is no voltage, current, or temperature fault condition present, but CHG and DSG drivers remain off, it is possible either CRC or BIST error is detected. Users can POR the device to reset the device.

# 9.3.7 Fault Detection Method

#### 9.3.7.1 Filtered Fault Detection

The device detects a fault once the applicable fault is triggered after accumulating sufficient trigger sample counts. The filtering scheme is based on a simple add/subtract. Starting with the triggered sample count cleared, the counts go up for a sample that is taken across the tested condition (for example, above the fault threshold when looking for a fault) and the counts go down for a sample that is taken before the tested condition (that is, below the fault threshold).  $\boxtimes$  9-6 shows an example of a signal that triggers a fault when accumulating five counts above the fault threshold. Once a fault has been triggered, the trigger sample counts reset.

#### 注

With a filtered detection, when the input signal falls below the fault threshold, the sample count does not reset but only counts down, as shown in  $\boxtimes$  9-6. Therefore, it is normal to observe a longer delay time if a signal is right at the detection threshold. The noise can push the delay count to be counting up and down, resulting in a longer time for the delay counter to reach its final accumulated trigger target.





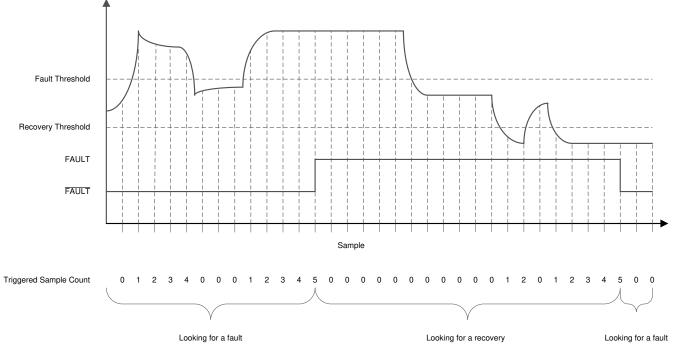


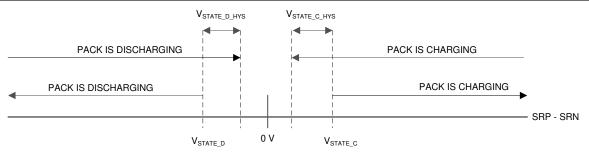
図 9-6. Filtered Fault Detection

#### 9.3.8 State Comparator

A small, low-offset analog state comparator monitors the sense resistor voltage (SRP–SRN) to determine when the pack is in a DISCHARGE state less than a minimum threshold, V<sub>STATE\_D</sub>, or a CHARGE state greater than a maximum threshold, V<sub>STATE\_C</sub>. The state comparator turns on the CHG FET to prevent damage or overheating during discharge in fault states that call for having only the CHG FET off. This is vice versa for the DSG FET during charging in fault that call for having only the DSG FET off. Also, the state comparator is turned on in NORMAL mode (CHG and DSG FETs on) during cell balancing so that cell balancing is performed only when the pack is charging.

MODE	CHG	DSG	STATE COMP		
NORMAL mode, no cell balancing	ON	ON	OFF		
NORMAL mode, cell balancing	ON	ON	V <sub>STATE_C</sub> detection		
UV, CTRD	ON	OFF	V <sub>STATE_C</sub> detection		
OV, UTC, OTC, CTRC	OFF	ON	V <sub>STATE_D</sub> detection		
OCD1, OCD2, SCD, OCC, UTD, OTD, OW	OFF	OFF	OFF		





# 図 9-7. State Comparator Thresholds

Any time a CHG fault is present and a DSG fault is not present, the device enables the state comparator. If the pack is in a fault state where charging is prohibited but discharging is permitted (OV, OTC, UTC, and CTRC), a discharge is possible. When this happens, the CHG FET driver is turned on to avoid damage, as it otherwise carries the discharge current through its body diode. The state comparator (with the  $V_{STATE_D}$  threshold and  $V_{STATE_D}$  Hys hysteresis) remains on for the entire duration of a CHG fault with no DSG fault event.

If there is a DSG fault under CTRD conditions, the DSG FET is turned on if charge is detected. The state comparator (with  $V_{STATE_C}$  threshold and  $V_{STATE_C_HYS}$  hysteresis) remains on for the entire duration of a DSG fault with no CHG fault event.

# 9.3.9 DSG FET Driver Operation

The DSG pin is driven high only when no related faults (UV, OW, OTD, UTD, OCD1, OCD2, SCD, OCC, and CTRD disabled) are present and the device is not in HIBERNATE mode of operation. It is a fast switching driver with a target on resistance of about 15  $\Omega$ -20  $\Omega$  and an off resistance of R<sub>DSGOFF</sub>. It is designed to enable customers to select the optimized R<sub>GS</sub> value to archive the desirable FET rise and fall time per the application requirement and the choice of FET characteristics. When the DSG FET is turned off, the DSG pin drives low and all discharge overcurrent protections (OCD1, OCD2, SCD) are disabled to better conserve power. These resume operation when the DSG FET is turned on. The device provides FET body diode protection through the state comparator if one FET driver is on and the other FET driver is off.

The DSG driver may be turned on to prevent FET damage if the battery pack is charging while a discharge inhibit fault condition is present. This is done by the state comparator. The state comparator (with  $V_{STATE_C}$  threshold and  $V_{STATE_C_HYS}$  hysteresis) remains on for the entire duration of a DSG fault with no CHG fault event.

- If (SRP–SRN) ≤ (V<sub>STATE\_C</sub> V<sub>STATE\_C\_HYS</sub>) and no charge event is detected, the DSG FET output will remain OFF due to the presence of a DSG fault.
- If (SRP–SRN) > V<sub>STATE\_C</sub> and a charge event is detected, the DSG FET output will turn ON for body diode protection.

#### See State Comparator for details.

The presence of any related faults, as shown in  $\boxed{2}$  9-8, results in the DSGFET\_OFF signal.



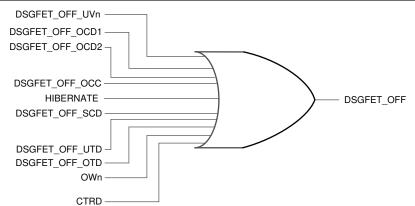


図 9-8. Faults that Can Qualify DSGFET\_OFF

# 9.3.10 CHG FET Driver Operation

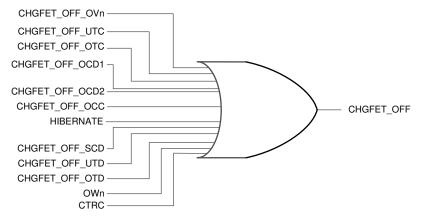
The CHG pin is driven high only when no related faults (OV, OW, OTC, UTC, OTD, UTD, OCD1, OCD2, SCD, OCC, and CTRC disabled) are present and the pack is not in HIBERNATE mode of operation. The CHG pin is used to drive the CHG FET, which is designed to be used on the single device configuration or used by the bottom device in a stack configuration.

Turning off the CHG pin has no influence on the overcurrent protection circuitry. The CHG pin is designed to turn on very quickly; the internal on resistance is about 2 k $\Omega$ . The CHG FET turn off relies on the external resistor connected in parallel to the gate-source nodes of the NCH power FET.

The CHG FET may be turned on to protect the FET's body diode if the pack is charging, even if a charging inhibit fault condition is present. This is done through the state comparator. The state comparator (with  $V_{STATE_D}$  threshold and  $V_{STATE_D_HYS}$  hysteresis) remains on for the entire duration of a DSG fault with no CHG fault event.

- If (SRP–SRN) > (V<sub>STATE\_D</sub> + V<sub>STATE\_D\_HYS</sub>) and no discharge event is detected, the CHG FET output will
  remain OFF due to the presence of a CHG fault.
- If (SRP–SRN) ≤ V<sub>STATE\_D</sub> and a discharge event is detected, the CHG FET output will turn ON for body diode protection.

The CHGFET\_OFF signal is a result of the presence of any related faults as shown in  $\boxtimes$  9-9.





# 9.3.11 External Override of CHG and DSG Drivers

The device allows direct disabling of the CHG and DSG drivers through the CTRC and CTRD pins, respectively.  $\boxtimes$  9-10 shows the operation of the CTRC and CTRD pins. To support the simple-stack solution for higher-cell count packs, these pins are designed to operate above the device's VDD level. Connect a 10-M $\Omega$  resistor



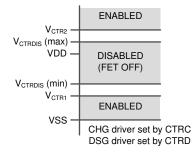
between a lower device CTRC and CTRD input pins to an upper device's CHG and DSG output pins (see the schematics in セクション 9.3.13).

CTRC only enables or disables the CHG pin, while CTRD only enables or disables the DSG pin. When the CTRx pin is in the DISABLED region, the respective FET pin is off, regardless of the state of the protection circuitry. When the CTRx pin is in either ENABLED region, the protection circuitry determines the state of the FET driver.

注

In any event where CTRC is disabled, CTRD is enabled, no DSG FET related faults are present, and  $(SRP-SRN) < V_{STATE_D}$ , the CHG output pin is held high regardless. In any event where CTRD is disabled, CTRC is enabled, no charge FET related faults present, and  $(SRP-SRN) > V_{STATE_C}$ , the DSG output pin is held high regardless.

Both CTRx pins apply the fault-detection filtered method to improve the robustness of the signal detection. The counter counts up if an ENABLED signal is sampled; the counter counts down if a DISABLED signal is sampled. When the counter counts up from 0% to > 70% of its full range, which takes about 7-ms typical of a solid signal, the CTRx pins take the signal as ENABLED. If the counter counts down from 100% to < 30% of its full range, which takes about 7-ms typical of a solid signal, the CTRx pins take the signal as ENABLED. If the counter counts down from 100% to < 30% of its full range, which takes about 7-ms typical of a solid signal, the CTRx pins take the signal as DISABLED. From a 0 count counter (solid DISABLE), a solid ENABLE signal takes about  $t_{CTRDEG_ON}$  time to deglitch. From a 100% count (solid ENABLE), a solid DISABLE signal takes about  $t_{CTRDEG_OFF}$  time to deglitch. Although such a filter scheme provides a certain level of noise tolerance, it is highly recommended to shield the CTRx traces and keep the traces as short as possible in the PCB layout design. The CTRx deglitch time will add onto the FET response timing on OV, UV, and OW faults in a stack configuration. The  $t_{CTRDEG_OFF}$  time adds an additional delay to the fault detection timing and the  $t_{CTRDEG_ON}$  time adds an additional delay to the fault recovery timing.



# **2** 9-10. CTRC, CTRD Voltage Levels

# 9.3.12 Configuring 3-Series, 4-Series, or 5-Series Modes

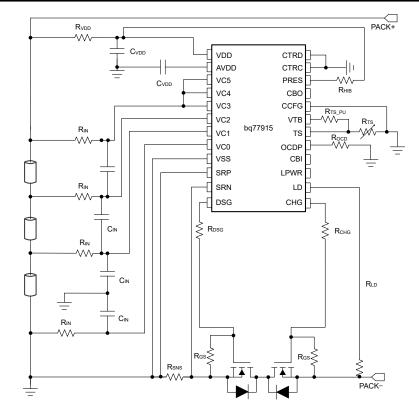
The BQ77915 device supports 3-series, 4-series, or 5-series packs. To avoid accidentally detecting a UV fault on unused (shorted) cell inputs, the device must be configured for the specific cell count of the pack. This is set with the configuration pin, CCFG, which is mapped as shown in  $\frac{1}{5}$  9-7. The device periodically checks the CCFG status and takes t<sub>CCFG DEG</sub> time to detect the pin status.

云 9-7. CCFG Configurations				
CCFG	CONFIGURATION	CONNECT TO		
< V <sub>CCFGL</sub> for t <sub>CCFG_DEG</sub>	3 cells	VSS		
Within V <sub>CCFGM</sub> for t <sub>CCFG_DEG</sub>	4 cells	AVDD		
> V <sub>CCFGH</sub> for t <sub>CCFG_DEG</sub>	5 cells	Floating		

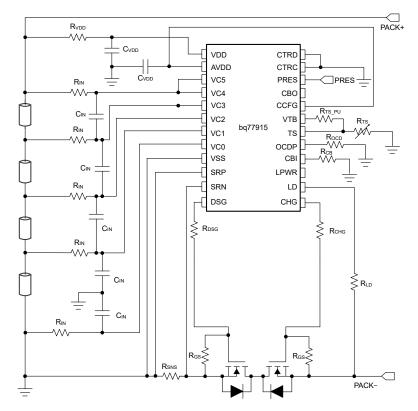
# The CCFG pin should be tied to the recommended net from $\frac{1}{20}$ 9-7. The device compares the CCFG input voltage to the AVDD voltage and should never be set above the AVDD voltage. When the device configuration is for 5 series, leave the CCFG pin floating. The internal pin bias is approximately 33% of the AVDD voltage for 5-series configuration.

Copyright © 2023 Texas Instruments Incorporated



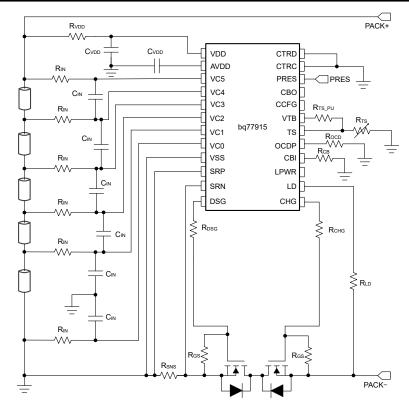


# **2** 9-11. 3-Series Configuration with Cell Balancing and HIBERNATE Mode Disabled



#### **2**9-12. 4-Series Configuration with Internal Cell Balancing and HIBERNATE Mode Enabled





#### **2** 9-13. 5-Series Configuration with Internal Cell Balancing and HIBERNATE Mode Enabled

#### 9.3.13 Stacking Implementations

To support higher than 5-series cell packs, daisy-chain multiple devices. Each device has OV, UV, OW, OTC, OTD, UTC, and UTD protections of its directly monitored cells, while any fault conditions disable the global CHG and/or DSG FET driver automatically.

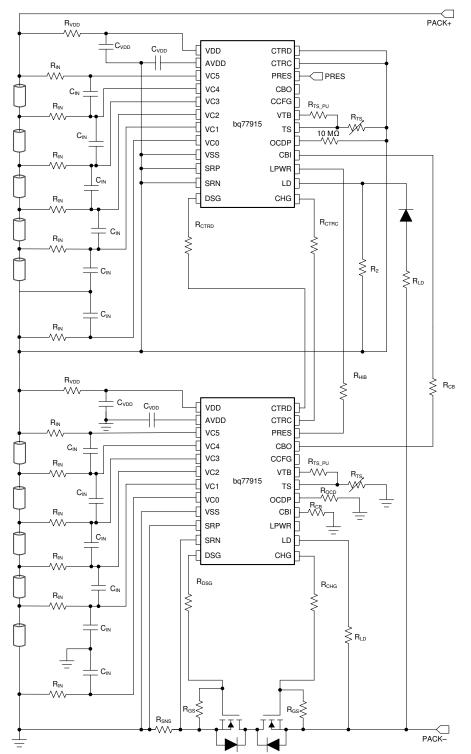
注

Upper devices do not provide OCC, OCD1, OCD2, or SCD protections, as these are based on pack current. For the BQ77915 device used on the upper stack, short the SRP and SRN pins to prevent false detection.

To configure higher-cell packs, follow this procedure:

- Connect each device on at least each of its three lowest cell input pins.
- Connect a higher cell count to the upper devices (for example, for a 7-series configuration, connect four cells on the upper device and three cells on the bottom device). This provides a stronger CTRx signal to the bottom device.
- Verify each device's CCFG pin is configured appropriately for its specific number of cells (that is, three, four, or five cells).
- Connect the upper CHG pins with an RCTRx to the immediate lower device CTRC pin.
- Connect the upper DSG pins with an RCTRx to the immediate lower device CTRD pin.
- All upper devices should have their SRP and SRN pins shorted to their VSS pins.
- Connect the upper CBI pins with an R<sub>CB</sub> to the immediate lower device CBO pin.
- Connect the upper LPWR pins with an R<sub>HIB</sub> to the immediate lower device PRES pin.
- Connect the upper OCDP pins with a 10-MΩ resistor to VSS. Use the lower OCDP pin to program the OCD1/2 delay.







# 9.3.14 Zero-Volt Battery Charging Inhibition

Once the device is powered up, it can pull the CHG pin up if the VDD  $\ge V_{SHUT}$ , which varies from about 1 V per cell on a 3-series configuration to about 0.6 V per cell on a 5-series configuration. If the battery stack voltage falls below  $V_{SHUT}$ , the device is in SHUTDOWN mode and the CHG driver is no longer active and charging is not allowed unless VDD rises above  $V_{POR}$  again.



# 9.4 Device Functional Modes

# 9.4.1 Power Modes

# 9.4.1.1 Power On Reset (POR)

The device powers up when VDD  $\geq$  V<sub>POR</sub>. At POR, the following events occur:

- A typical of 5-ms hold-off delay applies to both CHG and DSG drivers, keeping both drivers in the OFF state. This is to provide time for the internal LDO voltage to ramp up.
- The CTRC and CTRD deglitch occurs. During the deglitch time, the CHG and DSG driver remains off. Note that the deglitch time masks out the 5-ms hold-off delay.
- The device assumes an OV fault at POR; thus, the CHG driver is off for OV recovery time if all the cell
  voltages are < (V<sub>OV</sub> V<sub>HYS\_OV</sub>). The OV recovery time starts after the 5-ms hold-off delay. If device reset
  occurs when any cell voltage is above the OV hysteresis range, the CHG driver will remain off until an OV
  recovery condition is met.

#### 9.4.1.2 NORMAL Mode

This is the normal operation mode. All configured protections are active, no fault is detected, and both CHG and DSG drivers are enabled. HIBERNATE mode is deactivated. While the device is in NORMAL mode, cell balancing occurs if all the necessary conditions for balancing are valid. Refer to the *Cell Balancing* section for details.

#### 9.4.1.3 FAULT Mode

If any configured protection fault is detected, the device enters the FAULT mode. In this mode, the CHG and/or DSG driver can be turned off depending on the fault. Refer to *Fault Condition, State, and Recovery Methods* for details. When one of the FET drivers (either CHG or DSG) is turned off, while the other FET driver is still on, the state comparator is activated for FET body diode protection.

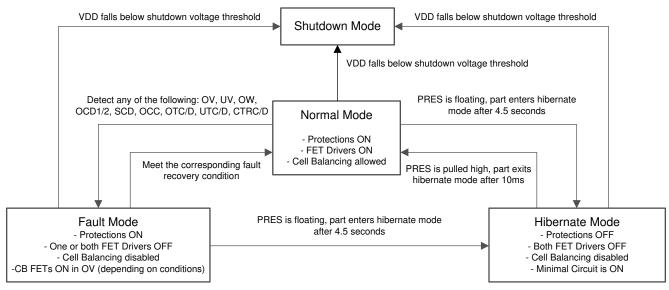
#### 9.4.1.4 HIBERNATE Mode

If the PRES pin is left floating, the device enters HIBERNATE mode operation. In this mode, all fault detection and cell balancing is deactivated and the CHG and DSG drivers are turned off to reduce power consumption to ultra-low levels. This mode of operation is recommended when the battery packs are in shipping or storage. The device can be brought back to NORMAL mode by driving PRES high.

#### 9.4.1.5 SHUTDOWN Mode

This is the lowest power consumption state of the device when VDD falls below  $V_{SHUT}$ . In this mode, all fault detections, CHG and DSG drivers are disabled. The device will wake up and enter NORMAL mode when VDD rises above  $V_{POR}$ .





**図** 9-15. Various Operational Modes

# 9.4.1.6 Customer Fast Production Test Modes

The BQ77915 device supports the ability to greatly reduce production test time by cutting down on protection fault delay times. To shorten fault times, place the BQ77915 device into Customer Test Mode (CTM). CTM is triggered by raising VDD to  $V_{CTM}$  voltage above the highest cell input pin (that is, VC5) for t<sub>CTM</sub> ENTRY time.

The CTM is expected to be used in single-chip designs only. CTM is not supported for stacked designs. Once the device is in CTM, all fault delays and non-current fault's recovery delay times reduce to a value of  $t_{CTM\_DELAY}$ . The fault recovery time for overcurrent faults (OCD1, OCD2, OCC, and SCD) is reduced to  $t_{CTM\_OC\_REC}$ .

Verification of protection fault functionality can be accomplished in a reduced timeframe in CTM. Reducing the VDD voltage to the same voltage applied to the highest-cell input pin for t<sub>CTM ENTRY</sub> will exit CTM.

In CTM, with reduced time for all internal delays, qualification of all faults will be reduced to a single instance. Thus, in this mode, fault-condition qualification is more susceptible to transients, so take care to have fault conditions clearly and cleanly applied during test mode to avoid false triggering of fault conditions during CTM.



# 10 Application and Implementation

注

Information in the following applications sections is not device of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

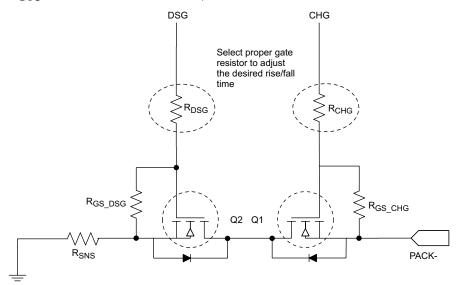
# **10.1 Application Information**

The BQ77915 device is a low power stackable battery pack protector with integrated low-side NMOS FET drivers. The device protects and recovers without MCU control. The following sections highlight implementations for the BQ77915 device.

#### **10.1.1 Recommended System Implementation**

#### 10.1.1.1 CHG and DSG FET Rise and Fall Time

The CHG and DSG FET drivers are designed to have fast switching time. Customers should select a proper gate resistor ( $R_{CHG}$  and  $R_{DSG}$  in the reference schematic) to set to the desired rise/fall time.



**図** 10-1. Select Proper Gate Resistor for FET Rise and Fall Time

The CHG FET fall time is generally slower because it is connected to the PACK– terminal. The CHG driver will pull to  $V_{SS}$  quickly when the driver is signaled to turn off. Once the gate of the CHG FET reaches ground or Vgsth, the PACK– will start to fall below ground, the CHG signal will follow suit in order to turn off the CHG FET. This portion of the fall time is strongly dependent on the FET characteristic, the number of FETs in parallel, and the value of the gate-source resistor (R<sub>GS CHG</sub>).



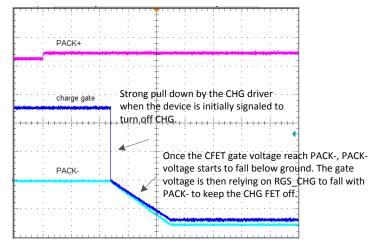


図 10-2. CHG FET Fall Time

# 10.1.1.2 Protecting CHG and LD

Because both CHG and LD are connected to PACK– terminal, these pins are specially designed to sustain an absolute max of -30 V. The device can be used in a wide variety of applications, and it is possible to expose the pins lower than -30-V absolute max rating.

To protect the pins, TI recommends to put a PMOS FET in series of the CHG pin, and a diode in series of the LD pin, as shown below.

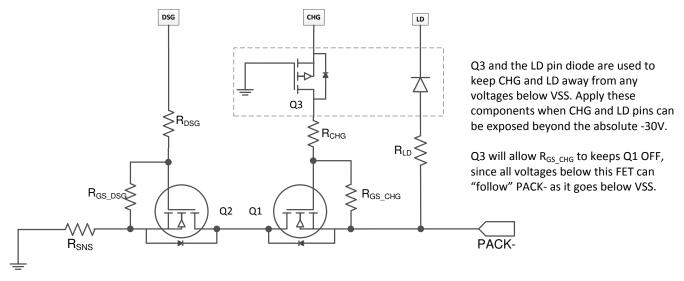


図 10-3. Protecting the CHG and LD Pins Below Absolute Minimum

# 10.1.1.3 Protecting the CHG FET

When the CHG driver is off, CHG is pulled to  $V_{SS}$ , the PACK– terminal can be pulled up to the PACK+ level when a load is connected. This can put the gate-source voltage above the absolute max of the MOSFET rating. Thus, it is common to place a Zener diode across the CHG FET's gate source to protect the CHG FET. Additional components are added when a Zener is used to limit current going into the CHG pin, as well as reducing the impact on rise time. See  $\boxtimes$  10-4 for details.



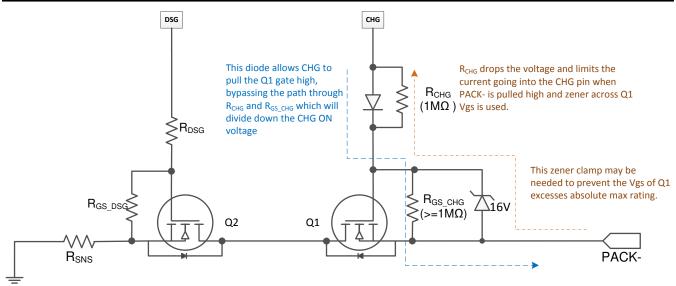
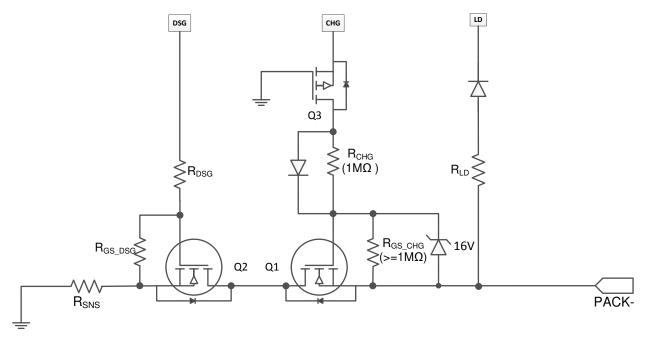


図 10-4. Protecting the CHG FET from High Voltage on PACK-

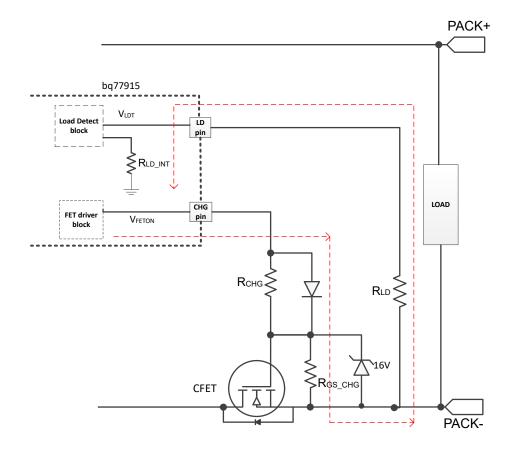




# 10.1.1.4 Using Load Detect for UV Fault Recovery

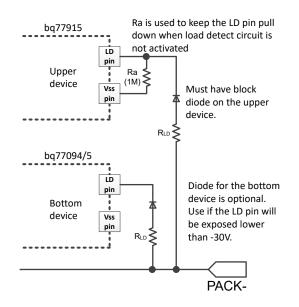
A larger CHG FET gate-source resistor is required if load removal is enabled as a device of the UV recovery criteria. When the load removal circuit is enabled, the device is internally connected to  $V_{SS}$ . Because in a UV fault, the CHG driver remains on, it creates a resistor divider path to the load detect circuit.





# 図 10-6. Load Detect Circuit During UV Fault

To verify load removal is detected properly during a UV fault, use 3.3 M $\Omega$  for R<sub>GS\_CHG</sub> (instead of a typical 1 M $\Omega$  when load removal is not required for UV recovery). R<sub>CHG</sub> can stay in 1 M $\Omega$  as recommended when using CHG FET protection components. The CHG FET rise time impact is minimized, as described in *Protecting the CHG FET*. On a stacked configuration, connect the LD pin as shown in 🗵 10-7 if load removal is used for a UV fault recovery. If load detection is not required for a UV fault recovery, a larger value of R<sub>GS\_CHG</sub> can be used (that is, 10 M $\Omega$ ), and the LD pin on the upper devices can be left floating.



### 2 10-7. Simplified Circuit: LD Connection on Upper Device When Using for UV Fault Recovery

#### 10.1.1.5 Temperature Protection

The device detects temperature by checking the voltage divided by  $R_{TS_PU}$  and  $R_{TS}$ , with the assumption of using 10 K $\Omega$   $R_{TS_PU}$  and 103AT NTC for  $R_{TS}$ . System designers should always check the thermistor resistance characteristic and refer to the temperature protection threshold specification in the *Electrical Characteristics* table to determine if a different pull up resistor should be used. If a different temperature trip pint is required, it is possible to scale the threshold using this equation: Temperature Protection Threshold =  $R_{TS}/(R_{TS} + R_{TS_PU})$ .

**Example**: Scale OTC trip points from 50°C to 55°C

The OTC protection can be set to 45°C or 50°C. When the device's OTC threshold is set to 50°C, it is referred to configure the V<sub>OTC</sub> parameter to 29.38% of VTB (typical), with the assumption of  $R_{TS_PU} = 10 \text{ K}\Omega$  and  $R_{TS} = 103AT$  or similar NTC (which the NTC resistance at 50°C = 4.16K $\Omega$ ). The V<sub>OTC</sub> specification is the resistor divider ratio of  $R_{TS_PU}$  and  $R_{TS}$ .

The  $V_{OTC}$ ,  $V_{OTD}$ ,  $V_{UTC}$ , and  $V_{UTD}$  configuration options are fixed in the device. Hence, the actual temperature trip point can only adjust by using a different B-value NTC and/or using a different R<sub>TS PU</sub>.

In this example, the 103AT NTC resistance at 55°C is 3.536 K $\Omega$ . By changing the R<sub>TS\_PU</sub> from 10 K $\Omega$  to 8.5 K $\Omega$ , we can scale the actual OTC temperature trip point from 50°C to 55°C. Because the R<sub>TS\_PU</sub> value is smaller, this change affects all the other temperature trip points and scales OTD, UTC, and UTD with the largest impact to OTD.

#### 10.1.1.6 Adding RC Filters to the Sense Resistor

Current fault is sensed through voltage across sense resistor. Optional RC filters can be added to the sense resistor to improve stability.



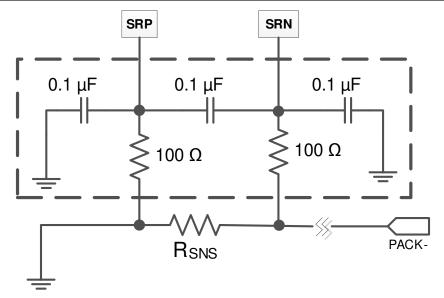


図 10-8. Optional Filters Improve Current Measurement

#### 10.1.1.7 Using the State Comparator in an Application

The state comparator has built-in hysteresis and  $t_{STATE}$  qualification time. In a typical application, the sense resistor is selected according to the application current, which is not usually close to the state comparator threshold. Current variation slowly through the hysteresis range causes the FET body diode protection to toggle on and off.

#### 10.1.1.7.1 Examples

As an example, using a 5-Ah battery, with 1C-rate (5 A) charge and 2C-rate (10 A) discharge, the sense resistor is mostly 3 m $\Omega$  or less.

The typical current to turn on the FET body diode protection is 625 mA using this example. The typical current to turn off the FET body diode protection with the 3-m $\Omega$  sense resistor is 417 mA. Using this example, a > 1 A current, either charge or discharge should provide a solid FET body diode protection detection. A momentary drop through the hysteresis threshold will not cause the body diode protection to drop, but drops of 2 ms or more will cause the FET to toggle.

Observe the device behavior during an OV event (and no other fault is detected). In an OV event, the CHG FET is off and the DSG FET is on. If a discharge of >1 A occurs, the device would turn on the CHG FET to allow the full discharge current to pass through. Once the overcharged cell is discharged to the OV recovery level, the OV fault is recovered and CHG driver turns on (or remains on in this scenario) and the state comparator is turned off.

If the discharge current drops below the  $V_{(STATE_D_HYS)}$  threshold for longer than  $t_{STATE}$  when the device is still in an OV fault, the CHG FET may toggle on and off until the overcharged cell voltage is reduced down to the OV recovery level. When the OV fault recovered, the CHG FET will be turned on solidly and the state comparator is off.

Without the FET body diode protection, if a discharge occurs during an OV fault state, the discharge current can only pass through the CHG FET body diode until the OV fault is recovered. This increases the risk of damaging the CHG FET if the MOSFET is not rated to sustain such current through its body diode. It also increases the FET temperature as current is now carried through the body diode.



### **10.2 Typical Application**

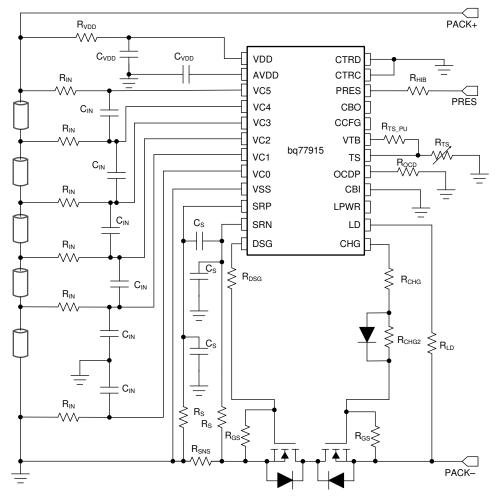


図 10-9. The BQ77915 Device with Five Cells

#### **10.2.1 Design Requirements**

For this design example, use the parameters shown in  $\pm$  10-1.

表 10-1. Design	Parameters
----------------	------------

PARAMETER		DESCRIPTION	VALUES					
R <sub>IN</sub>	Cell voltage sensing (Vo parameter to adjust the	Cx pins) filter resistor. System designers should change this cell balance current.	1 kΩ ±5%					
C <sub>IN</sub>	Cell voltage sensing (VC	Cx pins) filter capacitor	0.1 µF ±10%					
R <sub>VDD</sub>	Supply voltage filter resi	Supply voltage filter resistor						
C <sub>VDD</sub>	Supply voltage filter cap	1 µF ±20%						
R <sub>S</sub>	Current sensing input fil	100 Ω ±5%						
C <sub>S</sub>	Current sensing input fil	0.1 µF ±10%						
R <sub>TS</sub>	NTC thermistor	NTC thermistor						
R <sub>TS_PU</sub>	Thermistor pullup resistance-temperature	10 kΩ ±1%						
R <sub>GS_CHG</sub> CHG FET gate-source		Load removal is enabled for UV recovery.	3.3 MΩ ±5%					
	resistor	Load removal is disabled for UV recovery.	1 MΩ ±5%					
R <sub>GS_DSG</sub>	DSG FET gate-source r	DSG FET gate-source resistor						



PARAMETER		DESCRIPTION	VALUES				
R <sub>CHG</sub>	CHG gate resistor	System designers should adjust this parameter to meet the desired FET rise/fall time.	1 kΩ ±5%				
		If additional components are used to protect the CHG FET and/or to enable load removal detection for UV recovery	1 MΩ ±5%				
R <sub>DSG</sub>	DSG gate resistor. Sys FET rise/fall time.	SG gate resistor. System designers should adjust this parameter to meet the desired ET rise/fall time.					
$R_{CTRC}$ and $R_{CTRD}$	CTRC and CTRD curre	10 MΩ ±5%					
R <sub>HIB</sub>	PRES pullup resistor for	10 kΩ ±5%					
R <sub>OCD</sub>		OCDP discharge overcurrent protection delay pulldown resistor. System designers should change this parameter for the desired delay.					
R <sub>CB</sub>	CBI pulldown resistor b	CBI pulldown resistor between stacked devices to enable balancing					
R <sub>LD</sub>	LD resistor for load ren	LD resistor for load removal detection					
R <sub>SNS</sub>		for current protection. System designers should change this the application current protection requirement.	1 mΩ ±1%				

表 10-1. Design Parameters (continued)

# 10.2.2 Detailed Design Procedure

The following is the detailed design procedure:

- 1. Select the number of devices needed for the number of cells in the system, and for the configuration of the protection thresholds.
- 2. Select the proper sense resistor value based on the application current. The sense resistor should enable detection of the highest current protection, as well as the short circuit current.
- Set the temperature protection using a 103AT NTC (or an NTC with similar specifications). If using a different type of NTC, a different R<sub>TS\_PU</sub> may be used for the application. Refer to the actual temperature detection threshold voltage to determine the R<sub>TS\_PU</sub> value.
- 4. Connect the CCFG pin correctly for each device based on the number of cells in series.
- 5. Enable cell balancing if desired.
- 6. Select the configuration parameters and input filter resistors to set the current.
- 7. Review the *Recommended System Implementation* to determine if optional components should be added to the schematic.

#### 10.2.2.1 Design Example

This example shows how to design protection for an 18-V Li-ion battery pack using 4.2-V cells with the following requirements:

- The system operates from 15 V to 21.5 V.
- · The battery allows 4-A continuous current.
- The battery protects with 8-A discharge current > 500 ms.
- The battery has short circuit protection in < 2 ms.
- The system is for operation in an office environment: 10°C to 30°C.
- The cell normal charge voltage is 4.2 ±0.05 V to 0.05 C.
- The cell cutoff voltage is 2.75 V.
- The charge temperature is 0°C to 45°C.
- A cell configuration is selected to provide 5 Ah over the system range of operation.
- The cell assembly is capable of > 30-A short circuit current.
- Cell balancing is desired with a current of 10% of termination current.
- · Low current drain is desired when the pack is removed from the system.
- Load removal for fault recovery is required. Recovery by connecting the charger is acceptable.

To start the design:

- 1. Start the schematic:
  - An 18-V pack using 3.6-V nominal cells requires a 5-series configuration. A single BQ77915 device is needed.



- Follow the 5-series reference schematic in this document. Follow the recommended design parameters in *Design Requirements*.
- Because a single device is needed, CTRC and CTRD are connected directly to GND.
- The power FET used in this type of application usually has an absolute maximum of 20-V Vgs. For an 18-V pack design, transient voltage during an OCD may exceed 20 V, so the diode across the 1-MΩ R<sub>CHG2</sub> is used. R<sub>CHG</sub> helps to slow the charge FET from turning on.
- Because a charger connection for UV recovery is acceptable, the condition in Using Load Detect for UV Fault Recovery is not a concern. A 1-MΩ R<sub>GS CHG</sub> can be used for the schematic.
- The optional sense input filter is selected for the circuit.
- Because low current storage is desired, the PRES pin is brought out of the pack for control by the system. The standard recommended R<sub>HIB</sub> value is used.
- Because cell balancing is required:
  - Connect the CBI pin to VSS.
  - Determine the resistance for the R<sub>IN</sub> filter resistors. Since the charge taper current will be 0.05 × 5 A or 250 mA, 10% is 25 mA. With a 4.1-V cell, 25 mA would require 164-Ω resistance. This resistance includes the internal R<sub>BAL</sub> resistance and two R<sub>IN</sub> resistors. 75-Ω resistors are selected for R<sub>IN</sub>.
- 2. Decide the value of the sense resistor,  $R_{SNS}$ .
  - When selecting the value of R<sub>SNS</sub>, verify the voltage drop across SRP and SRN is within the available current protection threshold range.
  - In this example, only one protection threshold is specified. The minimum available OCD threshold is the 10-mV OCD1 threshold, but this would result in an odd value for R<sub>SNS</sub> and the tolerance of the threshold is 30%. Using the –60-mV threshold of the BQ77915 configuration, a 10-mΩ sense resistor would give a 6-A nominal OCD threshold. With the 20% tolerance, 4 A can pass without OCD and 8 A will always cross the threshold.
  - A 30-A SCD with a 10-mΩ sense resistor would be a nominal 300-mV threshold. Tolerance must be considered and the protection threshold can be lower than the battery capability. The 120-mV threshold of the BQ77915 configuration with a 10-mΩ R<sub>SNS</sub> will give a 12-A nominal short circuit threshold.
  - Select  $R_{SNS} = 10 \text{ m}\Omega$  for this example.
- 3. Determine the remaining BQ77915 protection configuration:
  - Charging the cells at a lower than maximum voltage allows a margin on setting the OV threshold. The system could allow a 4.15-V OV, while the cells might allow a 4.3-V OV. Since the charge voltage will be 4.1 V/cell, this is the desired VFC point of the BQ77915 device. The 4200-mV OV threshold and 100 mV VOV – VFC of the BQ77915 device are suitable.
  - OV hysteresis and delay values are not specified requirements. A 1-s delay will be selected. Some hysteresis is desired to prevent cycling if the battery were to reach OV. 200 mV is acceptable.
  - The system will stop operation at a nominal 3 V per cell, while the cells could operate to 2.75 V. Some margin below the 3 V should be allowed, because cell voltages possibly vary at low states of charge. A 2750-mV threshold option is available, but the existing BQ77915 configuration has the 2900 threshold.
  - UV hysteresis and delay are not specified requirements. A 1-s delay is selected. Generally, a larger UV
    hysteresis will avoid system cycling from automatic recovery; however, in this design load, removal is
    required and charger connection is expected for UV recovery. The value could vary, but 400 mV is
    selected.
  - Open-wire protection is selected at the 100-nA level.
  - $t_{OCD1}$  or  $t_{OCD2}$  could be programmed to 350 ms to protect in less than 500 ms, or the default BQ77915 180 ms is used. However, the 350 ms can be selected with  $R_{OCD}$ . Use 604 k $\Omega$  1% for  $R_{OCD}$ .
  - The 2-ms SCD response time allows either SCD delay selection.
  - Overcurrent charge protection is not specified in the requirements. The BQ77915 60-mV setting will allow a 1C charge.
  - For temperature protections, the 0°C to 45°C charge temperature thresholds match the range for the cells. Use the lower range for discharge.
  - The VCBTH VCBTHL determines the voltage spread during constant current charge when balancing is allowed. 100 mV allows some spread without balancing.
  - See the summary in 表 10-2.



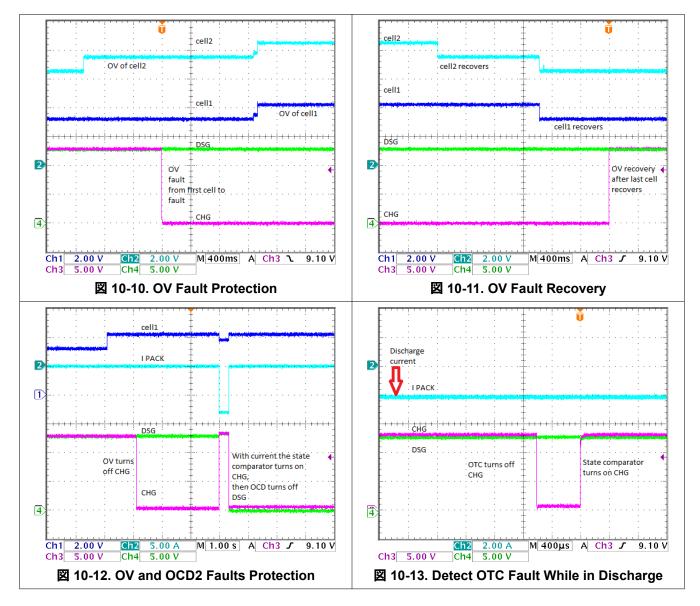
4. Review the available release in the *Device Comparison Table* to determine if it is a suitable option. In this example, the BQ7791500 configuration is suitable. If it is not suitable for your design, contact a TI representative for further assistance and for information on BQ77915 PRODUCT PREVIEW devices.

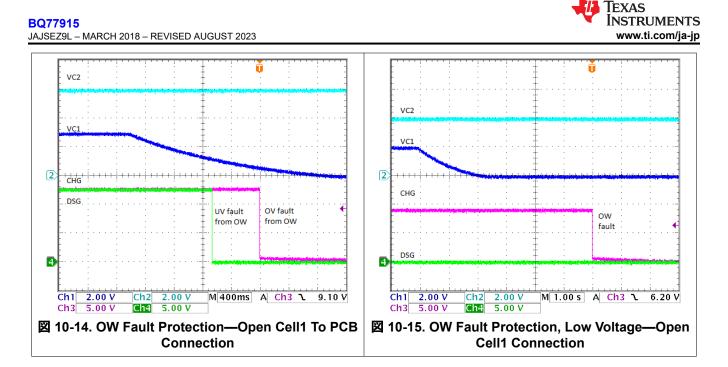
Protection	Threshold	Hysteresis	Delay	Recovery Method						
OV	4.2 V	200 mV	1 s (default setting)	Hysteresis						
UV	2.9 V	400 mV	1 s (default setting)	Hysteresis + load removal						
OW	100 nA (default setting)	_	_	$(VC_x - VC_{x-1}) > 600 \text{ mV (typical)}$						
OCD1	60 mV	—	Load removal only							
OCD2	60 mV	—	180 ms (350 ms using R <sub>OCD</sub> )	Load removal only						
SCD	120 mV	_	960 µs	Load removal only						
OCC	60 mV		Fixed at 10 ms	Load detection only						
OTC	45°C	10°C	4.5 s	Hysteresis						
OTD	65°C	10°C	4.5 s	Hysteresis						
UTC	0°C	10°C	4.5 s	Hysteresis						
UTD	-10°C	10°C	4.5 s	Hysteresis						
VOV – VFC	100 mV	—	—							
VCBTH – VCBTL	100 mV	_	_	—						
V <sub>START</sub>	3.8 V	—	—							

#### 表 10-2. Design Example Configuration



#### **10.2.3 Application Curves**





## **11 Power Supply Recommendations**

The recommended cell voltage range is up to 5 V. If three cells in series are connecting to the BQ77915 device, the unused VCx pins should be shorted to the highest unused VCx pin. The recommended VDD range is from 3 V to 25 V. This implies the device is still operational when cell voltage is depleted down to the ~1.5-V range.



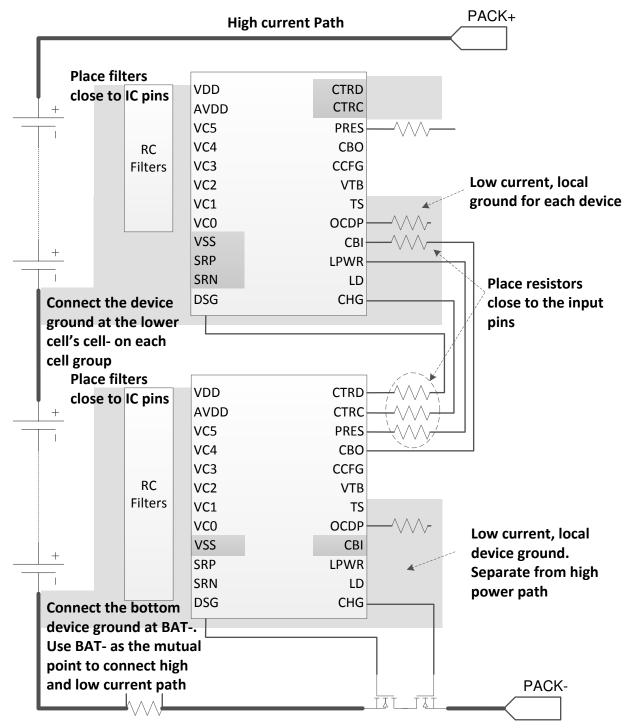
## 12 Layout

## 12.1 Layout Guidelines

- 1. Match SRN and SRP traces.
- 2.  $R_{IN}$  filters, VDD, AVDD filters, and the  $C_{VDD}$  capacitor should be placed close to the device pins.
- 3. Separate the device ground plane (low current ground) from the high current path. Filter capacitors should reference to the low current ground path or device Vss.
- 4. In a stack configuration, the R<sub>CTRD</sub> and R<sub>CTRC</sub> should be placed closer to the lower device CTRD and CTRC pins.
- 5. R<sub>GS</sub> should be placed near the FETs.
- 6. In a stacked configuration, verify in the PCB layout that the trace from the VC5 pin to a cell and the trace from the VC0 pin of the next upper device to the immediately higher cell are kept separate.



### 12.2 Layout Example



🛛 12-1. Layout Example



## 13 Device and Documentation Support

## 13.1 サード・パーティ製品に関する免責事項

サード・パーティ製品またはサービスに関するテキサス・インスツルメンツの出版物は、単独またはテキサス・インスツルメンツの製品、サービスと一緒に提供される場合に関係なく、サード・パーティ製品またはサービスの適合性に関する是認、サード・パーティ製品またはサービスの是認の表明を意味するものではありません。

### **13.2 Documentation Support**

#### 13.2.1 Related Documentation

For related documentation see the following:

- BQ77915 3–5S Low-Power Protector Evaluation Module User's Guide
- BQ77915 Functional Safety FIT Rate, FMD, and Pin FMA Application Report

## 13.3 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.comのデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

## 13.4 サポート・リソース

TI E2E<sup>™</sup> サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接 得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計で必要な支援を迅速に得るこ とができます。

リンクされているコンテンツは、該当する貢献者により、現状のまま提供されるものです。これらは TI の仕様を構成するものではなく、必ずしも TI の見解を反映したものではありません。TI の使用条件を参照してください。

### 13.5 Trademarks

TI E2E<sup>™</sup> is a trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

#### 13.6 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずか に変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

### 13.7 用語集

テキサス・インスツルメンツ用語集 この用語集には、用語や略語の一覧および定義が記載されています。

### 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
BQ7791500PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	BQ77915	Samples
BQ7791500PWT	ACTIVE	TSSOP	PW	24	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	BQ77915	Samples
BQ7791501PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791501	Samples
BQ7791501PWT	ACTIVE	TSSOP	PW	24	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791501	Samples
BQ7791502PW	ACTIVE	TSSOP	PW	24	60	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791502	Samples
BQ7791502PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791502	Samples
BQ7791504PW	ACTIVE	TSSOP	PW	24	60	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791504	Samples
BQ7791504PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791504	Samples
BQ7791506PW	ACTIVE	TSSOP	PW	24	60	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791506	Samples
BQ7791506PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791506	Samples
BQ7791508PW	ACTIVE	TSSOP	PW	24	60	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791508	Samples
BQ7791508PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791508	Samples
BQ7791513PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791513	Samples
BQ7791514PWR	ACTIVE	TSSOP	PW	24	2000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	7791514	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".



www.ti.com

## PACKAGE OPTION ADDENDUM

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption. **Green:** TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

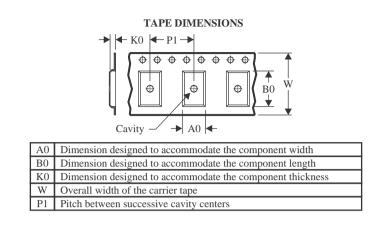


Texas

STRUMENTS

### TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



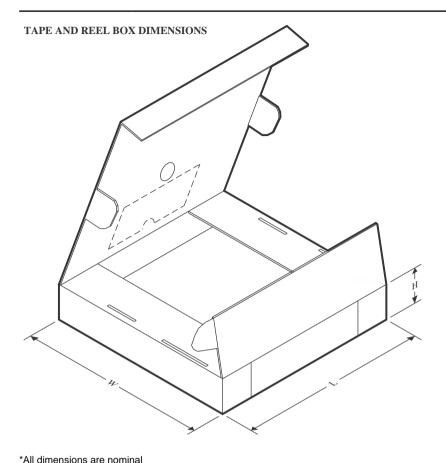
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ7791500PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791500PWT	TSSOP	PW	24	250	180.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791501PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791501PWT	TSSOP	PW	24	250	180.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791502PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791504PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791506PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791508PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791513PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1
BQ7791514PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1



www.ti.com

# PACKAGE MATERIALS INFORMATION

15-Dec-2023



All dimensions are nominal			<u> </u>	0.50			
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ7791500PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791500PWT	TSSOP	PW	24	250	210.0	185.0	35.0
BQ7791501PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791501PWT	TSSOP	PW	24	250	210.0	185.0	35.0
BQ7791502PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791504PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791506PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791508PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791513PWR	TSSOP	PW	24	2000	356.0	356.0	35.0
BQ7791514PWR	TSSOP	PW	24	2000	356.0	356.0	35.0

## TEXAS INSTRUMENTS

www.ti.com

15-Dec-2023

## TUBE



## - B - Alignment groove width

#### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
BQ7791502PW	PW	TSSOP	24	60	530	10.2	3600	3.5
BQ7791504PW	PW	TSSOP	24	60	530	10.2	3600	3.5
BQ7791506PW	PW	TSSOP	24	60	530	10.2	3600	3.5
BQ7791508PW	PW	TSSOP	24	60	530	10.2	3600	3.5

# **PW0024A**



# **PACKAGE OUTLINE**

## TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice. 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153.



# PW0024A

# **EXAMPLE BOARD LAYOUT**

## TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# PW0024A

# **EXAMPLE STENCIL DESIGN**

## TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



#### 重要なお知らせと免責事項

TIは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス・デザインを含みます)、アプリケーションや 設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供してお り、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的に かかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあら ゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプ リケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載す ることは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを 自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TIの製品は、TIの販売条件、または ti.com やかかる TI 製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供され ています。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありま せん。

お客様がいかなる追加条項または代替条項を提案した場合でも、TIはそれらに異議を唱え、拒否します。

郵送先住所:Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023, Texas Instruments Incorporated